

# Archivum Mathematicum

---

Josef Janyška

A remark on linear functions on the sphere

*Archivum Mathematicum*, Vol. 17 (1981), No. 3, 141--149

Persistent URL: <http://dml.cz/dmlcz/107104>

## Terms of use:

© Masaryk University, 1981

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>

## A REMARK ON LINEAR FUNCTIONS ON THE SPHERE

JOSEF JANYŠKA, Brno

(Received July 15, 1980)

1. Let  $S^n$  be a unit sphere in  $E^{n+1}$ . Let  $D$  be a domain in  $S^n$ . A function  $f : D \rightarrow R$  of class  $C^\infty$  is called linear if

$$(1) \quad f(M) = \langle m, a \rangle + k,$$

where  $a$  is a constant vector,  $m$  is the position vector of the point  $M \in S^n$  with respect to the centre of  $S^n$ ,  $k \in R$ . The linear function  $f$  is called homogeneous or non-homogeneous if  $k = 0$  or  $k \neq 0$ , respectively.

For the case  $S^2$ , A. Švec [2] found certain conditions for a function  $f$  to be a linear and homogeneous. These conditions are expressed in terms of partial differential equations on some domain  $D$  and on the boundary  $\partial D$  of  $D$ . These results are extended in [1] on the wider class of non-homogeneous linear functions.

The aim of this paper is to prove some assertions for the case of non-homogeneous linear functions on  $S^3$ .

2. Let us introduce some notations (see [4]). Consider the unit sphere  $S^3 \subset E^4$ . To each point  $M$  of  $S^3$ , let us associate a tangent orthonormal frame  $\{m, v_1, v_2, v_3, v_4\}$  such that  $m$  is the position vector of  $M \in S^3$ ,  $v_1, v_2, v_3 \in T_M S^3$  and  $v_4 \in N_M S^3$ . Then we have

$$\begin{aligned} dm &= \omega^i v_i, & dv_j &= \omega_j^i v_i + \omega^i v_4, \\ dv_4 &= -\omega^i v_i = -dm, & \omega_j^i &= -\omega_i^j, \quad (i, j = 1, 2, 3), \end{aligned}$$

with the usual integrability conditions.

Let  $f : S^3 \rightarrow R$  be a differentiable function. The covariant derivatives of  $f$  with respect to a field of tangent orthonormal frames  $\{m, v_k\}$  ( $k = 1, 2, 3, 4$ ) are defined by the following formulas

$$(2) \quad df = f_1 \omega^1 + f_2 \omega^2 + f_3 \omega^3,$$

$$(3) \quad df_1 - f_2 \omega_1^2 - f_3 \omega_1^3 = f_{11} \omega^1 + f_{12} \omega^2 + f_{13} \omega^3,$$

$$df_2 + f_1 \omega_1^2 - f_3 \omega_2^3 = f_{12} \omega^1 + f_{22} \omega^2 + f_{23} \omega^3,$$

$$df_3 + f_1 \omega_1^3 + f_2 \omega_2^3 = f_{13} \omega^1 + f_{23} \omega^2 + f_{33} \omega^3,$$

