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QUALITATIVE PROPERTIES OF THE SOLUTIONS TO THE NAVIER-STOKES EQUATIONS FOR COMPRESSIBLE FLUIDS

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1. Introduction.

We want to present a new method for showing the existence of a stationary solution to the equations which describe the motion of a viscous compressible barotropic fluid.

At first it is useful to recall some known results concerning the non-stationary case. The equations of motion are

$$\text{(NS)} \left\{ \begin{array}{ll}
 \rho \left[\frac{\partial v}{\partial t} + (v \cdot \nabla) v - f \right] = - \nabla [p(\rho)] + \mu \Delta v + (\zeta + \mu/3) \nabla \text{div } v & \text{in }]0, T[\times \Omega, \\
 \frac{\partial \rho}{\partial t} + \text{div}(\rho v) = 0 & \text{in }]0, T[\times \Omega, \\
 v|_{\partial \Omega} = 0 & \text{on }]0, T[\times \partial \Omega, \\
 \int_{\Omega} \rho = \bar{\rho} |\Omega| > 0 & (|\Omega| = \text{meas}(\Omega)), \\
 v|_{t=0} = v_0 & \text{in } \Omega, \\
 \rho|_{t=0} = \rho_0 & \text{in } \Omega,
 \end{array} \right.$$

where $\Omega \subset \mathbb{R}^3$ is a bounded domain, with smooth boundary $\partial \Omega$; v and ρ are the velocity and the density of the fluid; p is the pressure, which is assumed to be a known function of ρ ; f is the (assigned) external force field; the constants $\mu > 0$ and $\zeta \geq 0$ are the viscosity coefficients; $\bar{\rho} > 0$ is the mean density of the fluid, i.e. the total mass of fluid divided by $|\Omega|$; v_0 and ρ_0 are the initial velocity and density.

In the last years it has been proved that:

- (i) if v_0 and $\rho_0 - \bar{\rho}$ are small enough and $f = 0$, then problem (NS) has a unique global (in time) solution (Matsumura-Nishida [1]);

(ii) the preceding result also holds for a sufficiently small $f \neq 0$; moreover, two small solutions are asymptotically equivalent as $t \rightarrow +\infty$, and consequently if f is periodic (independent of t) then there exists a periodic (stationary) solution (Valli [3]).

It must be underlined that no other method is known for showing the existence of a stationary solution, excepting when the viscosity coefficients satisfy $\zeta \gg \mu$. In this case Padula [2] proved that, if f is small enough, then there exists a stationary solution. Remark, however, that in general the shear viscosity coefficient μ is larger than the bulk viscosity coefficient ζ . Moreover, from the mathematical point of view it would seem only necessary to require that μ is positive, without assumptions on the largeness of ζ .

The method that we want to present here is based on a "natural" linearization of the problem, followed by a fixed point argument. The viscosity coefficients are only required to satisfy the thermodynamic restrictions $\mu > 0$, $\zeta \geq 0$.

2. The linear problem (L).

Since we are searching for a solution in a neighbourhood of the equilibrium solution $\bar{\rho} = \bar{\rho}$, $\bar{v} = 0$, it is useful to introduce the new unknown

$$\sigma = \rho - \bar{\rho}.$$

The equations of motion in the stationary case thus become

$$(S) \left\{ \begin{array}{ll} -\mu \Delta v - (\zeta + \mu/3) \nabla \operatorname{div} v + p_1 \nabla \sigma = (\sigma + \bar{\rho}) [f - (v \cdot \nabla) v] + & \text{in } \Omega, \\ & + [p_1 - p'(\sigma + \bar{\rho})] \nabla \sigma \\ \bar{\rho} \operatorname{div} v + \operatorname{div}(v \sigma) = 0 & \text{in } \Omega, \\ v|_{\partial \Omega} = 0 & \text{on } \partial \Omega, \\ \int_{\Omega} \sigma = 0 & , \end{array} \right.$$

where it is assumed that $p_1 \equiv p'(\bar{\rho}) > 0$.

