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Transition from decay to blow-up in a parabolic system

Pavol Quittner*

Institute of Applied Mathematics, Comenius University,
Mlynská dolina, SK-84215 Bratislava, Slovakia
Email: quittner@fmph.uniba.sk

WWW: <http://www.iam.fmph.uniba.sk/institute/quittner/quittner.html>

Abstract. We show a locally uniform bound for global nonnegative solutions of the system $u_t = \Delta u + uv - bu$, $v_t = \Delta v + au$ in $(0, +\infty) \times \Omega$, $u = v = 0$ on $(0, +\infty) \times \partial\Omega$, where $a > 0$, $b \geq 0$ and Ω is a bounded domain in \mathbb{R}^n , $n \leq 2$. In particular, the trajectories starting on the boundary of the domain of attraction of the zero solution are global and bounded.

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1 Introduction

In many parabolic problems possessing blowing-up solutions, there also exist global bounded solutions. The large-time behavior of solutions lying on the borderline between global existence and blow-up may be quite complicated and its knowledge may be useful e.g. in the study of stationary solutions of these problems (see [8]).

Let us consider first the scalar problem

$$\left. \begin{aligned} u_t &= \Delta u + u|u|^{p-1} + f(x, t, u, \nabla u), & x \in \Omega, t > 0, \\ u &= 0, & x \in \partial\Omega, t > 0, \\ u(x, 0) &= u_o(x), & x \in \Omega, \end{aligned} \right\} \quad (\text{P})$$

where Ω is a smoothly bounded domain in \mathbb{R}^n , $p > 1$ and f represents a perturbation term. If $f \equiv 0$, $0 \not\equiv U_o \geq 0$ is a smooth function, $\lambda > 0$ and $u_o = \lambda U_o$

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then the solution u_λ of (P) exists globally and $u_\lambda(t) \rightarrow 0$ as $t \rightarrow +\infty$ for λ small while u_λ blows up in finite time in the $L^\infty(\Omega)$ -norm if λ is large. If we put $\lambda_o = \sup\{\lambda; u_\lambda \text{ exists globally}\}$ and if we consider only radially decreasing solutions in a ball then it is known (see [4], [5]) that the solution u_{λ_o}

- is global and bounded for p subcritical, i.e. $p < (n + 2)/(n - 2)$ if $n > 2$,
- is global and unbounded for p critical,
- blows up in finite time for p supercritical (and $n \leq 10$).

Similarly, if $n = 1$ and $f(x, t, u, u_x) = \varepsilon(u^m)_x$, where $\varepsilon > 0$ and $m > 1$ then the solution u_{λ_o}

- is global and bounded (at least for some) $p > 2m - 1$,
- cannot be global and bounded if $p \leq 2m - 1$ and ε is “large”.

Sufficient conditions for global existence and boundedness of the solution u_{λ_o} for $f \not\equiv 0$ and a more detailed discussion of the above facts can be found in [7].

In the present note we study the system

$$\left. \begin{aligned} u_t &= \Delta u + uv - bu, & x \in \Omega, \quad t > 0, \\ v_t &= \Delta v + av, & x \in \Omega, \quad t > 0, \\ u &= v = 0, & x \in \partial\Omega, \quad t > 0, \\ u(x, 0) &= u_o(x) \geq 0, & x \in \Omega, \\ v(x, 0) &= v_o(x) \geq 0, & x \in \Omega, \end{aligned} \right\} \quad (\text{S})$$

where Ω is a smoothly bounded domain in \mathbb{R}^n , $n \leq 2$, $a > 0$ and $b \geq 0$. It was shown in [6] that the system (S) possesses a positive stationary solution. Moreover, any positive stationary solution (\tilde{u}, \tilde{v}) of (S) represents a threshold between blow-up and decay to zero provided Ω is a ball. More precisely,

- if $\lambda < \mu \leq 1$, $0 \leq u_o \leq \lambda\tilde{u}$ and $0 \leq v_o \leq \mu\tilde{v}$ then the solution of (S) exists globally and tends to zero as $t \rightarrow \infty$,
- if $\lambda, \mu > 1$, $u_o \geq \lambda\tilde{u}$ and $v_o \geq \mu\tilde{v}$ then the solution of (S) blows up in finite time.

