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CONNECTIONS ON SOME FUNCTIONAL BUNDLES

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INTRODUCTION

Our starting point was the idea of the Schrödinger connection on a double fibered manifold by Jadczyk and Modugno, [4], [5]. We discuss the “pure case” of two classical fiber bundles E_1 and E_2 over the same base and define a connection Γ on the bundle $\mathcal{F}(E_1, E_2)$ of all smooth maps from a fiber of E_1 into the fiber of E_2 over the same base point. We study systematically the geometry of the iterated tangent bundle of the infinite dimensional space $\mathcal{F}(E_1, E_2)$ as well as the jet prolongations of $\mathcal{F}(E_1, E_2)$ by means of the ideas introduced by the second author in [9]. Since we deal with functional bundles, our vector fields and connections represent a kind of differential operators. That is why we pay special attention to the case of finite order operators, in which we are able to deduce a very concrete description of the objects and operations in question.

In such a situation we found the simplest way for introducing the curvature of Γ in a construction by Ehresmann, [2], which is based on the notion of semiholonomic 2-jets. In the new context we were obliged to rearrange some results, deduced in the finite dimension by direct evaluation, into a more geometrical setting, which could be generalized to our infinite dimensional case. Only then we study the bracket of two vector fields on $\mathcal{F}(E_1, E_2)$. This is a modification of the bracket of two vertical prolongation operators on a classical fibered manifold by Kosmann-Schwarzbach, [11], and the second author, [8]. In Proposition 14 we deduce a satisfactory bracket formula for the curvature of Γ . We also discuss the absolute differentiation with respect to Γ and the special case E_2 is a vector bundle.

If we deal with two finite dimensional manifolds and a map between them, we always assume they are of class C^∞ , i.e. smooth in the classical sense. On the other

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hand, the idea of smoothness in the infinite dimension is taken from the theory of smooth structures by Frölicher, [3].

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1. THE TANGENT BUNDLE OF $\mathcal{F}(E_1, E_2)$

Let $p_1: E_1 \rightarrow M$ and $p_2: E_2 \rightarrow M$ be two classical fiber bundles (i.e. locally trivial fibered manifolds) over the same base. Consider the set of all fiber maps

$$\mathcal{F}(E_1, E_2) = \bigcup_{x \in M} C^\infty(E_{1x}, E_{2x})$$

and denote by $p: \mathcal{F}(E_1, E_2) \rightarrow M$ the canonical projection. We define no topology on $\mathcal{F}(E_1, E_2)$, but we introduce the concept of a smooth map from a classical manifold Q into $\mathcal{F}(E_1, E_2)$.

Definition 1. A map $f: Q \rightarrow \mathcal{F}(E_1, E_2)$ is called smooth, if

- (i) $p \circ f: Q \rightarrow M$ is smooth and
- (ii) the induced map $\tilde{f}: (p \circ f)^*E_1 \rightarrow E_2$,

$$\tilde{f}(q, y) = f(q)(y), \quad (q, y) \in (p \circ f)^*E_1$$

is also smooth.

As usual, $(p \circ f)^*E_1 \rightarrow Q$ denotes the bundle induced from E_1 by means of $p \circ f$, i.e.

$$(p \circ f)^*E_1 = \{(q, y) \in Q \times E_1 \mid (p \circ f)(q) = p_1(y)\}.$$

Thus, $\mathcal{F}(E_1, E_2)$ is endowed with a smooth structure in the sense of Frölicher, [3].

For every smooth curve $f: \mathbb{R} \rightarrow \mathcal{F}(E_1, E_2)$ we first construct the tangent vector $X = \frac{\partial}{\partial t} \Big|_0 (p \circ f) \in TM$ of its base map at $t = 0$. Write

$$T_X E_1 = (Tp_1)^{-1}(X) \subset TE_1 \quad \text{or} \quad T_X E_2 = (Tp_2)^{-1}(X) \subset TE_2,$$

so that $T_X E_1$ or $T_X E_2$ is an affine bundle over E_{1x} or E_{2x} , $x = p(f(0))$, with the derived vector bundle $T(E_{1x}) := V_x E_1$ or $T(E_{2x}) := V_x E_2$, respectively. Then f defines a map $T_0 f: T_X E_1 \rightarrow T_X E_2$ by

$$(1) \quad T_0 f \left(\frac{\partial}{\partial t} \Big|_0 h(t) \right) = \frac{\partial}{\partial t} \Big|_0 f(t)(h(t))$$

where we may assume that $h: \mathbb{R} \rightarrow E_1$ satisfies $p \circ f = p_1 \circ h$.

Definition 2. We say that two smooth curves $f, g: \mathbb{R} \rightarrow \mathcal{F}(E_1, E_2)$ satisfying $\frac{\partial}{\partial t}\big|_0 p \circ f = \frac{\partial}{\partial t}\big|_0 p \circ g = X$ determine the same tangent vector at $f(0) = g(0) = \varphi$, if

$$T_0f = T_0g: T_X E_1 \rightarrow T_X E_2.$$

The set $T\mathcal{F}(E_1, E_2)$ of all equivalence classes will be called the tangent bundle of $\mathcal{F}(E_1, E_2)$.

We write $\frac{\partial}{\partial t}\big|_0 f(t) \in T\mathcal{F}(E_1, E_2)$ for the tangent vector determined by f and $\pi: T\mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2)$ and $Tp: T\mathcal{F}(E_1, E_2) \rightarrow TM$ for the canonical projections. If $A \in T\mathcal{F}(E_1, E_2)$, then we denote by $\tilde{A}: T_{Tp(A)}E_1 \rightarrow T_{Tp(A)}E_2$ the associated map (1).

Remark 1. Let $\varepsilon \subset \mathcal{F}(E_1, E_2)$ be any subset. Then we define $T\varepsilon \subset T\mathcal{F}(E_1, E_2)$ by restricting ourselves to the smooth curves with values in ε .

One sees easily that $T_0f = T_0g: T_X E_1 \rightarrow T_X E_2$ is an affine bundle morphism over the base map $\varphi: E_{1x} \rightarrow E_{2x}$ with the derived linear morphism $T\varphi: T(E_{1x}) \rightarrow T(E_{2x})$. Indeed, let x^i be some local coordinates on M , y^p or z^a be some additional coordinates on E_1 or E_2 and

$$(2) \quad x^i = f^i(t), \quad z^a = f^a(y^p, t)$$

be the coordinate expression of $f(t)$. Write

$$Y^p = dy^p, \quad Z^a = dz^a, \quad \varphi^a(y) = f^a(y, 0), \quad \Phi^a(y) = \frac{\partial f^a(y^p, 0)}{\partial t}.$$

Then the coordinate form of (1) is

$$(3) \quad Z^a = \frac{\partial \varphi^a(y)}{\partial y^p} Y^p + \Phi^a(y).$$

Hence the tangent vector to (2) is locally characterized by two systems of numbers and two systems of functions

$$(4) \quad x^i = f^i(0), \quad X^i = \frac{\partial f^i(0)}{\partial t}, \quad \varphi^a(y^p), \quad \Phi^a(y^p).$$

The following lemma gives a global assertion of such a type.

Lemma 1. Let $F: T_X E_1 \rightarrow T_X E_2$ be an affine bundle morphism over $\varphi: E_{1x} \rightarrow E_{2x}$ with the derived linear morphism $T\varphi: T(E_{1x}) \rightarrow T(E_{2x})$. Then there exists a smooth curve $f: \mathbb{R} \rightarrow \mathcal{F}(E_1, E_2)$ such that $F = \tilde{A}$ for the tangent vector $A = \frac{\partial}{\partial t}\big|_0 f(t)$.