It is easily verified that a solution of (S) exists if we find a fixed point of the map

$$\Phi : (v, \sigma) \longrightarrow (w, \eta),$$

defined by means of the solutions of the following linear problem

$$(L) \left\{ \begin{array}{ll} -\mu \Delta w - (\zeta + \mu/3) \nabla \operatorname{div} w + p_1 \nabla \eta = (\sigma + \bar{\rho}) [f - (v \cdot \nabla) v] + & \\ & + [p_1 - p'(\sigma + \bar{\rho})] \nabla \sigma \equiv F \quad \text{in } \Omega, \\ \bar{\rho} \operatorname{div} w + \operatorname{div}(v \eta) = 0 & \text{in } \Omega, \\ w|_{\partial \Omega} = 0 & \text{on } \partial \Omega, \\ \int_{\Omega} \eta = 0 & . \end{array} \right.$$

3. A-priori estimates for the solution of (L).

We want to obtain a-priori estimates in Sobolev spaces of sufficiently large order, in such a way that we can control the behaviour of the non-linear terms which appear in F . We shall prove that a solution (w, η) of (L) satisfies

$$(3.1) \quad \|w\|_3 + \|\eta\|_2 \leq c_1 \|F\|_1$$

for $v|_{\partial \Omega} = 0$ and $\|v\|_3 \leq A$ small enough. Here $\|\cdot\|_k$ is the norm in the Sobolev space $H^k(\Omega)$, and c_1 depends in a continuous way on μ , ζ and A (but it is independent of v).

(a) At first, from well-known results on Stokes problem we get

$$(3.2) \quad \|w\|_3 + \|\eta\|_2 \leq c(\|F\|_1 + \|\operatorname{div} w\|_2).$$

Hence our aim is to estimate $\|\operatorname{div} w\|_2$.

(b) Multiplying (L)₁ by w and (L)₂ by $(p_1/\bar{\rho})\eta$ and integrating in Ω one has

$$(3.3) \quad \|w\|_1 + \|\operatorname{div} w\|_0 \leq c(\|F\|_{-1} + \|v\|_3^{1/2} \|\eta\|_0).$$

The same argument can be used for estimating all the successive derivatives in the interior of Ω , and the tangential derivative $D_\tau \operatorname{div} w$ near the boundary $\partial \Omega$, obtaining in this way (in local coordinates near $\partial \Omega$)

$$(3.4) \quad \|D_\tau w\|_1 + \|D_\tau \operatorname{div} w\|_0 \leq c(\|F\|_0 + \|v\|_3^{1/2} \|\eta\|_1).$$

(c) The estimate for the normal derivative $D_n \operatorname{div} w$ is obtained by observing that on $\partial \Omega$

$$\Delta w \cdot n \equiv \nabla \operatorname{div} w \cdot n,$$

in the sense that their difference does not contain $D_n^2 w$.

Hence by taking the normal derivative of $(L)_2$, multiplied by $(\bar{\rho})^{-1} \cdot (\zeta+4\mu/3)$, and adding it to the normal component of $(L)_1$ we get (in local coordinates near $\partial\Omega$)

$$(3.5) \quad p_1 D_n \eta + (\zeta+4\mu/3)/\bar{\rho} D_n \operatorname{div}(v\eta) \cong F \cdot n .$$

From this equation one easily gets

$$(3.6) \quad \|D_n \eta\|_0 \leq c(\|F\|_0 + \|v\|_3^{1/2} \|\eta\|_1).$$

Moreover, going back to $(L)_1$, one has

$$p_1 D_n \eta = \mu \Delta w \cdot n + (\zeta+\mu/3) \nabla \operatorname{div} w \cdot n + F \cdot n \cong (\zeta+4\mu/3) D_n \operatorname{div} w + F \cdot n ,$$

hence from (3.6)

$$(3.7) \quad \|D_n \operatorname{div} w\|_0 \leq c(\|F\|_0 + \|v\|_3^{1/2} \|\eta\|_1).$$

By repeating the same argument for the second order derivatives one gets

$$(3.8) \quad \|\operatorname{div} w\|_2 \leq c(\|F\|_1 + \|v\|_3^{1/2} \|\eta\|_2),$$

hence (3.1) holds if $\|v\|_3 \leq A$ small enough.