We are interested in the behavior of all “threshold trajectories”, i.e. trajectories starting on the boundary ∂D_A of the domain of attraction of the zero solution

$$D_A = \{(u_o, v_o) \in H_0^1(\Omega)^+ \times H_0^1(\Omega)^+ ;$$

the solution (u, v) of (S) exists globally and $(u(t), v(t)) \rightarrow 0$ as $t \rightarrow \infty\}$,

where $H_0^1(\Omega)^+$ is the positive cone of the usual Sobolev space $H_0^1(\Omega)$. We shall prove the boundedness of any non-negative global trajectory of (S). Since the corresponding bound is locally uniform with respect to the initial values (u_o, v_o) , this result implies global existence and boundedness of all trajectories starting on ∂D_A .

Our proof is based on a non-trivial generalization of *a priori* estimates for stationary solutions in [6] (based on the method of Brézis and Turner [1]) to *a priori* estimates for all global solutions of (S). Such generalization sometimes may yield satisfactory results (see e.g. the optimal result in [4] for the problem (P) with $f \equiv 0$, $u_o \geq 0$ based on the method of *a priori* estimates of Gidas and Spruck); in general, it usually requires additional assumptions. This is also the case of our

proof: the *a priori* estimates in [6] were shown for a general domain $\Omega \subset \mathbb{R}^n$ if $n \leq 3$. For technical reasons, we had to restrict ourselves to the case $n \leq 2$.

Finally let us note that the boundedness of global solutions of problems of the type (P) is well known in the case where $f(x, t, u, \nabla u)$ is independent of t and ∇u (see e.g. [2], [3] and the references therein). Then the problem has variational structure, i.e. it admits a Lyapunov functional. A perturbation result for f depending on t and ∇u can be found in [7]. Anyhow, in our situation the system (S) does not seem to be “close” to any problem with variational structure.

2 Results and proofs

Throughout the rest of this paper we shall assume that the initial couple $(u_o, v_o) \in H_0^1(\Omega)^+ \times H_0^1(\Omega)^+$ is such that the corresponding solution (u, v) of (S) exists globally (in the classical sense). Moreover, we shall assume $u_o \not\equiv 0$ and we denote by λ_1 and φ_1 the first eigenvalue and the corresponding (positive) eigenfunction of the problem $-\Delta\varphi = \lambda\varphi$ in Ω , $\varphi = 0$ on $\partial\Omega$. We denote by $\|\cdot\|_p$ and $\|\cdot\|_{H^1}$ the norm in $L^p(\Omega)$ and $H^1(\Omega)$, respectively, and we put $\|\cdot\| := \|\cdot\|_2$. We shall also briefly write $u(t)$ instead of $u(\cdot, t)$ and $\int_\Omega u \, dx$ instead of $\int_\Omega u(x, t) \, dx$. Our main result is the following theorem.

Theorem 1. *There exists a constant $C_1 = C_1(\|\nabla u_o\|, \|\nabla v_o\|)$ such that*

$$\|\nabla u(t)\| + \|\nabla v(t)\| \leq C_1 \quad \text{for any } t \geq 0.$$

The proof of Theorem 1 will follow from the following series of lemmata (see Lemma 8 and Lemma 9).

Lemma 2. *There exists a constant $C_2 = C_2(\|u_o\|, \|v_o\|)$ such that*

$$\int_\Omega v(x, t)\varphi_1(x) \, dx \leq C_2 \quad \text{for any } t \geq 0.$$

Proof. Multiplying the equations in (S) by φ_1 and integrating by parts yields

$$\left(\int_\Omega u\varphi_1 \, dx\right)_t = -(\lambda_1 + b) \int_\Omega u\varphi_1 \, dx + \int_\Omega uv\varphi_1 \, dx, \tag{1}$$

$$\left(\int_\Omega v\varphi_1 \, dx\right)_t = -\lambda_1 \int_\Omega v\varphi_1 \, dx + a \int_\Omega u\varphi_1 \, dx. \tag{2}$$