- (4)  $\begin{aligned} df_{11} - 2f_{12}\omega_1^2 - 2f_{13}\omega_1^3 &= A\omega^1 + B\omega^2 + C\omega^3, \\ df_{12} + (f_{11} - f_{22})\omega_1^2 - f_{23}\omega_1^3 - f_{13}\omega_2^3 &= (B + f_2)\omega^1 + (D + f_1)\omega^2 + E\omega^3, \\ df_{13} - f_{23}\omega_1^2 + (f_{11} - f_{33})\omega_1^3 + f_{12}\omega_2^3 &= (C + f_3)\omega^1 + E\omega^2 + (F + f_1)\omega^3, \\ df_{22} + 2f_{12}\omega_1^2 - 2f_{23}\omega_2^3 &= D\omega^1 + G\omega^2 + H\omega^3, \\ df_{23} + f_{13}\omega_1^2 + f_{12}\omega_3^3 + (f_{22} - f_{33})\omega_2^3 &= E\omega^1 + (H + f_3)\omega^2 + (I + f_2)\omega^3, \\ df_{33} + 2f_{13}\omega_1^3 + 2f_{23}\omega_2^3 &= F\omega^1 + I\omega^2 + J\omega^3, \end{aligned}$
- (5)  $\begin{aligned} dA - (3B + 2f_2)\omega_1^2 - (3C + 2f_3)\omega_1^3 &= T_1\omega^1 + T_2\omega^2 + T_3\omega^3, \\ dB + (A - 2D - 2f_1)\omega_1^2 - 2E\omega_1^3 - C\omega_2^3 &= (T_2 + 2f_{12})\omega^1 + T_4\omega^2 + T_5\omega^3, \\ dC - 2E\omega_1^2 + (A - 2F - 2f_1)\omega_1^3 + B\omega_2^3 &= (T_3 + 2f_{13})\omega^1 + T_5\omega^2 + T_6\omega^3, \\ dD + (2B - G + 2f_2)\omega_1^2 - H\omega_1^3 - 2E\omega_2^3 &= (T_4 - 2f_{11} + 2f_{22})\omega^1 + \\ &\quad + (T_7 + 2f_{12})\omega^2 + T_8\omega^3, \\ dE + (C - H)\omega_1^2 + (B - I)\omega_1^3 + (D - F)\omega_2^3 &= (T_5 + 2f_{23})\omega^1 + \\ &\quad + (T_8 + 2f_{13})\omega^2 + (T_9 + 2f_{12})\omega^3, \\ dF - I\omega_1^2 + (2C - J + 2f_3)\omega_1^3 + 2E\omega_2^3 &= (T_6 - 2f_{11} + f_{22} + f_{33})\omega^1 + \\ &\quad + T_9\omega^2 + (T_{10} + 2f_{13})\omega^3, \\ dG + (3D + 2f_1)\omega_1^2 - (3H + 2f_3)\omega_2^3 &= T_7\omega^1 + T_{11}\omega^2 + T_{12}\omega^3, \\ dH + 2E\omega_1^2 + D\omega_1^3 + (G - 2I - 2f_2)\omega_2^3 &= T_8\omega^1 + \\ &\quad + (T_{12} + f_{23})\omega^2 + T_{13}\omega^3, \\ dI + F\omega_1^2 + 2E\omega_1^3 + (2H - J + 2f_3)\omega_2^3 &= T_9\omega^1 + \\ &\quad + (T_{13} - 2f_{22} + 2f_{33})\omega^2 + (T_{14} + 2f_{23})\omega^3, \\ dJ + (3F + 2f_1)\omega_1^2 + (3I + 2f_2)\omega_2^3 &= T_{10}\omega^1 + T_{14}\omega^2 + T_{15}\omega^3. \end{aligned}$

By means of these covariant derivatives, one can introduce the following differential operators  $\Delta$ ,  $\mathcal{L}$ ,  $\mathcal{K}$  and  $\mathcal{M}$ .

$$\Delta f = \sum_{i=1}^3 f_{ii},$$

$$\mathcal{L}f = \Delta f + 3f,$$

$$\mathcal{K}f = \sum_{\substack{i,j=1 \\ i < j}}^3 (f_{ii}f_{jj} - f_{ij}^2) + 2f \Delta f + 3f^2,$$

$$\mathcal{M}f = \det(f_{ij}) + f \sum_{\substack{i,j=1 \\ i < j}}^3 (f_{ii}f_{jj} - f_{ij}^2) + f^2 \sum_{i=1}^3 f_{ii} + f^3.$$

Now, let  $\{m, v_k^*\}$  ( $k = 1, 2, 3, 4$ ) be another field of tangent frames. That means there exists an orthonormal matrix  $(a_i^j)$  such that

$$v_j^* = a_j^i v_i, \quad v_4^* = v_4, \quad i, j = 1, 2, 3.$$

Let  $(\alpha_i^j)$  be the inverse matrix, i.e.  $\alpha_i^l \alpha_k^l = \delta_k^j$ . Then we have the following relations

$$\begin{aligned}\omega^i &= \alpha_i^l \omega^{j*}, & \omega^{j*} &= \alpha_j^l \omega^i, \\ f_i &= \alpha_i^l f_j^*, & f_j^* &= \alpha_j^l f_i, \\ \omega_1^{2*} &= \alpha_3^3 \omega_1^2 - \alpha_3^2 \omega_1^3 + \alpha_3^1 \omega_2^3, \\ \omega_1^{3*} &= -\alpha_2^3 \omega_1^2 + \alpha_2^2 \omega_1^3 - \alpha_2^1 \omega_2^3, \\ \omega_2^{3*} &= \alpha_1^3 \omega_2^2 - \alpha_1^2 \omega_2^3 + \alpha_1^1 \omega_1^3, \\ f_{ij}^* &= \alpha_i^k f_{kl} \alpha_l^j, & f_{kl} &= \alpha_k^l f_{ij}^* \alpha_l^j.\end{aligned}$$

