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NOTE ON HYPERBOLIC PARTIAL DIFFERENTIAL EQUATIONS

BOGDAN RZEPECKI

1. Introduction

Let f be a continuous function on $[0, a] \times (-\infty, \infty)$ such that $|f(t, x)| \leq M \cdot t^p$ and $t^r \cdot |f(t, x) - f(t, y)| \leq L \cdot |x - y|^q$, where $M > 0$, $L > 0$, $p > -1$, $q \geq 1$ and r are constants with $q(p+1) - r = p$ and $(2M)^{q-1} L < (p+1)^q$. Under the above assumption O. Kooi [7] (cf. also [10]) proved the uniqueness of a solution of the equation $x' = f(t, x)$ satisfying the condition $x(0) = x_0$, and the uniform convergence of successive approximation to this solution. (We note that the first result of the above type was obtained by A. Rosenblatt in [12].) For the Darboux problem for hyperbolic differential equations similar theorems were obtained by J. S. W. Wong [17] and V. Ďurkovič [3]—[6].

The purpose of the present paper is to give some results on the following hyperbolic partial differential equation

$$(+) \quad \frac{\partial^2 z}{\partial x \partial y} = f(x, y, z),$$

where f is a continuous function satisfying the Kooi type conditions.

We consider the questions of the existence of the unique solution (as a limit of successive approximations) and the continuous dependence of the Darboux problem solution on the right-hand side for the above equation. The method used here is based on the concept due to Luxemburg [9] of the "generalized metric space" (see also [10], [11], [16], [3]—[6], [15], [17]). Our results are connected with Bielecki's method ([1], [2]) of norm changing, and extend the facts of [7], [10], [16], [13], [14], [17].

2. Preliminaries

Let X be a non-empty set and let d be a function defined on $X \times X$ with the following conditions:

- (L1) $0 \leq d(x, y) \leq \infty$,
- (L2) $d(x, y) = 0$ if and only if $x = y$,
- (L3) $d(x, y) = d(y, x)$,
- (L4) $d(x, y) \leq d(x, z) + d(z, y)$

for all x, y, z in X .

A *generalized metric space* (X, d) is a pair composed with a non-empty set X and a distance function d satisfying the above axioms (L1)—(L4). If further every d -Cauchy sequence in X is d -convergent (i.e., $\lim_{p, q \rightarrow \infty} d(x_p, x_q) = 0$ for a sequence (x_n) in X implies the existence of an element $x_0 \in X$ such that $\lim_{n \rightarrow \infty} d(x_n, x_0) = 0$), then X is called a *complete generalized metric space*.

Moreover, we shall use the notion of the \mathcal{L}^* -space [8]:

The set X is called an \mathcal{L}^* -space if a certain class of sequences in X (named elements of this class are *convergent sequences*) is distinguished in such a way that for every sequence (p_n) from this class there exists an element $p = \lim_{n \rightarrow \infty} p_n$ in X having the following properties:

1° if $\lim_{n \rightarrow \infty} p_n = p$ and $k_1 < k_2 < \dots$, then $\lim_{n \rightarrow \infty} p_{k_n} = p$;

2° if $p_n = p$ for all $n \geq 1$, then $\lim_{n \rightarrow \infty} p_n = p$;

3° if the sequence (p_n) is not convergent to p , then it contains a subsequence (p_{k_n}) in which every subsequence fails to converge to p .

Let X and Y be two \mathcal{L}^* -spaces. A mapping f of X into Y is called *continuous at the point* $x_0 \in X$ if for each sequence (x_n) in X converging to x_0 we have $\lim_{n \rightarrow \infty} f(x_n) = f(x_0)$. Further, a mapping f is called *continuous* (on the \mathcal{L}^* -space X) if it is continuous at each point of X .

Generally, the theorems on the existence of the unique solution to the initial-value problems for the differential equations are proved with the help of either a fixed-point theorem of the Banach type or successive approximations in various forms. The proof of our main result will be based on the following theorem of the Banach fixed-point principle type:

Proposition (cf. [16]). *Let (X, d) be a generalized complete metric space, let T_0 and T_n ($n = 1, 2, \dots$) be mappings of X into itself such that $\lim_{n \rightarrow \infty} d(T_n x, T_0 x) = 0$ for all x in X . Assume, moreover, that there exist constants $\varepsilon > 0$, $0 \leq k < 1$ and an element $z_0 \in X$ such that*

$$d(z_0, T_n z_0) \leq \varepsilon, \quad d(T_n x, T_n y) \leq k \cdot d(x, y)$$

for all $n \geq 1$ and $x, y \in X$ with $d(x, y) \leq \varepsilon$.