Differentiating (2), using (1), (2), $au = v_t - \Delta v$ and integration by parts we get

$$\begin{aligned} \left(\int_\Omega v\varphi_1 \, dx\right)_{tt} &= -\lambda_1 \left(\int_\Omega v\varphi_1 \, dx\right)_t + a \int_\Omega (\Delta u + uv - bu)\varphi_1 \, dx \\ &= -\lambda_1 \left(\int_\Omega v\varphi_1 \, dx\right)_t - a(\lambda_1 + b) \int_\Omega u\varphi_1 \, dx + a \int_\Omega uv\varphi_1 \, dx \\ &\geq -(2\lambda_1 + b) \left(\int_\Omega v\varphi_1 \, dx\right)_t - \lambda_1(\lambda_1 + b) \int_\Omega v\varphi_1 \, dx \\ &\quad + \frac{1}{2} \left(\int_\Omega v^2\varphi_1 \, dx\right)_t + \frac{\lambda_1}{2} \int_\Omega v^2\varphi_1 \, dx, \end{aligned}$$

where in the last step we have used

$$\begin{aligned} \int_{\Omega} (-\Delta v)v\varphi_1 \, dx &= \int_{\Omega} \nabla v \cdot \nabla(v\varphi_1) \, dx \\ &= \int_{\Omega} |\nabla v|^2\varphi_1 \, dx + \frac{1}{2} \int_{\Omega} \nabla v^2 \cdot \nabla\varphi_1 \, dx \geq \frac{\lambda_1}{2} \int_{\Omega} v^2\varphi_1 \, dx. \end{aligned}$$

Hence, denoting

$$\begin{aligned} w &:= w(t) := \int_{\Omega} v(x, t)\varphi_1(x) \, dx, \\ y &:= y(t) := w'(t) + (\lambda_1 + b)w(t) - \frac{1}{2} \int_{\Omega} v^2(x, t)\varphi_1(x) \, dx, \end{aligned}$$

we obtain $y_t \geq -\lambda_1 y$ so that $y(t) \geq e^{-\lambda_1 t}y(0) \geq -c_0$ for some $c_0 > 0$. Since

$$\frac{1}{2} \int_{\Omega} v^2(x, t)\varphi_1(x) \, dx \geq c_1 \int_{\Omega} v^2(x, t)\varphi_1^2(x) \, dx \geq c_2 w^2(t) \quad \text{for some } c_1, c_2 > 0,$$

we have

$$-c_0 \leq y \leq w' + (\lambda_1 + b)w - c_2w^2 \leq w' - c_3w^2 + c_4 \quad \text{for some } c_3, c_4 > 0,$$

hence $w' \geq c_3w^2 - (c_0 + c_4)$. Since $w(t)$ exists globally, the last inequality implies $w(t) \leq \sqrt{(c_0 + c_4)/c_3}$ (where $c_0 = c_0(v_o)$ and c_3, c_4 do not depend on v).

Lemma 3. *There exists a constant $C_3 = C_3(\|u_o\|, \|v_o\|)$ such that*

$$\int_{\Omega} u(x, t)\varphi_1(x) \, dx \leq C_3 \quad \text{for any } t \geq 0. \tag{3}$$

Proof. Multiplying the first equation in (S) by φ_1 , integrating over Ω and over $(t, t + \theta)$, using $u = \frac{1}{a}(v_t - \Delta v)$ and Lemma 2 we get

$$\begin{aligned} \int_{\Omega} u\varphi_1 \, dx \Big|_t^{t+\theta} &\geq -(\lambda_1 + b) \int_t^{t+\theta} \int_{\Omega} u\varphi_1 \, dx \, dt \\ &= -\frac{\lambda_1 + b}{a} \int_{\Omega} v\varphi_1 \, dx \Big|_t^{t+\theta} - \frac{\lambda_1(\lambda_1 + b)}{a} \int_t^{t+\theta} \int_{\Omega} v\varphi_1 \, dx \, dt \geq -\tilde{c}, \end{aligned}$$

where $\tilde{c} = \tilde{c}(C_2)$ does not depend on t and $\theta \in (0, 1]$. Integrating the last inequality over $\theta \in (0, 1)$ and using $u = \frac{1}{a}(v_t - \Delta v)$ again we obtain

$$\begin{aligned} \int_{\Omega} u(x, t)\varphi_1(x) \, dx - \tilde{c} &\leq \int_t^{t+1} \int_{\Omega} u\varphi_1 \, dx \, dt \\ &= \frac{1}{a} \int_{\Omega} v\varphi_1 \, dx \Big|_t^{t+1} + \frac{\lambda_1}{a} \int_t^{t+1} \int_{\Omega} v\varphi_1 \, dx \, dt \leq C_2 \frac{\lambda_1 + 1}{a}, \end{aligned}$$

which concludes the proof.