**Remark.** It is easy to see that the functions  $\mathcal{L}f$ ,  $\mathcal{K}f$  and  $\mathcal{M}f$  satisfy  $\mathcal{L}f^* = \mathcal{L}f$ ,  $\mathcal{K}f^* = \mathcal{K}f$ ,  $\mathcal{M}f^* = \mathcal{M}f$ , i.e. are invariant with respect to the choice of the field of tangent frames.

3. Now, let us consider the function

$$\mathcal{G}(f) = (\mathcal{L}f)^2 - 3\mathcal{K}f = \frac{1}{2} \sum_{\substack{i,j=1 \\ i < j}}^3 \{(f_{ii} - f_{jj})^2 + 3f_{ij}^2\}.$$

It is invariant with respect to the choice of the field of tangent frames. For  $\mathcal{G}(f)$  the following lemma is fulfilled

**Lemma 1.** If  $\mathcal{G}(f) = (\mathcal{L}f)^2 - 3\mathcal{K}f = 0$  on some domain  $D \subset S^3$ , then  $f$  is linear on  $D$ .

**Proof:** The supposition  $\mathcal{G}(f) = 1/2 \sum_{\substack{i,j=1 \\ i < j}}^3 \{(f_{ii} - f_{jj})^2 + 3f_{ij}^2\} = 0$  implies  $f_{ii} = f_{jj}$ ,  $f_{ij} = 0$ , ( $i < j$ ,  $i, j = 1, 2, 3$ ). From (4), we get  $A = D = F = -f_1$ ,  $B = G = I = -f_2$ ,  $C = H = J = -f_3$ ,  $E = 0$  and from this  $df_{ii} = -df$ . This implies  $f_{ii} = -f + c$ , where  $c \in R$ . Now, let us consider the vector field

$$a = -\sum_{i=1}^3 f_i v_i + (f - c) v_4.$$

Then  $da = 0$  and hence  $a$  is a constant vector. Then

$$f = \langle a, v_4 \rangle + c, \quad \text{QED.}$$

In the following propositions we shall use the maximum principle in the form described in [3].

**Proposition 1.** Let  $D \subset S^3$  be a domain,  $\partial D$  its boundary. Let  $f: S^3 \rightarrow R$  be a differentiable function. If

- (i)  $\mathcal{G}(f) = (\mathcal{L}f)^2 - 3\mathcal{K}f = 0$  on  $\partial D$ ,
  - (ii)  $\mathcal{L}f = \text{const.}$  on  $D$ ,
- then  $f$  is linear on  $D$ .

**Proposition 2.** Let  $D \subset S^3$  be a domain,  $\partial D$  its boundary. Let  $f : S^3 \rightarrow \mathbb{R}$  be a differentiable function. If

$$(i) \mathcal{G}(f) = (\mathcal{L}f)^2 - 3\mathcal{K}f = 0 \text{ on } \partial D,$$

$$(ii) 2\mathcal{L}f \Delta \mathcal{L}f \geq 3\Delta \mathcal{K}f \text{ on } D,$$

then  $f$  is linear on  $D$ .

**Proof:** First of all we must calculate the covariant derivatives of the functions  $\mathcal{L}f$ ,  $\mathcal{K}f$  and  $\mathcal{G}(f)$ .