Then the equation $T_m x = x$ ($m = 0, 1, \dots$) has a unique solution $u_m \in X$ such that there exists an ε -chain joining z_0 and u_m^* , and $\lim_{n \rightarrow \infty} d(u_n, u_0) = 0$. Further, every sequence of successive approximations $x_n^{(m)} = T_m x_{n-1}^{(m)}$ ($n = 1, 2, \dots$), where $x_0^{(m)}$ is an element such that there exists an ε -chain joining z_0 and $x_0^{(m)}$, is d -convergent to this solution u_m .

3. Assumptions and notations

Let us put $G = (0, a) \times (0, b)$, $P = [0, a] \times [0, b]$ and $Q = P \times (-\infty, \infty)$. Let $\sigma \in C^1[0, a]$ and $\tau \in C^1[0, b]$ be functions such that $\sigma(0) = \tau(0)$. Assume, moreover, that λ is a bounded function on P and $\lambda(x, y) > 0$ for all (x, y) in G .

These assumptions remain valid throughout the paper and will not be repeated in formulations of particular results.

Let us denote:

\mathfrak{X} — the set of all real continuous functions z on P such that $z(x, 0) = \sigma(x)$ for $0 \leq x \leq a$ and $z(0, y) = \tau(y)$ for $0 \leq y \leq b$;

by $\tilde{\mathfrak{X}}$ — the set of real continuous functions f on Q such that

$$\begin{aligned} |f(x, y, z)| &\leq \delta(x, y) \quad \text{for all } (x, y, z) \in Q, \\ |f(x, y, u) - f(x, y, v)| &\leq L_f(x, y) \cdot |u - v|^{q_f} \end{aligned}$$

for all $(x, y) \in G$ and $-\infty < u, v < \infty$, where δ is a non-negative integrable function on P which does not depend on f , $L_f: P \rightarrow [0, +\infty]$ is a function and $q_f \geq 1$ is a constant which may depend on f .

Let us put:

$$\begin{aligned} A &= \sup_{(x, y) \in G} \frac{1}{\lambda(x, y)} \int_0^x \int_0^y \delta(u, v) \, du \, dv; \\ z^0(x, y) &= \sigma(x) + \tau(y) - \sigma(0) + \int_0^x \int_0^y \delta(u, v) \, du \, dv \quad \text{for } (x, y) \in P; \\ U_f(x, y) &= (\lambda(x, y))^{q_f} \cdot L_f(x, y) \quad \text{for } (x, y) \in P; \\ B_f &= \sup_{(x, y) \in G} \frac{1}{\lambda(x, y)} \int_0^x \int_0^y U_f(u, v) \, du \, dv. \end{aligned}$$

* A finite sequence x_0, x_1, \dots, x_q of points of X is called ε -chain joining x_0 and x_q if $d(x_{i-1}, x_i) \leq \varepsilon$ for $i = 1, 2, \dots, q$.

The hyperbolic equation (+) with the initial conditions

$$\begin{aligned} z(x, 0) &= \sigma(x) \quad \text{for } 0 \leq x \leq a, \\ z(0, y) &= \tau(y) \quad \text{for } 0 \leq y \leq b \end{aligned}$$

is equivalent to the integral equation

$$z(x, y) = \varphi_0(x, y) + \int_0^x \int_0^y f(u, v, z(u, v)) \, du \, dv,$$

where $\varphi_0(x, y) = \sigma(x) + \tau(y) - \sigma(0)$. The successive approximations of the solution to the above problem with $f \in \tilde{\mathcal{L}}$ are defined by

$$\begin{aligned} (*) \quad w_{j+1}(x, y) &= \varphi_0(x, y) + \int_0^x \int_0^y f(u, v, w_j(u, v)) \, du \, dv \\ &\quad (j = 0, 1, 2, \dots), \end{aligned}$$

where w_0 is an arbitrary function in \mathfrak{X} such that there exists a $2A$ -chain joining z^0 and w_0 .