Proof. Consider some local trivializations $U \times S_1$ and $U \times S_2$ of E_1 and E_2 over a neighborhood $U \subset M$ of x . Then $\mathcal{F}(U \times S_1, U \times S_2) = U \times C^\infty(S_1, S_2)$. The restriction of F to $Y^p = 0$ represents a map $\bar{F}: S_1 \rightarrow TS_2$ along φ . By Proposition 5 from [16] there exists a smooth curve $\gamma: \mathbb{R} \rightarrow C^\infty(S_1, S_2)$ such that $\bar{F}(y) = \frac{\partial \tilde{\gamma}(y, 0)}{\partial t}$, where $\tilde{\gamma}: \mathbb{R} \times S_1 \rightarrow S_2$ is defined by $\tilde{\gamma}(y, t) = \gamma(t)(y)$. If $\delta: \mathbb{R} \rightarrow U$ is any curve with $\frac{\partial}{\partial t} \Big|_0 \delta = X$, then the curve $(\delta, \gamma): \mathbb{R} \rightarrow U \times C^\infty(S_1, S_2)$ has the required property. \square

Now we show that each fiber of $T\mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2)$ is a vector space. Consider $\tilde{A}_1: T_{X_1}E_1 \rightarrow T_{X_1}E_2$ and $\tilde{A}_2: T_{X_2}E_1 \rightarrow T_{X_2}E_2$ over the same φ . Given $Y \in (T_{X_1+X_2}E_1)_y$, $y \in E_{1x}$, we take any $W \in (T_{X_1}E_1)_y$, so that $Y - W \in (T_{X_2}E_1)_y$, and we define

$$\widetilde{A_1 + A_2}(Y) = \tilde{A}_1(W) + \tilde{A}_2(Y - W).$$

If we select another $\bar{W} \in (T_{X_1}E_1)_y$, then $W - \bar{W}$ is a vertical vector. Hence

$$\tilde{A}_1(\bar{W}) = \tilde{A}_1(W) + T\varphi(\bar{W} - W), \quad \tilde{A}_2(Y - \bar{W}) = \tilde{A}_2(Y - W) + T\varphi(W - \bar{W}),$$

so that our definition is correct. Further, for $0 \neq k \in \mathbb{R}$ we define

$$\widetilde{kA}: T_{kX}E_1 \rightarrow T_{kX}E_2 \quad \text{by} \quad \widetilde{kA}(Y) = k\tilde{A}\left(\frac{1}{k}Y\right)$$

while for $k = 0$ we prescribe $\widetilde{0A}$ to be $T\varphi: T_0E_{1x} \rightarrow T_0E_{2x}$. In coordinates, if $A_1 = (x^i, X_1^i, \varphi^a, \Phi_1^a)$ and $A_2 = (x^i, X_2^i, \varphi^a, \Phi_2^a)$, then

$$(5) \quad A_1 + A_2 = (x^i, X_1^i + X_2^i, \varphi^a, \Phi_1^a + \Phi_2^a), \quad kA_1 = (x^j, kX_1^i, \varphi^a, k\Phi_1^a).$$

This proves that each $\pi^{-1}(\varphi)$ is a vector space.

In general, consider another pair $E_3 \rightarrow N, E_4 \rightarrow N$ of fiber bundles over the same base and subset $\varepsilon \subset \mathcal{F}(E_1, E_2)$.

Definition 3. A map $f: \varepsilon \rightarrow \mathcal{F}(E_3, E_4)$ is called smooth, if $f \circ g: Q \rightarrow \mathcal{F}(E_3, E_4)$ is smooth for every smooth map $g: Q \rightarrow \varepsilon$.

Definition 4. A vector field on $\mathcal{F}(E_1, E_2)$ is a smooth map $A: \mathcal{F}(E_1, E_2) \rightarrow T\mathcal{F}(E_1, E_2)$ satisfying $\pi \circ A = \text{id}$. We say that A is projectable, if there exists a classical smooth vector field $A^0: M \rightarrow TM$ such that $A^0 \circ \pi = Tp \circ A$.

Write $V\mathcal{F}(E_1, E_2)$ for the kernel of $Tp: T\mathcal{F}(E_1, E_2) \rightarrow TM$, which will be called the vertical tangent bundle of $\mathcal{F}(E_1, E_2)$. Then we have an exact sequence

$$(6) \quad 0 \rightarrow V\mathcal{F}(E_1, E_2) \rightarrow T\mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2) \times_M TM \rightarrow 0$$

Consider a linear splitting $\Gamma: \mathcal{F}(E_1, E_2) \times_M TM \rightarrow T\mathcal{F}(E_1, E_2)$, i.e. $\pi \circ \Gamma = pr_1, T_p \circ \Gamma = pr_2$ and $\Gamma(\varphi, -): T_x M \rightarrow T_\varphi \mathcal{F}(E_1, E_2)$ is a linear map for each $\varphi \in \mathcal{F}(E_1, E_2), x = \pi(\varphi)$. Then for every vector field $X: M \rightarrow TM$ we have defined its Γ -lift $\Gamma X: \mathcal{F}(E_1, E_2) \rightarrow T\mathcal{F}(E_1, E_2)$. We say that Γ is smooth, if ΓX is smooth for every classical smooth vector field $X: M \rightarrow TM$.

Definition 5. A connection (in tangent form) on $\mathcal{F}(E_1, E_2)$ is a smooth linear splitting $\Gamma: \mathcal{F}(E_1, E_2) \times_M TM \rightarrow T\mathcal{F}(E_1, E_2)$.

Remark 2. If E_1 is the trivial fibering $M \rightarrow M$, then $\mathcal{F}(E_1, E_2) = E_2$ and we obtain the standard connection on $E_2 \rightarrow M$.

2. JET PROLONGATIONS OF $\mathcal{F}(E_1, E_2)$

The simplest way how to define the r -th jet prolongation of $\mathcal{F}(E_1, E_2)$ is based on the concept of the fiber r -jet, [9], [10]. In general, given a fiber bundle $E \rightarrow M$ and a manifold N , two maps $f, g: E \rightarrow N$ are said to determine the same fiber r -jet $j_x^r f = j_x^r g$ at $x \in M$, if $j_y^r f = j_y^r g$ for all $y \in E_x$. Every smooth section s of $\mathcal{F}(E_1, E_2)$ determines the associated base-preserving morphism $\tilde{s}: E_1 \rightarrow E_2, \tilde{s}(y) = s(p_1 y)(y)$.

Definition 6. Two sections $s_1, s_2: M \rightarrow \mathcal{F}(E_1, E_2)$ determine the same r -jet $j_x^r s_1 = j_x^r s_2$ at $x \in M$, if $j_x^r \tilde{s}_1 = j_x^r \tilde{s}_2$. The set $J^r \mathcal{F}(E_1, E_2)$ of all r -jets of the local sections of $\mathcal{F}(E_1, E_2)$ is called the r -jet prolongation of $\mathcal{F}(E_1, E_2)$.

However, it will be useful to discuss another approach as well. Since $\tilde{s}: E_1 \rightarrow E_2$ is a base-preserving morphism, we can construct its r -th jet prolongation $J^r \tilde{s}: J^r E_1 \rightarrow J^r E_2$. Write $J_x^r \tilde{s} = J^r \tilde{s}|_{J_x^r E_1}, x \in M$. By direct evaluation, one easily verifies.

Proposition 1. We have $j_x^r s_1 = j_x^r s_2$ iff $J_x^r \tilde{s}_1 = J_x^r \tilde{s}_2$.