$$(6) \quad (\mathcal{L}f)_1 = A + D + F + 3f_1,$$

$$(\mathcal{L}f)_2 = B + G + I + 3f_2,$$

$$(\mathcal{L}f)_3 = C + H + J + 3f_3,$$

$$(7) \quad (\mathcal{L}f)_{11} = T_1 + T_4 + T_6 - f_{11} + 3f_{22} + f_{33},$$

$$(\mathcal{L}f)_{22} = T_4 + T_{11} + T_{13} + 2f_{33} + f_{22},$$

$$(\mathcal{L}f)_{33} = T_6 + T_{13} + T_{15} + 3f_{33},$$

$$(8) \quad (\mathcal{K}f)_1 = (f_{22} + f_{33} + 2f)A + (f_{11} + f_{33} + 2f)D + \\ + (f_{11} + f_{22} + 2f)F + 2f_1 \mathcal{L}f - 2f_{12}(B + f_2) - \\ - 2f_{13}(C + f_3) - 2f_{23}E,$$

$$(\mathcal{K}f)_2 = (f_{22} + f_{33} + 2f)B + (f_{11} + f_{33} + 2f)G + \\ + (f_{11} + f_{22} + 2f)I + 2f_2 \mathcal{L}f - 2f_{12}(D + f_1) - \\ - 2f_{13}E - 2f_{23}(H + f_3),$$

$$(\mathcal{K}f)_3 = (f_{22} + f_{33} + 2f)C + (f_{11} + f_{33} + 2f)H + \\ + (f_{11} + f_{22} + 2f)J + 2f_3 \mathcal{L}f - 2f_{12}(E + f_1) - \\ - 2f_{13}(F + f_2) - 2f_{23}(I + f_3),$$

$$(9) \quad (\mathcal{K}f)_{11} = 2\{(A + f_1)(D + f_1) + (A + f_1)(F + f_1) - (B + f_2)^2 + \\ + (D + f_1)(F + f_1) - (C + f_3)^2 - E^2\} + 2f_{11} \mathcal{L}f + \\ + (f_{22} + f_{33} + 2f)T_1 + (f_{11} + f_{33} + 2f)(T_4 - 2f_{11} + 2f_{22}) + \\ + (f_{11} + f_{22} + 2f)(T_6 - 2f_{11} + f_{22} + f_{33}) - \\ - 2f_{12}(T_2 + 3f_{12}) - 2f_{13}(T_3 + 3f_{13}) - 2f_{23}(T_5 + 2f_{23}),$$

$$(\mathcal{K}f)_{22} = 2\{(B + f_2)(G + f_2) + (B + f_2)(I + f_2) - (D + f_1)^2 + \\ + (G + f_2)(I + f_2) - E^2 - (H + f_3)^2\} + 2f_{22} \mathcal{L}f + \\ + (f_{22} + f_{33} + 2f)T_4 + (f_{11} + f_{33} + 2f)T_{11} + \\ + (f_{11} + f_{22} + 2f)(T_{13} - 2f_{22} + 2f_{33}) - \\ - 2f_{12}(T_7 + 3f_{12}) - 2f_{13}(T_8 + 2f_{13}) - 2f_{23}(T_{12} + 3f_{23}),$$

$$(\mathcal{K}f)_{33} = 2\{(C + f_3)(H + f_3) + (C + f_3)(J + f_3) - 2E^2 + \\ + (H + f_3)(J + f_3) - 2(F + f_1)^2 - 2(I + f_2)^2\} +$$

$$(13) \quad \Delta g(f) = 2 \sum_{i=1}^3 (g_i f_i)^2 + 2g_1 g_2 g_3 - 3A g f$$

From (6), (7), (9) and (11), we get

$$(12) \quad \Delta g(f) - 3g(f) = 3(f_{11} - f_{22})^2 + 9f_{12}^2 + 9f_{13}^2 + 9f_{23}^2 + \\ + 3(A + f_1)^2 + 9(B + f_2)^2 + 9(C + f_3)^2 + 9(G + f_4)^2 + 3(H + f_5)^2 + \\ + 9(D + f_6)^2 + 18E^2 + 9(F + f_7)^2 + 3(G + f_8)^2 + 3(H + f_9)^2 +$$