We define on the set $\tilde{\mathcal{L}}$ a distance function d defined in the following way

$$d(z, w) = \sup_{(x, y) \in G} \frac{|z(x, y) - w(x, y)|}{\lambda(x, y)}.$$

We have: $(\sup_{(x, y) \in G} \lambda(x, y))^{-1} \cdot \sup_{(x, y) \in P} |z(x, y) - w(x, y)| \leq d(z, w)$. This shows that the d -convergence is generally stronger than the uniform one. Therefore, by a slight modification of the proof from [9] (cf. [11]) we can prove that (\mathfrak{X}, d) is a generalized complete metric space.

4. Main result

Let us put

$$T(f, z)(x, y) = \varphi_0(x, y) + \int_0^x \int_0^y f(u, v, z(u, v)) \, du \, dv$$

for $f \in \tilde{\mathcal{L}}$ and $z \in \mathfrak{X}$, where $\varphi_0(x, y) = \sigma(x) + \tau(y) - \sigma(0)$. The set $\tilde{\mathcal{L}}$ will be considered as an \mathcal{L}^* -space. Moreover, suppose that for every fixed z in \mathfrak{X} the transformation $T(\cdot, z)$ maps continuously the \mathcal{L}^* -space $\tilde{\mathcal{L}}$ into (\mathfrak{X}, d) .

Theorem. *Let $A < \infty$ and let $f \in \tilde{\mathcal{L}}$. Suppose that the function U_f is integrable on P and $(2A)^{q-1} \cdot B_f < 1$. Then there exists the unique function $z_f \in \mathfrak{X}$ satisfying the equation (+) on P . Moreover, there exists a $2A$ -chain joining z^0 and z_f , and every sequence of successive approximations $(*)$ is d -convergent to this z_f .*

Next assume that each U_f ($f \in \tilde{\mathcal{L}}$) is integrable on P and $k = \sup_{f \in \tilde{\mathcal{L}}} (2A)^{q-1} \cdot B_f < 1$.

Then the function $f \mapsto z_f$ maps continuously the \mathcal{L}^* -space $\tilde{\mathfrak{X}}$ into (\mathfrak{X}, d) .

Proof. Let $f_m \in \tilde{\mathfrak{X}}$ ($m = 0, 1, 2, \dots$) be such that $\lim_{m \rightarrow \infty} f_m = f_0$. We define a transformation T_m as $z \mapsto T(f_m, z)$. Then this T_m ($m = 0, 1, \dots$) maps \mathfrak{X} into itself, and for each $z \in \mathfrak{X}$ $d(T_n z, T_0 z) \rightarrow 0$ as $n \rightarrow \infty$.

Since $|z^0(x, y) - (T_n z^0)(x, y)| \leq 2 \cdot \int_0^x \int_0^y \delta(u, v) du dv$, and so $d(z^0, T_n z^0) \leq 2A$ for all $n \geq 1$. We now prove that $d(T_n z, T_n w) \leq k \cdot d(z, w)$ ($n = 1, 2, \dots$) for all $z, w \in \mathfrak{X}$ such that $d(z, w) \leq 2A$.

Indeed, for $(x, y) \in G$, $n \geq 1$ and $z, w \in \mathfrak{X}$ with $d(z, w) \leq 2A$ we have

$$\begin{aligned} |(T_n z)(x, y) - (T_n w)(x, y)| &\leq \int_0^x \int_0^y L_n(u, v) |z(u, v) - w(u, v)|^{q_n} du dv \leq \\ &\leq d(z, w) \cdot \int_0^x \int_0^y \lambda(u, v) \cdot L_n(u, v) \cdot |z(u, v) - w(u, v)|^{q_n - 1} du dv \leq \\ &\leq (2A)^{q_n - 1} \cdot d(z, w) \cdot \int_0^x \int_0^y U_n(u, v) du dv, \end{aligned}$$

whence

$$d(T_n z, T_n w) \leq (2A)^{q_n - 1} \cdot B_n \cdot d(z, w) \leq k \cdot d(z, w).$$

Consequently, our Proposition is applicable to the mappings T_m and the proof is finished.