In what follows we shall exploit the following well known result (used also in [1] and [6]).

Lemma 4. *Let $\Omega \subset \mathbb{R}^n$ be a smoothly bounded domain. For any $u \in H_0^1(\Omega)$, we have*

$$\left\| \frac{u}{\delta^r} \right\|_p \leq C_4 \|\nabla u\|, \tag{4}$$

where $\delta = \delta(x) = \text{dist}(x, \partial\Omega)$, $r \in [0, 1]$ and $p \leq \frac{2n}{n-2(1-r)}$ ($=\frac{2}{r}$ if $n = 2$).

Since $\delta(x) \leq C_\varphi \varphi_1(x)$ for some $C_\varphi > 0$, it is now easy to show the next three lemmata.

Lemma 5. *There exists a constant $C_5 = C_5(\|u_o\|, \|v_o\|)$ such that*

$$\frac{1}{2} \frac{d}{dt} \|u\|^2 + \|\nabla u\|^2 + b\|u\|^2 = \int_\Omega u^2 v \, dx \leq C_5 \|\nabla u\|^{4/3} \|\nabla v\|. \tag{5}$$

Proof. The equality in (5) can be obtained by multiplying the first equation in (S) by u and integrating over Ω . Now the Hölder inequality, Lemmata 3, 4 and any choice of $\alpha, \alpha' > 1$ with $\frac{1}{\alpha} + \frac{1}{\alpha'} = 1$ imply

$$\begin{aligned} \int_\Omega u^2 v \, dx &\leq \left(\int_\Omega u \delta \, dx \right)^{2/3} \left(\int_\Omega u^4 v^3 \delta^{-2} \, dx \right)^{1/3} \\ &\leq (C_\varphi C_3)^{2/3} \left(\int_\Omega \left(\frac{u}{\delta^{1/(2\alpha)}} \right)^{4\alpha} \, dx \right)^{1/(3\alpha)} \left(\int_\Omega \left(\frac{v}{\delta^{2/(3\alpha')}} \right)^{3\alpha'} \, dx \right)^{1/(3\alpha')} \\ &\leq (C_\varphi C_3)^{2/3} C_4^{7/3} \|\nabla u\|^{4/3} \|\nabla v\|. \end{aligned}$$

Lemma 6. *There exists a constant $C_6 = C_6(\|u_o\|, \|v_o\|)$ such that*

$$\frac{1}{2} \frac{d}{dt} \|v\|^2 + \|\nabla v\|^2 = a \int_\Omega uv \, dx \leq C_6 \|\nabla u\|^{1/2} \|\nabla v\|. \tag{6}$$

Proof. The equality in (6) follows from the second equation in (S). Now, similarly as in the proof of Lemma 5 we obtain

$$\begin{aligned} \int_\Omega uv \, dx &\leq \left(\int_\Omega u \delta \, dx \right)^{1/2} \left(\int_\Omega uv^2 \delta^{-1} \, dx \right)^{1/2} \\ &\leq (C_\varphi C_3)^{1/2} \left(\int_\Omega \left(\frac{u}{\delta} \right)^2 \, dx \right)^{1/4} \left(\int_\Omega v^4 \, dx \right)^{1/4} \leq C_6 \|\nabla u\|^{1/2} \|\nabla v\|, \end{aligned}$$

since $H^1(\Omega)$ is imbedded in $L^p(\Omega)$ for any $p \geq 1$.