Let $z^a = f^a(x^i, y^p)$ be the coordinate expression of \tilde{s} . Then the additional coordinate expression of $J_x^1 \tilde{s}$ is

$$(7) \quad z_i^a = \frac{\partial f^a}{\partial x^i} + \frac{\partial f^a}{\partial y^p} y_i^p$$

where y_i^p or z_i^a are the induced coordinates on $J^1 E_1$ or $J^1 E_2$. For $x = 0$, the functions $\varphi^a(y^p) := f^a(0, y^p)$ are the coordinates of the target $s(0)$ of $j_0^1 s_1$ and $J_0^1 \tilde{s}$ has the form

$$(8) \quad z_i^a = \frac{\partial \varphi^a(y)}{\partial y^p} y_i^p + \varphi_i^a(y), \quad \varphi_i^a(y) = \frac{\partial f^a(0, y)}{\partial x^i}$$

It is well-known that $J_x^1 E_1$ or $J_x^1 E_2$ is an affine bundle over E_{1x} or E_{2x} , whose derived vector bundle is $V_x E_1 \otimes T_x^* M$ or $V_x E_2 \otimes T_x^* M$, respectively. Obviously, (8) is an affine bundle morphism over φ with the derived linear morphism $T\varphi \otimes \text{id}_{T_x^* M}$. Similarly to §1, we denote by $\tilde{j}_x^1 s$ the associated map $J_x^1 \tilde{s}: J_x^1 E_1 \rightarrow J_x^1 E_2$. Analogously to Lemma 1, one can prove

Lemma 2. *Let $S: J_x^1 E_1 \rightarrow J_x^1 E_2$ be an affine bundle morphism over $\varphi: E_{1x} \rightarrow E_{2x}$ with the derived linear morphism $T\varphi \otimes \text{id}_{T_x^* M}$. Then there exists a local section s of $\mathcal{F}(E_1, E_2)$ such that $s(x) = \varphi$ and $\tilde{j}_x^1 s = S$.*

By (8), every $X = \frac{\partial}{\partial t}|_0 f \in T_x M$ and every $S = j_x^1 s$ define a vector

$$(9) \quad S(X) = \frac{\partial}{\partial t}|_0 (s \circ f) \in T_{s(x)} \mathcal{F}(E_1, E_2)$$

such that $Tp(S(X)) = X$.

Definition 7. A connection in the jet form on $\mathcal{F}(E_1, E_2)$ is a smooth section $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$ of the target jet projection.

Proposition 2. *The map (9) establishes a bijection between the jet form and the tangent form of connections on $\mathcal{F}(E_1, E_2)$.*

Proof. Using (8) we find directly that (9) defines a bijection between the linear splittings $T_x M \rightarrow T_\varphi \mathcal{F}(E_1, E_2)$ of Tp and the elements of $J^1 \mathcal{F}(E_1, E_2)_\varphi$. Assume the jet form of Γ is smooth and $f: Q \rightarrow \mathcal{F}(E_1, E_2)$ is a smooth map, so that $\Gamma \circ f: Q \rightarrow J^1 \mathcal{F}(E_1, E_2)$ is smooth. For every smooth vector field $X: M \rightarrow TM$, the map $(\Gamma \circ f)(X \circ p \circ f)$ is also smooth, so that the tangent form of Γ is smooth. Conversely, take a local basis X_1, \dots, X_m of vector fields on TM . Then $(\Gamma X_1) \circ f, \dots, (\Gamma X_m) \circ f$ are smooth maps $Q \rightarrow T \mathcal{F}(E_1, E_2)$. By (8) we deduce that $\Gamma \circ f: Q \rightarrow J^1 \mathcal{F}(E_1, E_2)$ is smooth. \square

To define the curvature of a connection of $\mathcal{F}(E_1, E_2)$ in §5, we shall use the second semiholonomic prolongation of $\mathcal{F}(E_1, E_2)$. We recall that $J^1(J^1 E_1 \rightarrow M) := \tilde{J}^2 E_1$ is the classical second nonholonomic prolongation of $E_1 \rightarrow M$. If x^i, y^p, y_i^p are the above local coordinates of $J^1 E_1$, then the induced coordinates on $\tilde{J}^2 E_1$ are $y_{0i}^p = \frac{\partial y^p}{\partial x^i}$ and $y_{ij}^p = \frac{\partial y_i^p}{\partial x^j}$. We have the target jet projection $\beta_1: \tilde{J}^2 E_1 \rightarrow J^1 E_1$ and the induced map $J^1 \beta: \tilde{J}^2 E_1 \rightarrow J^1 E_1$ of the target jet projection $\beta: J^1 E_1 \rightarrow E_1$. An element $Y \in \tilde{J}^2 E_1$ is said to be semiholonomic if $\beta_1(Y) = J^1 \beta(Y)$. In coordinates this is characterized by $y_i^p = y_{0i}^p$. All semiholonomic elements form a subbundle $\bar{J}^2 E_1 \subset \tilde{J}^2 E_1$, and the second holonomic prolongation $J^2 E$ is a subbundle of $\bar{J}^2 E$.

Since we have interpreted $J^1 \mathcal{F}(E_1, E_2)$ as a subset of $\mathcal{F}(J^1 E_1, J^1 E_2)$, we have defined $j_x^1 \sigma$ for a local smooth section σ of $J^1 \mathcal{F}(E_1, E_2) \rightarrow M$ by $j_x^1 \tilde{\sigma}$. In this way we

introduce the second nonholonomic prolongation $\tilde{J}^2 \mathcal{F}(E_1, E_2)$ of $\mathcal{F}(E_1, E_2)$. An element $j_x^1 \sigma$ is said to be semiholonomic, if $\sigma(x) = j_x^1(\beta \circ \sigma)$, where $\beta: J^1 \mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2)$ is the target jet projection. This defines $\tilde{J}^2 \mathcal{F}(E_1, E_2) \subset J^2 \mathcal{F}(E_1, E_2)$. The inclusion $J^2 \mathcal{F}(E_1, E_2) \subset \tilde{J}^2 \mathcal{F}(E_1, E_2)$ is given by $j_x^2 s \mapsto j_x^1(j^1 s)$.

Analogously to the first order case, $j_x^1 \sigma$ determines a map $\tilde{j}_x^1 \sigma: \tilde{J}_x^2 E_1 \rightarrow \tilde{J}_x^2 E_2$. In coordinates, if $\sigma = (f^a(x, y), f_i^a(x, y))$, then \tilde{s} is of the form

$$(10) \quad z^a = f^a(x, y), \quad z_i^a = \frac{\partial f^a(x, y)}{\partial y^p} y_i^p + f_i^a(x, y).$$

Hence

$$(11) \quad \varphi^a(y) = f^a(0, y), \quad \varphi_i^a = f_i^a(0, y), \quad \varphi_{0i}^a = \frac{\partial f^a(0, y)}{\partial x^i}, \quad \varphi_{ij}^a = \frac{\partial f_i^a(0, y)}{\partial x^j}$$

are the coordinates of $j_0^1 \sigma$. From (10) we obtain the coordinate expression of $\tilde{j}_x^1 \sigma$ in the form $z^a = \varphi^a(y)$ and

$$(12) \quad z_i^a = \frac{\partial \varphi^a}{\partial y^p} y_i^p + \varphi_i^a, \quad z_{0i}^a = \frac{\partial \varphi^a}{\partial y^p} y_{0i}^p + \varphi_{0i}^a,$$

$$z_{ij}^a = \varphi_{ij}^a + \frac{\partial \varphi_i^a}{\partial y^p} y_{0j}^p + \frac{\partial \varphi_{0j}^a}{\partial y^p} y_i^p + \frac{\partial^2 \varphi^a}{\partial y^p \partial y^q} y_i^p y_{0j}^q + \frac{\partial \varphi^a}{\partial y^p} y_{ij}^p.$$

Using (12) we deduce directly the following assertion.