Remark. Let $\sup_{(x, y) \in G} (\lambda((x, y)))^{-1} \cdot \int_0^x \int_0^y \lambda(u, v) du dv < \infty$. Assume, moreover,

that the set $\tilde{\mathfrak{X}}$ is considered as an \mathcal{L}^* -space, where $\lim_{n \rightarrow \infty} f_n = f_0$ means that

$$\sup_{\substack{(x, y) \in G \\ z \in \Omega}} \frac{1}{\lambda(x, y)} |f_n(x, y, z) - f_0(x, y, z)| \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

for every compact Ω in the Euclidean space. Then $T(\cdot, z)$ (z is fixed in \mathfrak{X}) maps continuously $\tilde{\mathfrak{X}}$ into \mathfrak{X} .

Indeed, fix z in \mathfrak{X} and let (f_n) be a sequence of $\tilde{\mathfrak{X}}$ converging to f_0 . Then

$$\begin{aligned} \left| \int_0^x \int_0^y [f_n(u, v, z(u, v)) - f_0(u, v, z(u, v))] du dv \right| &\leq \\ &\leq \sup_{\substack{(u, v) \in G \\ u \in z\{P\}}} \frac{|f_n(u, v, s) - f_0(u, v, s)|}{\lambda(u, v)} \cdot \int_0^x \int_0^y \lambda(u, v) du dv \end{aligned}$$

for (x, y) in G , whence

$$\begin{aligned} & \sup_{(x,y) \in G} \frac{1}{\lambda(x,y)} \left| \int_0^x \int_0^y [f_n(u,v,z(u,v)) - f_0(u,v,z(u,v))] du dv \right| \leq \\ & \leq \sup_{(x,y) \in G} \frac{1}{\lambda(x,y)} \int_0^x \int_0^y \lambda(u,v) du dv \cdot \sup_{\substack{(u,v) \in G \\ s \in z[P]}} \frac{|f_n(u,v,s) - f_0(u,v,s)|}{\lambda(u,v)} \end{aligned}$$

and therefore $d(T(f_n, z), T(f_0, z)) \rightarrow 0$ as $n \rightarrow \infty$.

Now we are going to give some corollaries from the above results. Let us denote:

by $\tilde{\delta}_0$ — the set $\tilde{\delta}$ with $q_f \equiv q$ and $\delta(x,y) = M \cdot (x \cdot y)^p$, $L_f(x,y) = L(x \cdot y)^{-r}$ on P , where $M > 0$, $L > 0$, $p > -1$, $q \geq 1$ and r are constants such that $q(p+1) - p = r$;

by $\tilde{\delta}_1$ — the set $\tilde{\delta}$ with $q_f \equiv 1$ and $L_f(x,y) \equiv A_f$ on P , where $A_f > 0$ is a constant (depending on a function $f \in \tilde{\delta}_1$);

by $\tilde{\delta}_2$ — the set $\tilde{\delta}_1$ with $\delta(x,y) \equiv C$ on P , where $C > 0$ is a constant;

by $\tilde{\mathfrak{X}}_0$ — the generalized metric space $\tilde{\mathfrak{X}}$ with a distance function d generated by $\lambda(x,y) = (x \cdot y)^{p+1}$ on P , where p is a constant from the definition of the set $\tilde{\delta}_0$;

by $C_0(P)$ — the set $\tilde{\mathfrak{X}}$ with the usual supremum metric.

The set $\tilde{\delta}_0$ be considered with the convergence defined as that in the above Remark in the case of $\lambda(x,y) = (x \cdot y)^{p+1}$. Moreover, we shall deal with the sets $\tilde{\delta}_1, \tilde{\delta}_2$ as \mathcal{L}^* -spaces endowed with the almost uniform convergence and pointwise convergence on Q , respectively.

Corollary 1. Suppose that $(2M)^{q-1} \cdot L < (p+1)^q$. Then for each $f \in \tilde{\delta}_0$ there exists a unique $z_f \in \tilde{\mathfrak{X}}_0$ satisfying the equation (+) on P and, moreover, the function $f \mapsto z_f$, which maps $\tilde{\delta}_0$ into $\tilde{\mathfrak{X}}_0$, is continuous.