From assumption (ii) of Proposition 1, (6), (7), we have

$$\begin{aligned} & - (T_6 + T_{13} + T_{15}) g f \\ & + 6f_{12}(T_3 + 2f_{12}) + 6f_{13}(T_{10} + 3f_{13}) + 6f_{23}(T_{14} + 3f_{23}) - \\ & + 3(f_{11} + f) T_6 + 3(f_{22} + f) T_{13} + 3(f_{33} + f) T_{15} + \\ & + 6(F + f_1)^2 + 6(I + f_2)^2 - (C + H + f + f_3)^2 + \\ & + 6(E + f_4)^2 + 6(H + f_5)^2 + 6(G + f_6)^2 + 6E^2 + \\ & g_{33}(f) = 3(C + f_3)^2 + 3(H + f_3)^2 + 3(I + f_3)^2 + 6E^2 + \\ & - (T_4 + T_{11} + T_{13} - 2f_{22} + 2f_{33}) g f \\ & + 6f_{12}(T_7 + 3f_{12}) + 6f_{13}(T_8 + 2f_{13}) + 6f_{23}(T_{12} + 3f_{23}) - \\ & + 3(f_{11} + f) T_4 + 3(f_{22} + f) T_{11} + 3(f_{33} + f) (T_{13} - 2f_{22} + 2f_{33}) + \\ & + 6E^2 + 6(H + f_5)^2 - (B + G + I + 3f_2)^2 + \\ & g_{22}(f) = 3(B + f_2)^2 + 3(G + f_2)^2 + 3(I + f_2)^2 + 6(D + f_1)^2 + \\ & - (T_1 + T_4 + T_6 - 4f_{11} + 3f_{22} + f_{33}) g f \\ & + 6f_{12}(T_2 + 3f_{12}) + 6f_{13}(T_3 + 3f_{13}) + 6f_{23}(T_5 + 2f_{23}) - \\ & + 3(f_{33} + f) (T_6 - 2f_{11} + f_{22} + f_{33}) + \\ & + 3(f_{11} + f) T_1 + 3(f_{22} + f) (T_4 - 2f_{11} + 2f_{22}) + \\ & + 6(C + f_3)^2 + 6E^2 - (A + D + F + 3f_1)^2 + \\ & g_{11}(f) = 3(A + f_1)^2 + 3(D + f_1)^2 + 3(F + f_1)^2 + 6(B + f_2)^2 + \\ & + 6f_{12}E + 6f_{13}(F + f_1) + 6f_{23}(I + f_2) - (C + H + f) g f \\ & g_3(f) = 3(f_{11} + f) C + 3(f_{22} + f) H + 3(f_{33} + f) I + \\ & + 6f_{12}(D + f_1) + 6f_{13}(H + f_3) - (B + G + I) g f \\ & g_{21}(f) = 3(f_{11} + f) B + 3(f_{22} + f) G + 3(f_{33} + f) I + \\ & + 6f_{12}(B + f_2) + 6f_{13}(C + f_3) + 6f_{23}E - (A + D + F) g f \\ & g_1(f) = 3(f_{11} + f) A + 3(f_{22} + f) D + 3(f_{33} + f) F + \\ & - 2f_{13}(T_{10} + 3f_{13}) - 2f_{23}(T_{14} + 3f_{23}) - \\ & + (f_{11} + f_{22} + 2f) T_{15} - 2f_{12}(T_6 + 2f_{12}) - \\ & + 2f_{33} g f + (f_{22} + f_3 + 2f) T_6 + (f_{11} + f_3 + 2f) T_{13} + \end{aligned}$$

These equations (12) and (13) satisfy the conditions of the maximum principle if the assumptions of Propositions 1 and 2 hold, respectively. This proves our propositions because of Lemma 1, QED.

**Consequence.** Replacing (ii) in Proposition 2 by

$$(ii)' \quad \mathcal{K}f = \text{const. on } D,$$

$$(iii)' \quad \mathcal{L}f \Delta \mathcal{L}f \geq 0 \text{ on } D,$$

then  $f$  is linear on  $D$ .

4. Now, let us consider a new function

$$\mathcal{G}(f) = (\mathcal{K}f)^2 - 3\mathcal{L}f \mathcal{M}f.$$

It is easy to prove the following

**Lemma 2.** Let  $f: S^3 \rightarrow \mathbb{R}$  be a differentiable function satisfying  $f_{ij} = 0$  ( $i \neq j$ ) on some domain  $\bar{D} \subset S^3$  and  $\mathcal{G}'(f) = (\mathcal{K}f)^2 - 3\mathcal{L}f \mathcal{M}f = 0$  on  $\bar{D}$ , then  $f$  is linear on  $\bar{D}$ .

**Proof:** From the assumption  $f_{ij} = 0$  ( $i \neq j$ ) and  $\mathcal{G}'(f) = 0$ , we obtain either  $f_{ii} = -f$  or  $f_{ii} = f_{jj}$ . Now, our assertion follows from Lemma 1, QED.