Lemma 7. *There exists a constant $C_7 = C_7(\|u_o\|, \|v_o\|)$ and for any $\varepsilon > 0$ there exists a constant $C_\varepsilon > 0$ such that*

$$\begin{aligned} \|u\| &\leq C_7 \|\nabla u\|^{2/3}, & \|v\| &\leq C_7 \|\nabla v\|^{2/3}, \\ \|uv\| &\leq C_\varepsilon (\|\nabla u\|^{2/3+\varepsilon} + 1) \|\nabla v\|. \end{aligned} \tag{7}$$

Proof. Denoting $w := u$ or $w := v$ and $C_{23} := \max(C_2, C_3)$ we get

$$\int_{\Omega} w^2 dx \leq \left(\int_{\Omega} w \delta dx \right)^{2/3} \left(\int_{\Omega} \left(\frac{w}{\delta^{1/2}} \right)^4 dx \right)^{1/3} \leq (C_{\varphi} C_{23})^{2/3} C_4^{4/3} \|\nabla w\|^{4/3}.$$

Putting $K_{\varepsilon} = \frac{2(2+\varepsilon)}{\varepsilon}$ and using $\|w\|_p \leq c_p \|\nabla w\|$ for any $p \geq 1$ we obtain

$$\begin{aligned} \int_{\Omega} u^2 v^2 dx &\leq \left(\int_{\Omega} u^{2+\varepsilon} dx \right)^{2/(2+\varepsilon)} \left(\int_{\Omega} v^{K_{\varepsilon}} dx \right)^{2/K_{\varepsilon}} \\ &\leq c_{K_{\varepsilon}}^2 \|\nabla v\|^2 \left(\int_{\Omega} u^2 dx \right)^{(2-\varepsilon)/(2+\varepsilon)} \left(\int_{\Omega} u^4 dx \right)^{\varepsilon/(2+\varepsilon)} \\ &\leq c_{K_{\varepsilon}}^2 c_4^{4\varepsilon/(2+\varepsilon)} C_7^{2(2-\varepsilon)/(2+\varepsilon)} \|\nabla v\|^2 \|\nabla u\|^{4/3+\varepsilon'}, \end{aligned}$$

where $\varepsilon' < 2\varepsilon$.

Lemma 8. *There exists a constant $C_8 = C_8(\|\nabla v_o\|, \|\nabla u_o\|)$ such that*

$$\|\nabla v(t)\| \leq C_8 \max_{0 \leq \tau \leq t} \|\nabla u(\tau)\|^{1/2} \quad \text{for any } t \geq 0. \quad (8)$$

Proof. If $\frac{d}{dt} \|v(t)\|^2 \geq -\|\nabla v(t)\|^2$ then (6) implies

$$\|\nabla v(t)\| \leq 2C_6 \|\nabla u(t)\|^{1/2} \quad (9)$$

and we are done. Hence, let $\frac{d}{dt} \|v(t)\|^2 < -\|\nabla v(t)\|^2$. Then

$$\|\nabla v(t)\|^2 < -\frac{d}{dt} \|v\|^2 \leq 2\|v\| \cdot \|v_t\| \leq 2C_7 \|\nabla v\|^{2/3} \cdot \|v_t\|,$$

so that

$$\|\nabla v\|^{4/3} \leq 2C_7 \|v_t\|. \quad (10)$$

Multiplying the second equation in (S) by v_t and integrating over Ω we get

$$\|v_t\|^2 + \frac{1}{2} \frac{d}{dt} \|\nabla v\|^2 = a \int_{\Omega} u v_t dx \leq \frac{1}{2} \|v_t\|^2 + \frac{a^2}{2} \|u\|^2,$$

which together with (7) yields

$$\|v_t\|^2 + \frac{d}{dt} \|\nabla v\|^2 \leq a^2 \|u\|^2 \leq (aC_7)^2 \|\nabla u\|^{4/3}. \quad (11)$$

Now (10) and (11) imply

$$\frac{1}{(2C_7)^2} \|\nabla v\|^{8/3} + \frac{d}{dt} \|\nabla v\|^2 \leq (aC_7)^2 \|\nabla u\|^{4/3}. \quad (12)$$

If $\|\nabla v\| \leq (2aC_7^2)^{3/4}\|\nabla u\|^{1/2}$ then we are done. Otherwise the inequality (12) implies $\frac{d}{dt}\|\nabla v\|^2 < 0$ and putting

$$t_1 := \inf\{\tau > 0; \frac{d}{dt}\|\nabla v\|^2 < 0 \text{ on } (\tau, t]\}$$

we have $\|\nabla v(t)\| < \|\nabla v(t_1)\|$.