Proof. Let us put $\lambda(x,y) = (x \cdot y)^{p+1}$ for $(x,y) \in P$, where p is a constant from the definition of the set $\tilde{\delta}_0$. Then

$$A = \sup_G \frac{1}{(x \cdot y)^{p+1}} \cdot \int_0^x \int_0^y M \cdot (u \cdot v)^p du dv = \frac{M}{(p+1)^2},$$

$$z^0(x,y) = \sigma(x) + \tau(y) - \sigma(0) + \frac{M}{(p+1)^2} (x \cdot y)^{p+1} \text{ on } P.$$

Further, for f in $\tilde{\mathcal{F}}_0$ we have:

$$U_f(x,y) = L(x \cdot y)^{q(p+1)-r} = L(x \cdot y)^p \text{ on } P,$$

$$B_f = \sup_G \frac{1}{(x \cdot y)^{p+1}} \int_0^x \int_0^y L(u \cdot v)^p du dv = \frac{L}{(p+1)^2}.$$

Since $(2M)^{q-1} \cdot L < (p+1)^{2q}$, and so

$$k = \sup_{f \in \tilde{\delta}_0} (2A)^{q-1} B_f = \frac{(2M)^{q-1} L}{(p+1)^{2q}} < 1.$$

The application of our Theorem and Remark completes the proof.

Corollary 2. For an arbitrary $f \in \tilde{\gamma}_i$ ($i = 1, 2$) there exists a unique $z_f \in C_0(P)$ satisfying the equation (+) on P . Moreover, if $\sup \{A_f: f \in \tilde{\gamma}_i\} < \infty$, then $f \mapsto z_f$ maps continuously $\tilde{\gamma}_i$ into $C_0(P)$.

Proof. Let us put $\lambda(x, y) = \exp(p(x + y))$ for $(x, y) \in P$, where p is a positive constant such that $p^2 > \sup \{A_f: f \in \tilde{\gamma}_i\}$.

The distance function d generated by the above λ is equivalent to the original supremum metric of the space of continuous functions on P . For $f \in \tilde{\gamma}_i$ ($i = 1, 2$) and $(x, y) \in P$

$$U_f(x, y) = A_f \cdot \exp(p(x + y)) \text{ on } P,$$

$$B_f = \sup_{(x,y)} \exp(-p(x + y)) \int_0^x \int_0^y U_f(u, v) \, du \, dv$$

and

$$k = \sup_{f \in \tilde{\gamma}_i} B_f = \sup_{f \in \tilde{\gamma}_i} A_f \cdot \sup_{(x,y)} \exp(-p(x + y)) \cdot \int_0^x \int_0^y \exp(p(u + v)) \, du \, dv \leq \\ \leq p^{-2} \cdot \sup_{f \in \tilde{\gamma}_i} A_f < 1.$$

Consequently the case $i = 1$ is obvious. Next, let us fix z in $C_0(P)$, let $f_n \in \tilde{\gamma}_2$ ($n = 1, 2, \dots$) and let the sequence (f_n) converge pointwise to f_0 . Then the Lebesgue bounded convergence theorem implies that $\lim_{n \rightarrow \infty} T(f_n, z)(x, y) = T(f_0, z)(x, y)$ on P . By an equicontinuity of a sequence $(T(f_n, z))$ on the compact P , $\lim_{n \rightarrow \infty} T(f_n, z)(x, y) = T(f_0, z)(x, y)$ uniformly on P . Finally, the application of our Theorem completes the proof.

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ЗАМЕТКА ОБ ГИПЕРБОЛИЧЕСКИХ ДИФФЕРЕНЦИАЛЬНЫХ УРАВНЕНИЯХ ВТОРОГО ПОРЯДКА (I)

Б. Жепецки

Резюме

В данной работе рассматривается применение обобщенного принципа Банаха неподвижной точки к исследованию задачи Дарбу для уравнения вида $\partial^2 z / \partial x \partial y = f(x, y, z)$ при условиях типа Кооп [7]. Полученные результаты о существовании единственного решения связаны с методом Белецкого о изменении нормы в теории дифференциальных уравнений. Кроме того, мы покажем, что наша задача поставлена корректно. Для этой цели в множествах правых частей и граничных условий введен понятия предела последовательности точек и тем самым наделим их структурной \mathcal{L}^* -пространства.