Proposition 3. $j_x^1 \sigma$ is semiholonomic or holonomic iff $\tilde{j}_x^1 \sigma$ maps $\tilde{J}_x^2 E_1$ into $\tilde{J}_x^2 E_2$ or $J_x^2 E_1$ into $J_x^2 E_2$, respectively.

In coordinates, an element of $\tilde{J}^2 \mathcal{F}(E_1, E_2)$ is characterized by $\varphi_i^a = \varphi_{0i}^a$ and the additional condition for a holonomic element is $\varphi_{ij}^a = \varphi_{ji}^a$.

We remark that the higher order nonholonomic and semiholonomic prolongations of $\mathcal{F}(E_1, E_2)$ can be defined in a quite similar way.

3. THE FINITE ORDER CASE

Since both vector fields from §1 and the connections from §2 are defined on a functional bundle, they represent a kind of differential operators. We are going to describe the simplest case of finite order operators.

Definition 8. A projectable vector field $A: \mathcal{F}(E_1, E_2) \rightarrow T \mathcal{F}(E_1, E_2)$ over $A^0: M \rightarrow TM$ is of order r , if the condition $j_y^r \varphi = j_y^r \psi$, $\varphi, \psi \in C^\infty(E_{1x}, E_{2x})$, $y \in E_{1x}$ implies that the restrictions of $\widetilde{A(\varphi)}$ and $\widetilde{A(\psi)}$ over y coincide, i.e.

$$(13) \quad \widetilde{A(\varphi)}|_{(T_{A^0(x)} E_1)_y} = \widetilde{A(\psi)}|_{(T_{A^0(x)} E_1)_y}.$$

Let $S(TE_1, TE_2)$ be the set of all affine morphism $(T_X E_1)_y \rightarrow (T_X E_2)_z$, $p_1 y = p_2 z = \pi_M X$, where $\pi_M: TM \rightarrow M$ is the bundle projection. This is a fibered manifold over $E_1 \times_M E_2 \times_M TM$. Write

$$\mathcal{F}J^r(E_1, E_2) = \bigcup_{x \in M} J^r(E_{1x}, E_{2x}).$$

This is a classical manifold as well.

A projectable r -th order vector field $A: \mathcal{F}(E_1, E_2) \rightarrow T\mathcal{F}(E_1, E_2)$ over A^0 defines the associated map $\mathcal{A}: \mathcal{F}J^r(E_1, E_2) \rightarrow S(TE_1, TE_2)$ by

$$(14) \quad \mathcal{A}(j_y^r \varphi) = A(\varphi)|_{(T_{A^0(x)} E_1)_y}.$$

Proposition 4. *The associated map of a projectable r -th order vector field on $\mathcal{F}(E_1, E_2)$ is a classical C^∞ -map.*

Proof. This follows from the fact that A is smooth in the sense of Definition 3 quite analogously to [6]. □

The local coordinates on $\mathcal{F}J^r(E_1, E_2)$ induced by x^i, y^p and z^a are z_α^a , $1 \leq |\alpha| \leq r$, where α is a multiindex, the range of which is the fiber dimension of E_1 . Hence the coordinate form of \mathcal{A} is $X^i(x^j)$ and

$$(15) \quad \Phi^\alpha = \Phi^\alpha(x^i, y^p, z_\alpha^a), \quad 0 \leq |\alpha| \leq r.$$

The derived linear map of each element of $S(TE_1, TE_2)$ is identified with an element of $\mathcal{F}J^1(E_1, E_2)$. This defines a map $D: S(TE_1, TE_2) \rightarrow \mathcal{F}J^1(E_1, E_2)$ and the following diagram commutes:

$$\begin{array}{ccc} \mathcal{F}J^1(E_1, E_2) & & \\ \beta_r \uparrow & \swarrow D & \\ \mathcal{F}J^r(E_1, E_2) & \xrightarrow{\mathcal{A}} & S(TE_1, TE_2) \\ \downarrow & & \downarrow \\ E_1 \times_M E_2 & \xrightarrow[\text{id} \times A^0]{\text{id} \times A^0} & E_1 \times_M E_2 \times_M TM \end{array}$$

where β_r is the jet projection. Conversely, let $\mathcal{A}: \mathcal{F}J^r(E_1, E_2) \rightarrow S(TE_1, TE_2)$ be a smooth map with an underlying vector field $A^0: M \rightarrow TM$ such that (16) commutes. Then the rule

$$(17) \quad A(\widetilde{\varphi}) = \bigcup_{y \in E_{1x}} \mathcal{A}(j_y^r \varphi)$$

defines a projectable r -th order vector field A on $\mathcal{F}(E_1, E_2)$.

Since $T\mathcal{F}(E_1, E_2)$ is a subset of $\mathcal{F}(TE_1, TE_2)$, we can define the second tangent bundle $T(T\mathcal{F}(E_1, E_2))$. This will be described in more detail in §6. Here we restrict ourselves to a general remark, which is related to our study of the order of connections.

Definition 9. A vector field $A: \mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2)$ is called differentiable if the formula

$$(18) \quad TA\left(\frac{\partial}{\partial t}\Big|_0 f\right) = \frac{\partial}{\partial t}\Big|_0 A \circ f$$

defines a smooth map $TA: T\mathcal{F}(E_1, E_2) \rightarrow TT\mathcal{F}(E_1, E_2)$.

From (16) we easily deduce (see the coordinate formula in §6) the following assertion.

Proposition 5. Every r -th order vector field on $\mathcal{F}(E_1, E_2)$ is differentiable.

Definition 10. A connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1\mathcal{F}(E_1, E_2)$ is of order r if the condition $j_y^r\varphi = j_y^r\psi$, $\varphi, \psi \in C^\infty(E_{1x}, E_{2x})$, $y \in E_{1x}$, implies

$$(19) \quad \widetilde{\Gamma}(\varphi)|_{J_y^1 E_1} = \widetilde{\Gamma}(\psi)|_{J_y^1 E_1}.$$

Let $S(J^1 E_1, J^1 E_2)$ be the set of all affine maps $(J^1 E_1)_y \rightarrow (J^1 E_2)_z$ with the derived linear map of the form

$$(20) \quad B \otimes \text{id}_{T_x^* M} \quad B \in \mathcal{L} \in (V_y E_1, V_z E_2).$$

An r -th order connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1\mathcal{F}(E_1, E_2)$ defines the associated map $\mathcal{G}: \mathcal{F}J^r(E_1, E_2) \rightarrow S(J^1 E_1, J^1 E_2)$ by

$$(21) \quad \mathcal{G}(j_y^r\varphi) = \widetilde{\Gamma}(\varphi)|_{J_y^1 E_1}.$$

The coordinate form of \mathcal{G} is

$$(22) \quad \Phi_i^\alpha = \Phi_i^\alpha(x^i, y^p, z_\alpha^a), \quad 0 \leq |\alpha| \leq r.$$

Analogously to Proposition 4, one proves

Proposition 6. The associated map of an r -th order connection $\mathcal{F}(E_1, E_2) \rightarrow J^1\mathcal{F}(E_1, E_2)$ is a classical C^∞ -map.

Let $D: S(J^1 E_1, J^1 E_2) \rightarrow \mathcal{F} J^1(E_1, E_2)$ be the map defined by (20). Then the following diagram commutes

$$(23) \quad \begin{array}{ccc} \mathcal{F} J^1(E_1, E_2) & & \\ \uparrow \beta_r & \swarrow D & \\ \mathcal{F} J^r(E_1, E_2) & \xrightarrow{\mathcal{G}} & S(J^1 E_1, J^1 E_2) \end{array}$$

Conversely, let $\mathcal{G}: \mathcal{F} J^r(E_1, E_2) \rightarrow S(J^1 E_1, J^1 E_2)$ be a smooth morphism over the identity of $E_1 \times E_2$ such that (23) commutes. Then the rule

$$(24) \quad \widetilde{\Gamma}(\varphi) = \bigcup_{y \in E_{1r}} \mathcal{G}(j_y^r \varphi)$$

defines an r -th order connection on $\mathcal{F}(E_1, E_2)$.