4. Existence of the solution of (L).

Though problem (L) is linear, and we know that the a-priori estimate (3.1) holds, the existence of a solution $w \in H^3(\Omega)$, $\eta \in H^2(\Omega)$ is not obvious.

In fact, the usual elliptic approximation cannot work in this case. More precisely, if we add $-\varepsilon \Delta \eta_\varepsilon$ to $(L)_2$, we must also require a boundary condition (say, Dirichlet or Neumann) on η_ε . But the limit function η is free on $\partial\Omega$. Hence the sequence η_ε can only converge in $L^2(\Omega)$ (Dirichlet condition), or in $H^1(\Omega)$ (Neumann condition), and cannot converge in $H^2(\Omega)$!

Moreover, if $v \neq 0$ (L) is not an elliptic system in the sense of Agmon-Douglis-Nirenberg (if $v = 0$ (L) is the Stokes system). Hence the usual regularization procedures do not work.

One can proceed in the following way. By adapting the method of Pa-

dula [2] to problem (L), one defines

$$(4.1) \quad \pi \equiv (p_1/\mu)\eta - (\zeta/\mu + 1/3)\operatorname{div} w$$

and (L) is transformed into

$$(L') \quad \left\{ \begin{array}{ll} -\Delta w + \nabla \pi = F/\mu & \text{in } \Omega, \\ \operatorname{div} w = (\zeta/\mu + 1/3)^{-1}(p_1\eta/\mu - \pi) & \text{in } \Omega, \\ w|_{\partial\Omega} = 0 & \text{on } \partial\Omega, \end{array} \right.$$

$$(L'') \quad \left\{ \begin{array}{ll} \bar{\rho}(\zeta/\mu + 1/3)^{-1}p_1\eta/\mu + \operatorname{div}(v\eta) = \bar{\rho}(\zeta/\mu + 1/3)^{-1}\pi & \text{in } \Omega, \\ \int_{\Omega} \eta = 0 & \end{array} \right.$$

These equations can be solved via a fixed point argument if $\zeta \gg \mu$. Hence the a-priori estimates (3.1) and the continuity method give the result for any pair of viscosity coefficients satisfying $\mu > 0$ and $\zeta \geq 0$.

5. Existence of a solution of (S).

We prove at last the existence of a fixed point for the map

$$\Phi : (v, \sigma) \longrightarrow (w, \eta).$$

Taking

$$K \equiv \{ (v, \sigma) \in H^3(\Omega) \times H^2(\Omega) \mid v|_{\partial\Omega} = 0, \int_{\Omega} \sigma = 0, \|v\|_3 + \|\sigma\|_2 \leq A \},$$

by using (3.1) one sees that

$$\|w\|_3 + \|\eta\|_2 \leq c_1 \|F\|_1 \leq c [(\|\sigma\|_2 + 1) (\|f\|_1 + \|v\|_2^2) + \|\sigma\|_2^2] \leq c(A+1) (\|f\|_1 + A^2).$$

Choosing $A^2 \equiv \|f\|_1 \ll 1$, one has

$$\|w\|_3 + \|\eta\|_2 \leq A,$$

hence $\Phi(K) \subset K$. The set K is convex and compact in $X \equiv H^2(\Omega) \times H^1(\Omega)$, and it is easily seen that the map Φ is continuous in X . The existence of a fixed point is now a consequence of Schauder's theorem.

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