If $t_1 = 0$ then $\|\nabla v(t)\| < \|\nabla v(0)\| \leq C_0\|\nabla u(0)\|^{1/2}$ for some $C_0 > 0$. Hence, we may assume $t_1 > 0$.

If $\frac{d}{dt}\|v(t_1)\|^2 \geq -\|\nabla v(t_1)\|^2$ then the inequality (9) (with t replaced by t_1) implies

$$\|\nabla v(t)\| < \|\nabla v(t_1)\| \leq 2C_6\|\nabla u(t_1)\|^{1/2}.$$

If $\frac{d}{dt}\|v(t_1)\|^2 < -\|\nabla v(t_1)\|^2$ then the inequality (12) (with t replaced by t_1) implies

$$\|\nabla v(t)\| < \|\nabla v(t_1)\| \leq (2aC_7^2)^{3/4}\|\nabla u(t_1)\|^{1/2},$$

since the definition of t_1 implies $\frac{d}{dt}\|\nabla v(t_1)\|^2 = 0$ if $t_1 > 0$.

Lemma 9. *There exists a constant $C_9 = C_9(\|\nabla u_o\|, \|\nabla v_o\|)$ such that*

$$\|\nabla u(t)\| \leq C_9 \quad \text{for any } t \geq 0.$$

Proof. We may suppose $\|\nabla u(0)\| < \sup_{t \geq 0} \|\nabla u(t)\|$ (otherwise we are done). Let $t_o > 0$ be such that

$$\|\nabla u(t_o)\| = \max_{0 \leq t \leq t_o} \|\nabla u(t)\|. \tag{13}$$

If $\frac{d}{dt}\|u(t_o)\|^2 \geq -\|\nabla u(t_o)\|^2$ then (5), Lemma 8 and (13) imply

$$\|\nabla u(t_o)\|^2 \leq 2C_5\|\nabla u(t_o)\|^{4/3}\|\nabla v(t_o)\| \leq 2C_5C_8\|\nabla u(t_o)\|^{11/6},$$

hence

$$\|\nabla u(t_o)\| \leq (2C_5C_8)^6.$$

Consequently, we may assume

$$\frac{d}{dt}\|u(t_o)\|^2 < -\|\nabla u(t_o)\|^2.$$

This implies

$$\|\nabla u(t_o)\|^2 < -\frac{d}{dt}\|u\|^2 \leq 2\|u\| \cdot \|u_t\| \leq 2C_7\|\nabla u\|^{2/3}\|u_t\|,$$

so that

$$\|\nabla u(t_o)\|^{4/3} \leq 2C_7\|u_t(t_o)\|. \tag{14}$$

Multiplying the first equation in (S) by u_t and integrating over Ω we obtain

$$\begin{aligned} \|u_t(t_o)\|^2 &\leq \|u_t\|^2 + \frac{1}{2} \frac{d}{dt} \|\nabla u\|^2 = -b \int_{\Omega} uu_t \, dx + \int_{\Omega} uvu_t \, dx \\ &\leq \frac{1}{2} \|u_t\|^2 + \|uv\|^2 + b^2 \|u\|^2, \end{aligned}$$

where the inequality $\frac{d}{dt} \|\nabla u(t_o)\|^2 \geq 0$ follows from (13). Now the last inequality together with (14) and Lemmata 7, 8 imply

$$\begin{aligned} \frac{1}{(2C_7)^2} \|\nabla u(t_o)\|^{8/3} &\leq \|u_t(t_o)\|^2 \leq 2\|uv(t_o)\|^2 + 2b^2 \|u(t_o)\|^2 \\ &\leq \tilde{C}_{\varepsilon} (\|\nabla u(t_o)\|^{4/3+2\varepsilon} + 1) (\|\nabla v(t_o)\|^2 + 1) \\ &\leq \tilde{C}'_{\varepsilon} (\|\nabla u(t_o)\|^{7/3+2\varepsilon} + 1), \end{aligned}$$

so that the choice $\varepsilon < 1/6$ yields the desired estimate for $\|\nabla u(t_o)\|$.

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