Analogously to Definition 9, we introduce

Definition 11. A connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$ is called differentiable if the formula

$$(25) \quad J^1 \Gamma(j_x^1 s) = j_x^1 (\Gamma \circ s)$$

defines a smooth map $J^1 \mathcal{F}(E_1, E_2) \rightarrow \tilde{J}^2 \mathcal{F}(E_1, E_2)$.

Proposition 7. Every r -th order connection is differentiable.

Proof. We deduce from (22) the coordinate form of $J^1 \Gamma$ in some coordinates x^i, φ^a, ψ_i^a on $J^1 \mathcal{F}(E_1, E_2)$ and $x^i, \varphi^a, \varphi_i^a, \varphi_{0i}^a, \varphi_{ij}^a$ on $\tilde{J}^2 \mathcal{F}(E_1, E_2)$. Take a section σ

$$(26) \quad z^a = \Psi^a(x^i, y^p)$$

so that $\varphi^a = \psi^a(0, y)$ and $\psi_i^a = \frac{\partial \psi^a(0, y)}{\partial x^i}$. Then we obtain for $\Gamma \circ \sigma$

$$(27) \quad z_i^a = \frac{\partial \psi^a(x, y)}{\partial y^p} y_i^p + \Phi_i^a(x, y, \partial_\alpha \psi^a(x, y)).$$

Now (26) yields

$$(28) \quad z_{0i}^a = \frac{\partial \psi^a(0, y)}{\partial y^p} y_{0i}^p + \frac{\partial \psi^a(0, y)}{\partial x^i}, \quad \text{i.e.} \quad \varphi_{0i}^a = \psi_i^a$$

and (27) implies

$$(29) \quad \begin{aligned} z_{ij}^a &= \frac{\partial \psi_j^a}{\partial y^p} y_i^p + \frac{\partial^2 \varphi^a}{\partial y^p \partial y^q} y_i^p y_{0j}^q + \frac{\partial \varphi^a}{\partial y^p} y_{ij}^p + \frac{\partial \varphi_i^a}{\partial y^p} y_{0j}^p \\ &+ \frac{\partial \Phi_i^a}{\partial x^j} + \frac{\partial \Phi_i^a}{\partial z^b} \partial_j \psi^b + \dots + \frac{\partial \Phi_i^a}{\partial z_\alpha^b} \partial_\alpha \partial_j \psi^b. \end{aligned}$$

In particular, (29) shows that $J^1 \Gamma$ is well-defined and smooth. □

Following Virsik, [17], if Γ is differentiable and Δ is another connection $\mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$, we define a section

$$(30) \quad \Gamma * \Delta = J^1 \Gamma \circ \Delta: \mathcal{F}(E_1, E_2) \rightarrow \tilde{J}^2 \mathcal{F}(E_1, E_2).$$

The order of such a section can be introduced similarly to Definition 10.

Proposition 8. *If Γ and Δ are connections of orders r and s , respectively, then $\Gamma * \Delta$ has the order $r + s$.*

Proof. We substitute the associated map of Δ into (28) and (29). □

To obtain an explicit formula for the associated map of $\Gamma * \Delta$, we introduce the following concept. Having a smooth function $f: \mathcal{F}J^r(E_1, E_2) \rightarrow \mathbb{R}$, we define its formal differential Df by

$$(31) \quad Df: \mathcal{F}J^{r+1}(E_1, E_2) \rightarrow V^*E_1, Df(j_y^{r+1}\varphi) = d_y f(j^r\varphi).$$

Then every vertical vector field μ on V^*E_1 determines $\langle Df, \mu \rangle: \mathcal{F}J^{r+1}(E_1, E_2) \rightarrow \mathbb{R}$. For the coordinate vector fields $\frac{\partial}{\partial y^p}$ we obtain the formal derivatives

$$(32) \quad D_p f = \frac{\partial f}{\partial y^p} + \frac{\partial f}{\partial z^a} z_p^a + \dots + \frac{\partial f}{\partial z_\alpha^a} z_{\alpha+p}^a.$$

By iteration, we introduce $D_\beta f: \mathcal{F}J^{r+|\beta|}(E_1, E_2) \rightarrow \mathbb{R}$. Let $\Psi_i^a(x^i, y^p, z_\beta^a)$, $0 \leq |\beta| \leq s$, be associated map of Δ . Then the coordinate form of the main term of (29) is

$$(33) \quad \varphi_{ij}^a = \frac{\partial \Phi_i^a}{\partial x^j} + \frac{\partial \Phi_i^a}{\partial z^b} \Psi_j^b + \frac{\partial \Phi_i^a}{\partial z_p^b} D_p \Psi_j^b + \dots + \frac{\partial \Phi_i^a}{\partial z_\alpha^b} D_\alpha \Psi_j^b.$$

Remark 3. In both cases of connections in the jet form and of projectable vector fields we have a situation somewhat similar to the vertical prolongation operators on classical fibered manifolds studied by Kosmann-Schwarzbach, [11], and the second author, [8]. In [10] Slovák deduced that every vertical prolongation operator is differentiable in the sense of our Definitions 9 and 11. However, his proof is based on quite sophisticated procedures in mathematical analysis, so that we have the feeling that such a problem in our setting is beyond the scope of the present paper.

4. EHRESMANN PROLONGATION IN THE CLASSICAL CASE

We describe some properties of connections on a classical fibered manifold $p: E \rightarrow M$ in a way which can be generalized to $\mathcal{F}(E_1, E_2)$. Given $A \in J_y^1 E$ and $B \in T_x M, x = py$, we denote by $A(B) \in T_y E$ the A -lift of B . We show that every $A \in \tilde{J}_y^2 E$ induces similarly a lifting $\lambda A: TT_x M \rightarrow TT_y E$. If $A = J_x^1 \sigma$ and $B = \frac{\partial}{\partial t} \Big|_0 f(t) \in TT_x M$, then we construct $\sigma(\pi(f(t)))(f(t)): \mathbb{R} \rightarrow TE$ and set

$$(34) \quad \lambda A(B) = \frac{\partial}{\partial t} \Big|_0 \sigma(\pi(f(t)))(f(t))$$

where $\pi: TM \rightarrow M$ is the bundle projection. Given some local fiber coordinates x^i, y^p on E , we have the induced coordinates $y_i^p, y_{0i}^p, y_{ij}^p$ on $\tilde{J}^2 E$, the induced coordinates X^i, Y^p on TE and the additional coordinates on TEE denoted by a dot. Then one finds easily the following coordinate form of (34):

$$(35) \quad Y^p = y_i^p X^i, \quad \dot{y}^p = y_{0i}^p \dot{x}^i, \quad \dot{Y}^p = y_{ij}^p X^i \dot{x}^j + y_i^p \dot{X}^i.$$

Let κ be the canonical involution of the second tangent bundle. If $A \in \tilde{J}_y^2 E$, then $\kappa_E \circ \lambda A \circ \kappa_M: TT_x M \rightarrow TT_y E$ is the lifting of another element $\kappa A \in \tilde{J}_y^2 E$, [15]. In coordinates, $y_{ji}^p(\kappa A) = y_{ij}^p(A)$. Hence A is holonomic iff $\kappa A = A$. Since $\tilde{J}_y^2 E \rightarrow J^1 E$ is an affine bundle with the derived vector bundle $VE \otimes (\otimes^2 T^* M)$, the points κA and A determine a vector $\Delta(A) := \overrightarrow{(\kappa A)A} \in V_y E \otimes \Lambda^2 T_x^* M$, which is called the deviation (or difference tensor) of A , [7], [12]. The coordinates of $\Delta(A)$ are $y_{ij}^p - y_{ji}^p$. If $X_1, X_2 \in T_x M$, then we have $\Delta(A)(X_1, X_2) \in V_y E$.