**Proposition 3.** Let  $D \subset S^3$  be a domain,  $\partial D$  its boundary. Let  $f: S^3 \rightarrow \mathbb{R}$  be a differentiable function satisfying  $f_{ij} = 0$  ( $i \neq j$ ) on  $\bar{D} = D \cup \partial D$ . If

$$(i) \quad \mathcal{G}'(f) = 0 \text{ on } \partial D,$$

$$(ii) \quad 2\mathcal{K}f \Delta \mathcal{K}f \geq 3\mathcal{L}f \Delta \mathcal{M}f + 3\mathcal{M}f \Delta \mathcal{L}f + 6 \sum_{i=1}^3 (\mathcal{L}f)_i \cdot (\mathcal{M}f)_i,$$

then  $f$  is linear on  $\bar{D}$ .

**Proof:** From  $f_{ij} = 0$ , we obtain

$$(14) \quad (\mathcal{M}f)_1 = (f_{22} + f)(f_{33} + f)(A + f_1) + (f_{11} + f)(f_{33} + f)(D + f_1) + (f_{11} + f)(f_{22} + f)(F + f_1),$$

$$(\mathcal{M}f)_2 = (f_{22} + f)(f_{33} + f)(B + f_2) + (f_{11} + f)(f_{33} + f)(G + f_2) + (f_{11} + f)(f_{22} + f)(I + f_2),$$

$$(\mathcal{M}f)_3 = (f_{22} + f)(f_{33} + f)((C + f_3) + (f_{11} + f)(f_{33} + f)(H + f_3) + (f_{11} + f)(f_{22} + f)(J + f_3)),$$

$$(15) \quad (\mathcal{M}f)_{11} = 2\{(f_{11} + f)(D + f_1)(F + f_1) + (f_{22} + f)(A + f_1)(F + f_1) + (f_{33} + f)(A + f_1)(D + f_1)\} + (f_{22} + f)(f_{33} + f)(T_1 + f_{11}) + (f_{11} + f)(f_{33} + f)(T_4 - f_{11} + 2f_{22}) + (f_{11} + f)(f_{22} + f)(T_6 - f_{11} + f_{22} + f_{33}),$$

$$(\mathcal{M}f)_{22} = 2\{(f_{11} + f)(G + f_2)(I + f_2) + (f_{22} + f)(B + f_2)(I + f_2) + (f_{33} + f)(B + f_2)(G + f_2)\} + (f_{22} + f)(f_{33} + f)(T_4 + f_{22}) +$$



$$\begin{aligned}
& + (f_{33} + f)^2 (f_{11} - f_{22}) \} (T_1 + f_{11}) + \\
& + \{(f_{22} + f) (f_{11} - f_{33})^2 + (f_{11} + f)^2 (f_{22} - f_{33}) - \\
& + (f_{33} + f)^2 (f_{11} - f_{22}) \} (T_4 - f_{11} + 2f_{22}) + \\
& + \{(f_{33} + f) (f_{11} - f_{22})^2 - (f_{22} + f)^2 (f_{11} - f_{33}) - \\
& - (f_{11} + f)^2 (f_{22} - f_{33}) \} (T_6 - f_{11} + f_{22} + f_{33}),
\end{aligned}$$

$$\begin{aligned}
g'_{22}(f) = & (B + f_2)^2 \{(f_{22} - f_{33})^2 + (f_{22} + f)^2 + (f_{33} + f)^2\} + \\
& + (G + f_2)^2 \{(f_{11} - f_{33})^2 + (f_{11} + f)^2 + (f_{33} + f)^2\} + \\
& + (I + f_2)^2 \{(f_{11} - f_{22})^2 + (f_{11} + f)^2 + (f_{22} + f)^2\} + \\
& + 2(B + f_2)(G + f_2) \{2(f_{11} + f) (f_{22} - f_{33}) + \\
& + 2(f_{22} + f) (f_{11} - f_{33}) - (f_{33} + f)^2\} + \\
& + 2(B + f_2)(I + f_2) \{2(f_{33} + f) (f_{11} - f_{22}) - \\
& - 2(f_{11} + f) (f_{22} - f_{33}) - (f_{22} + f)^2\} + \\
& + 2(G + f_2)(I + f_2) \{-2(f_{22} + f) (f_{11} - f_{33}) - \\
& - 2(f_{33} + f) (f_{11} - f_{22}) - (f_{11} + f)^2\} + \\
& + \{(f_{11} + f) (f_{22} - f_{33})^2 + (f_{22} + f)^2 (f_{11} - f_{33}) + \\
& + (f_{33} + f)^2 (f_{11} - f_{22})\} (T_4 + f_{22}) + \\
& + \{(f_{22} + f) (f_{11} - f_{33})^2 + (f_{11} + f)^2 (f_{22} - f_{33}) - \\
& - (f_{33} + f)^2 (f_{11} - f_{22})\} (T_{11} + f_{22}) + \\
& + \{(f_{33} + f) (f_{11} - f_{22})^2 - (f_{22} + f)^2 (f_{11} - f_{33}) - \\
& - (f_{11} + f)^2 (f_{11} - f_{33})\} (T_{13} - f_{22} + 2f_{33}),
\end{aligned}$$