Let $\pi_1 = \pi_{TM} = TTM \rightarrow TM$ and $\pi_2 = T\pi_{TM} = TTM \rightarrow TM$ be the canonical projections. Consider $C, D \in TT_x M$ satisfying

$$(36) \quad \pi_1(C) = \pi_2(D) \quad \text{and} \quad \pi_1(D) = \pi_2(C).$$

Since κ exchanges the two projections, C and κD are in the same fiber of TTM with respect to π_1 and satisfy $\pi_2(C - \kappa D) = 0$. Hence $C - \kappa D$ is a tangent vector to a fiber of TM and such a vector can be identified with an element of $T_x M$, which will be denoted by $C \dot{-} D$ and called the strong difference of C and D . In coordinates, if

$$(37) \quad C \equiv (a^i, b^i, c^i), D \equiv (b^i, a^i, d^i) \quad \text{then} \quad C \dot{-} D \equiv (c^i - d^i).$$

In [8] it is deduced the the bracket $[X, Y]$ of two vector fields $X, Y: M \rightarrow TM$ can be expressed by

$$(38) \quad [X, Y] = TY \circ X \dot{-} TX \circ Y.$$

Lemma 3. Let $C, D \in TT_x M$ satisfy the condition (36) for the strong difference and $A \in \bar{J}_y^2 E$. Then $\lambda A(C)$, $\lambda A(D)$ also satisfy (36) and

$$\Delta A(\pi_1 C, \pi_2 C) = (\lambda A(C) \dot{-} \lambda A(D)) - \beta_1(A)(C \dot{-} D)$$

where $\beta_1: \bar{J}_1^2 E \rightarrow J^1 E$ is the jet projection.

Proof. By (35) and (37) we have $\lambda A(C) = (y_i^p a^i, y_i^p b^i, y_{ij}^p a^i b^j + y_i^p c^i)$, $\lambda A(D) = (y_i^p b^i, y_i^p a^i, y_{ij}^p b^i a^j + y_i^p d^i)$. This implies our claim. \square

According to Remark 2, two connections $\Gamma, \Delta: E \rightarrow J^1 E$ determine $\Gamma * \Delta = J^1 \Gamma \circ \Delta: E \rightarrow \bar{J}^2 E$. For $\Gamma = \Delta$ the values of $\Gamma * \Gamma$ lie in $\bar{J}_y^2 E$. In this case we obtain a construction closely related to an idea by Ehresmann, [2].

Definition 12. The map $\tilde{\Gamma} = J^1 \Gamma \circ \Gamma: E \rightarrow \bar{J}^2 E$ is the Ehresmann prolongation of Γ . The composition

$$(39) \quad C\Gamma := -\Delta \circ \tilde{\Gamma}: E \rightarrow VE \otimes \Lambda^2 T^* M$$

is the curvature of Γ .

To deduce that $C\Gamma$ coincides with the standard curvature of Γ , we need a property of the lifting map

$$\lambda \tilde{\Gamma}: E \times_M TTM \rightarrow TTE.$$

Consider two vector fields $X, Y: M \rightarrow TM$, so that $TX \circ Y: M \rightarrow TTM$.

Lemma 4. We have

$$\lambda \tilde{\Gamma}(TX \circ Y) = (T\Gamma X) \circ \Gamma Y: E \rightarrow TTE.$$

Proof. We have $\tilde{\Gamma}(y) = j_x^1(\Gamma \circ s)$, $j_x^1 s = \Gamma(y)$. If $Y(x) = \frac{\partial}{\partial t} \Big|_0 f(t)$, then

$$TX(Y(x)) = \frac{\partial}{\partial t} \Big|_0 (X \circ f).$$

By (34),

$$\lambda \tilde{\Gamma}(TX(Y(x))) = \frac{\partial}{\partial t} \Big|_0 \Gamma(s(f(t)))(X(f(t))) = (T\Gamma X \circ \Gamma Y)(y).$$

\square

Proposition 9. For every vector fields $X, Y: M \rightarrow TM$, we have

$$C\Gamma(X, Y) = [\Gamma X, \Gamma Y] - \Gamma([X, Y]).$$

Proof. Consider $TX \circ Y, TY \circ X: M \rightarrow TTM$. By Lemma 4 we obtain

$$\lambda\tilde{\Gamma}(TX \circ Y) = T\Gamma X \circ \Gamma Y \quad \text{and} \quad \lambda\tilde{\Gamma}(TY \circ X) = T\Gamma Y \circ \Gamma X.$$

Then Lemma 3 and (38) imply

$$\begin{aligned} \Delta \circ \tilde{\Gamma}(X, Y) &= (\lambda\tilde{\Gamma}(TX \circ Y) - \lambda\tilde{\Gamma}(TY \circ X)) - \Gamma(TX \circ Y - TY \circ X) = \\ &= -[\Gamma X, \Gamma Y] + \Gamma([X, Y]). \end{aligned}$$

□

5. THE CURVATURE OF A CONNECTION ON $\mathcal{F}(E_1, E_2)$

The deviation of an element $j_x^1\sigma \in \tilde{J}^2 \mathcal{F}(E_1, E_2)$ can be defined by means of the associated map $\tilde{j}_x^1\sigma: \tilde{J}_x^2 E_1 \rightarrow \tilde{J}_x^2 E_2$. In the semiholonomic case we have $\varphi_i^a = \varphi_{0i}^a$. So if we take a holonomic 2-jet $Y \in J_x^2 E_1$, then the right-hand side of the second line in (12) is symmetric except the first term. Hence the deviation $\Delta(\tilde{j}_x^1\sigma(Y))$ is independent of y_i^p and y_{ij}^p . This defines a map $\Delta(j_x^1\sigma): E_{1x} \rightarrow V_x E_2 \otimes \Lambda^2 T_x^* M$ over φ , i.e. an element of $\mathcal{F}(E_1, VE_2 \otimes \Lambda^2 T^* M)$.

Definition 13. $\Delta(j_x^1\sigma)$ is called the deviation of $j_x^1\sigma$. The coordinate form of $\Delta(j_x^1\sigma)$ is $\varphi_{ij}^a - \varphi_{ji}^a$.

Definition 14. For a differentiable connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$, the map $\tilde{\Gamma} := J^1\Gamma \circ \Gamma: \mathcal{F}(E_1, E_2) \rightarrow \tilde{J}^2 \mathcal{F}(E_1, E_2)$ is the Ehresmann prolongation of Γ .

Definition 15. The composition

$$C\Gamma := -\Delta \circ \tilde{\Gamma}: \mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, VE_2 \otimes \Lambda^2 T^* M)$$

is the curvature of a differentiable connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$.

Clearly, $C\Gamma$ is a section of the canonical projection $\mathcal{F}(E_1, VE_2 \otimes \Lambda^2 T^* M) \rightarrow \mathcal{F}(E_1, E_2)$.

Let Γ be an r -th order connection with the associated map $\Phi_i^a(x^i, y^p, z_\alpha^a)$. Then we obtain the associated map of $C\Gamma$ by setting $\Psi_i^a = \Phi_i^a$ in (33) and by antisymmetrizing in i and j . This implies

Proposition 10. The curvature of an r -th order connection has the order $2r$.

6. THE BRACKET FORMULA FOR CURVATURE

As remarked in §3, the inclusion $T\mathcal{F}(E_1, E_2) \subset \mathcal{F}(TE_1 \rightarrow TM, TE_2 \rightarrow TM)$ defines the second tangent bundle $T(T\mathcal{F}(E_1, E_2)) = TT\mathcal{F}(E_1, E_2)$. We have a projection $TTp: TT\mathcal{F}(E_1, E_2) \rightarrow TTM$ and two projections $\pi_T, T\pi: TT\mathcal{F}(E_1, E_2) \rightarrow T\mathcal{F}(E_1, E_2)$. In the above coordinates, consider an element $F \in TT\mathcal{F}(E_1, E_2)$ tangent to a curve $x^j(t), X^i(t), f^a(y, t)$ and

$$Z^a = \frac{\partial f^a(y, t)}{\partial y^p} Y^p + \Phi^a(y, t).$$

Then its associated map $\tilde{F}: TT_x E_1 \rightarrow TT_x E_2, X = TTp(F)$, is of the form

$$(40) \quad Z^a = \frac{\partial \varphi^a}{\partial y^p} Y^p + \Phi^a(y), \dot{z}^a = \frac{\partial \varphi^a}{\partial y^p} \dot{y}^p + f^a(y)$$

$$\dot{Z}^a = F^a(y) + \frac{\partial \Phi^a}{\partial y^p} \dot{y}^p + \frac{\partial f^a}{\partial y^p} Y^p + \frac{\partial^2 \varphi^a}{\partial y^p \partial y^q} Y^p \dot{y}^q + \frac{\partial \varphi^a}{\partial y^p} \dot{Y}^p.$$

So $\varphi^a, \Phi^a, f^a, F^a$ are the functional coordinates of F , which are completed by the coordinates $x^i, X^i, \dot{x}^i, \dot{X}^i$ of $X \in TTM$. The coordinate form of π_T or $T\pi$ is

$$\pi_T(x^i, X^i, \dot{x}^i, \dot{X}^i, \varphi^a, \Phi^a, f^a, F^a) = (x^i, X^i, \varphi^a, \Phi^a),$$

$$T\pi(x^i, X^i, \dot{x}^i, \dot{X}^i, \varphi^a, \Phi^a, f^a, F^a) = (x^i, \dot{x}^i, \varphi^a, f^a).$$

Consider the canonical involution κ_{E_1} or κ_{E_2} of the second tangent bundle.

Proposition 11. *For every $F \in TT\mathcal{F}(E_1, E_2)$ over $X \in TTM$ there exists a unique element $\kappa F \in TT\mathcal{F}(E_1, E_2)$ such that its associated map $\widetilde{\kappa F}: TT_{\kappa_M X} E_1 \rightarrow TT_{\kappa_M X} E_2$ is $\widetilde{\kappa F} = \kappa_{E_2} \circ \tilde{F} \circ \kappa_{E_1}$.*

Proof. This follows from (40). □

Obviously, the coordinate form of κ is

$$(41) \quad \kappa(x, X, \dot{x}, \dot{X}, \varphi, \Phi, f, F) = (x, \dot{x}, X, \dot{X}, \varphi, f, \Phi, F).$$

Consider $C, \bar{C} \in TT\mathcal{F}(E_1, E_2)$ over $X, \bar{X} \in TTM$ satisfying

$$(42) \quad \pi_T(C) = T\pi(\bar{C}) \quad \text{and} \quad \pi_T(\bar{C}) = T\pi(C).$$

Then we define the strong difference $C \dot{-} \bar{C} \in T\mathcal{F}(E_1, E_2)$, $Tp(C \dot{-} \bar{C}) = X \dot{-} \bar{X}$, as follows. For every $B \in (T_{X \dot{-} \bar{X}} E_1)_y$ we take any $Y, \bar{Y} \in (TTE_1)_y$ over X, \bar{X}

such that $Y \dot{-} \bar{Y} = B$. Then one easily verifies that $C(Y)$, $\bar{C}(\bar{Y})$ also satisfy (42), $C(Y) \dot{-} \bar{C}(\bar{Y})$ depends on C , \bar{C} and B only and represents the associated map of an element $C \dot{-} \bar{C} \in T \mathcal{F}(E_1, E_2)$, whose coordinates are

$$(43) \quad (x^i, \dot{X}^i - \bar{X}^i, \varphi^a, F^a - \bar{F}^a).$$

Let A, B be two differentiable vector fields on $\mathcal{F}(E_1, E_2)$. Then the maps $TA \circ B, TB \circ A: \mathcal{F}(E_1, E_2) \rightarrow TT \mathcal{F}(E_1, E_2)$ satisfy the condition (42) at every $\varphi \in \mathcal{F}(E_1, E_2)$.

Definition 16. The vector field

$$[A, B] := TB \circ A \dot{-} TA \circ B: \mathcal{F}(E_1, E_2) \rightarrow T \mathcal{F}(E_1, E_2)$$

is called the bracket of A and B .

By (38) we immediately deduce

Proposition 12. *If A and B are projectable over A^0 and B^0 , then $[A, B]$ is projectable over $[A^0, B^0]$.*

Assume A is of order r and B is of order s with the associated maps $X^i(x)$, $A^\alpha(x^i, y^p, z_\alpha^a)$, $|\alpha| \leq r$ and $Y^i(x)$, $B^\beta(x^i, y^p, z_\beta^a)$, $|\beta| \leq s$, respectively. Analogously to §3, the fourth component of the associated map of $TA \circ B$ is

$$(44) \quad \frac{\partial A^\alpha}{\partial x^i} Y^i + \frac{\partial A^\alpha}{\partial z^b} B^b + \frac{\partial A^\alpha}{\partial z_p^b} D_p B^b + \dots + \frac{\partial A^\alpha}{\partial Z_\alpha^b} D_\alpha B^b, \quad |\alpha| \leq r$$

while the fourth component of the associated map of $TB \circ A$ is

$$(45) \quad \frac{\partial B^\beta}{\partial x^i} X^i + \frac{\partial B^\beta}{\partial z^b} A^b + \frac{\partial B^\beta}{\partial z_p^b} D_p A^b + \dots + \frac{\partial B^\beta}{\partial z_\beta^b} D_\beta A^b, \quad |\beta| \leq s.$$

Hence we can summarize by

Proposition 13. *The bracket $[A, B]$ has the order $r + s$ and its associated map is $[A^0, B^0]$ and the difference (45)–(44).*

We are going to generalize Proposition 9 to connections on $\mathcal{F}(E_1, E_2)$. First of all we remark that every $A = j_x^1 \sigma \in \tilde{J}^2 \mathcal{F}(E_1, E_2)_\varphi$ defines a lifting $\lambda A: TT_x M \rightarrow TT_\varphi \mathcal{F}(E_1, E_2)$ by

$$\lambda A \left(\frac{\partial}{\partial t} \Big|_0 f \right) = \frac{\partial}{\partial t} \Big|_0 \sigma(\pi_M(f(t)))(f(t)).$$

In coordinates, if $A = (x^i, \varphi^a, \varphi_i^a, \varphi_{0i}^a, \varphi_{ij}^a)$ and $B = \frac{\partial}{\partial t} \Big|_0 f = (x^i, X^i, \dot{x}^i, \dot{X}^i)$, then one easily finds the following coordinate form of $\lambda A(B)$:

$$(46) \quad (x^i, \varphi^a, \varphi_i^a X^i, \varphi_{0i}^a \dot{x}^i, \varphi_{ij}^a X^i \dot{x}^j + \varphi_i^a \dot{X}^i).$$

This directly implies the following generalization of Lemma 3.

Lemma 5. *Let $C, D \in TT_x M$ satisfy the condition (36) for the strong difference and $A \in \bar{J}^2 \mathcal{F}(E_1, E_2)$. Then $\lambda A(C)$, $\lambda A(D)$ satisfy (42) and*

$$\Delta A(\pi_T C, T\pi C) = (\lambda A(C) \dot{-} \lambda A(D)) - \beta_1(A)(C \dot{-} D).$$

Now we need an assumption of technical character (which is fulfilled for every finite order connection).