$$\begin{aligned}
g'_{33}(f) = & (C + f_3)^2 \{(f_{22} - f_{33})^2 + (f_{22} + f)^2 + (f_{33} + f)^2\} + \\
& + (H + f_3)^2 \{(f_{11} - f_{33})^2 + (f_{11} + f)^2 + (f_{33} + f)^2\} + \\
& + (J + f_3)^2 \{(f_{11} - f_{22})^2 + (f_{11} + f)^2 + (f_{22} + f)^2\} + \\
& + 2(C + f_3)(H + f_3) \{2(f_{11} + f) (f_{22} - f_{33}) + \\
& + 2(f_{22} + f) (f_{11} - f_{33}) - (f_{33} + f)^2\} + \\
& + 2(C + f_3)(J + f_3) \{2(f_{33} + f) (f_{11} - f_{22}) - \\
& - 2(f_{11} + f) (f_{22} - f_{33}) - (f_{22} + f)^2\} + \\
& + 2(H + f_3)(J + f_3) \{-2(f_{22} + f) (f_{11} - f_{33}) - \\
& - (f_{11} + f)^2 - 2(f_{33} + f) (f_{11} - f_{22})\} + \\
& + \{(f_{11} + f) (f_{22} - f_{33})^2 + (f_{22} + f)^2 (f_{11} - f_{33}) + \\
& + (f_{33} + f)^2 (f_{11} - f_{22})\} (T_6 + f_{33}) + \\
& + \{(f_{22} + f) (f_{11} - f_{33})^3 + (f_{11} + f)^2 (f_{22} - f_{33}) - \\
& - (f_{33} + f)^2 (f_{11} - f_{22})\} (T_{13} + f_{33}) + \\
& + \{(f_{33} + f) (f_{11} - f_{22})^2 - (f_{11} + f)^2 (f_{22} - f_{33}) - \\
& - (f_{22} + f)^2 (f_{11} - f_{33})\} (T_{15} + f_{33}).
\end{aligned}$$

From (6), (7), (9), (14), (15) and (17), we obtain

$$\begin{aligned}\Delta \mathcal{G}'(f) &= 2 \sum_{i=1}^3 (\mathcal{K}f)_i^2 + 2\mathcal{K}f\Delta\mathcal{K}f - 3\mathcal{L}f\Delta\mathcal{M}f - \\ &\quad - 3\mathcal{M}f\Delta\mathcal{L}f - 6 \sum_{i=1}^3 (\mathcal{L}f)_i \cdot (\mathcal{M}f)_i.\end{aligned}$$

This expression satisfies the conditions of the maximum principle because of (ii) and the assertion follows from Lemma 2, QED.

## REFERENCES

- [1] J. Janyška: *On linear functions on the sphere  $S^2$* , Cz. mat. J. 31 (106) 1981, 75–82.
- [2] A. Švec: *A remark on the differential equations on the sphere*, Čas. pro pěst. mat., 101 (1976), 278–282.
- [3] A. Švec: *Contributions to the global differential geometry of surfaces*, Rozpravy ČSAV, 87 (1977), No. 1.
- [4] M. Afwata, A. Švec: *Global differential geometry of hypersurfaces*, Rozpravy ČSAV, 88 (1978), No. 7.

J. Janyška  
662 95 Brno, Janáčkovo nám. 2a  
Czechoslovakia