Definition 17. *A differentiable connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$ is called strongly differentiable, if ΓX is a differentiable vector field on $\mathcal{F}(E_1, E_2)$ for every smooth vector field $X: M \rightarrow TM$.*

Proposition 14. *For every strongly differentiable connection Γ on $\mathcal{F}(E_1, E_2)$ and for all vector fields X, Y on M we have*

$$C\Gamma(X, Y) = [\Gamma X, \Gamma Y] - \Gamma([X, Y]).$$

Proof. In the same way as in Lemma 4 we deduce $\lambda \tilde{\Gamma}(TX \circ Y) = (T\Gamma X) \circ \Gamma Y$. Then we apply Lemma 5. □

7. THE ABSOLUTE DIFFERENTIATION

Let $A, B \in J^1 \mathcal{F}(E_1, E_2)_\varphi$ be two 1-jets with the same target φ . To deduce that their difference is an element $A - B \in \mathcal{F}(E_1, VE_2 \otimes T^*M)$ over φ , we consider the associated maps $\tilde{A}, \tilde{B}: J_x^1 E_1 \rightarrow J_x^1 E_2$,

$$A \equiv z_i^a = \frac{\partial \varphi^a}{\partial y^p} y_i^p + \Phi_i^p(y), \quad B \equiv z_i^a = \frac{\partial \varphi^a(x, y)}{\partial y^p} y_i^p + \Psi_i^p(y).$$

The element $A(Y) - B(Y)$ is independent of the choice of $Y \in J_x^1 E_1$, which defines a map $E_{1x} \rightarrow VE_2 \otimes T^*M$ over φ . (In this sense $J^1 \mathcal{F}(E_1, E_2)$ is an affine bundle with the derived vector bundle $\mathcal{F}(E_1, VE_2 \otimes T^*M)$ analogously to the classical case.)

Let $s: M \rightarrow \mathcal{F}(E_1, E_2)$ be a section and $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$ a connection.

Definition 18. The absolute differential

$$\nabla s: M \rightarrow \mathcal{F}(E_1, VE_2 \otimes T^*M)$$

is the above difference $\nabla s(x) = j_x^1 s - \Gamma(s(x))$.

If $X: M \rightarrow TM$ is a vector field, we define the absolute derivative of s with respect to X by

$$(47) \quad \nabla_X s = \langle \nabla s, X \rangle: M \rightarrow \mathcal{F}(E_1, VE_2)$$

where $\langle \cdot, \cdot \rangle$ is the extension of the evaluation map $T \times_M T^* \rightarrow \mathbb{R}$. Having an r -th order connection with the associated map (22) and a section s of the form $z^a = \varphi^a(x, y)$, then the coordinate form of ∇s is

$$(48) \quad \frac{\partial \varphi^a(x, y)}{\partial x^i} - \Phi_i^a(x^i, y^p, \partial_\alpha \varphi^a(x, y)).$$

To obtain $\nabla_x s$, we contract (48) with the coordinate functions $X^i(x)$ of X .

Remark 4. In the case $E_1 = E_2 := E$ we have a distinguished section $I: M \rightarrow \mathcal{F}(E, E)$, $I(x) = \text{id}_{E_x}$. Analogously to the case of a classical linear connection on TM , the absolute differential $\nabla I: M \rightarrow \mathcal{F}(E, VE \otimes T^*M)$ can be called the torsion of a connection Γ on $\mathcal{F}(E, E)$. By (48), the coordinate form of the torsion of an r -th order connection is $-\Phi_i^p(x^i, y^p, y^p, \delta_q^p, 0, \dots, 0)$.

It might be instructive to discuss a special case in more detail. Let $E \rightarrow M$ be a vector bundle. Consider the subspace $LE \subset \mathcal{F}(E, E)$ of all linear maps, which is a classical vector bundle over M . A connection Γ on LE in our sense is a classical general connection on LE . Hence our approach leads to the original idea of the torsion of a general connection Γ on LE . If w_q^p are the induced fiber coordinates on LE , the usual coordinate expression of Γ is $dw_q^p = F_{qi}^p(x^j, w_s^r) dx^i$. Then $-F_{qi}^p(x^j, \delta_s^r)$ is the coordinate form of the torsion of Γ . Of course, if we take for Γ the tensor product $\Delta \otimes \Delta^*$ of a linear connection Δ on E and of the dual connection Δ^* on E^* , [10], then the torsion of $\Delta \otimes \Delta^*$ vanishes, for I is invariant with respect to $\Delta \otimes \Delta^*$.

8. THE VECTOR BUNDLE CASE

Assume $p: E_2 \rightarrow M$ is a vector bundle. Then each fiber of $\mathcal{F}(E_1, E_2)$ is a vector space, provided the linear operations on $C^\infty(E_{1x}, E_{2x})$ are defined by extending the linear operations on E_{2x} . In other words, $\mathcal{F}(E_1, E_2) \rightarrow M$ is a vector bundle over sets, cf. [4]. Such a vector bundle structure is further extended to $J^1 \mathcal{F}(E_1, E_2)$ by

$$j_x^1 s_1 + j_x^1 s_2 = j_x^1 (\tilde{s}_1 + \tilde{s}_2), \quad j_x^1 (ks) = j_x^1 k\tilde{s}, \quad k \in \mathbb{R}$$

with addition and multiplication by reals in E_2 . Hence $J^1 \mathcal{F}(E_1, E_2) \rightarrow M$ also is a vector bundle over sets.

Definition 19. A connection $\Gamma: \mathcal{F}(E_1, E_2) \rightarrow J^1 \mathcal{F}(E_1, E_2)$ is called linear if Γ is a linear morphism over M .

In the case of an r -th order linear connection, its associated map (22) has the form

$$(49) \quad \Phi_{ib}^a(x, y)z^b + \Phi_{ib}^{aq}(x, y)z_q^b + \dots + \Phi_{ib}^{a\alpha} z_\alpha^b.$$

If E_2 is a vector bundle, then $VE_2 = E_2 \times_M E_2$, which implies

$$\mathcal{F}(E_1, VE_2 \otimes \Lambda^2 T^*M) = \mathcal{F}(E_1, E_2) \times_M \mathcal{F}(E_1, E_2 \otimes \Lambda^2 T^*M).$$

In this case, analogously to the classical situation, the curvature will be interpreted as the second component of the map from Definition 15,

$$C\Gamma: \mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2 \otimes \Lambda^2 T^*M),$$

while the first component is the identity.

Proposition 15. For every differentiable linear connection Γ , the map $C\Gamma: \mathcal{F}(E_1, E_2) \rightarrow \mathcal{F}(E_1, E_2 \otimes \Lambda^2 T^*M)$ is a linear morphism over M .

Proof. One easily verifies that in the linear case both $\tilde{\Gamma}$ and Δ in Definition 15 are linear morphisms over M . □

Quite similarly, if E_2 is a vector bundle, then the absolute derivative $\nabla_X s$ of a section s with respect to a vector field X on M is identified with the second component of (47), so that it is section of $\mathcal{F}(E_1, E_2)$ as well.

We finally remark that several other ideas from the classical theory of connections can be generalized to the case of $\mathcal{F}(E_1, E_2)$. The most interesting ones could be the vertical prolongation of Γ , the connections on $T\mathcal{F}(E_1, E_2) \subset \mathcal{F}(TE_1 \rightarrow TM, TE_2 \rightarrow TM)$ or a detailed study of the absolute differentiation in the linear case. Such a research can be based on some general ideas from the theory of classical connections collected in the book [10].

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