# Commentationes Mathematicae Universitatis Carolinae

Jaroslav Haslinger; Ivan Hlaváček Convergence of a dual finite element method in  $R_n$ 

Commentationes Mathematicae Universitatis Carolinae, Vol. 16 (1975), No. 3, 469--485

Persistent URL: http://dml.cz/dmlcz/105640

### Terms of use:

© Charles University in Prague, Faculty of Mathematics and Physics, 1975

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* http://project.dml.cz

#### COMMENTATIONES MATHEMATICAE UNIVERSITATIS CAROLINAE

16,3 (1975)

## CONVERGENCE OF A DUAL FINITE ELEMENT METHOD IN R

J. HASLINGER, I. HLAVÁČEK, Praha

Abstract: Using the dual variational formulation of the elliptic second order problems, the question arises to construct suitable subspaces of admissible vector-funcions in  $\mathbf{R}_{\mathbf{n}}$ . In the paper a possible system of piecewise linear functions is shown and the rate of convergence  $O(h^2)$  proved, provided the exact solution is sufficiently regular.

 $\underline{\text{Key words}}\colon$  Finite elements, dual variational formulation, equilibrium models.

AMS: 65N30 Ref. Z.: 8.33

1. Introduction. Let  $\Omega \subset \mathbb{R}_n$  be a bounded domain with Lipschitz boundary (cf. [2]),  $k \ge 0$  integer. By  $\mathbb{W}^{k,2}(\Omega)$  we denote the set of real functions, which are square-integrable together with their generalized derivatives up to the order k,  $\mathbb{W}^{0,2}(\Omega) = \mathbb{L}_2(\Omega)$ ,  $[\mathbb{W}^{k,2}(\Omega)]^m = \mathbb{W}^{k,2}(\Omega) \times \dots \times \mathbb{W}^{k,2}(\Omega)$  with the norm m-times

$$\|\mathbf{v}\|_{\mathbf{k},\Omega} = \left(\sum_{i=1}^{m} \|\mathbf{v}_i\|_{\mathbf{k},\Omega}^2\right)^{1/2}, \quad \mathbf{v} = (\mathbf{v}_1,\dots,\mathbf{v}_m),$$

where

$$\|\mathbf{v_i}\|_{\mathbf{k},\Omega} = \left(\int_{\Omega} \sum_{|\mathbf{x}| \leq \mathbf{k}} |\mathbf{D}^{\mathbf{x}} \mathbf{v_i}(\mathbf{x})|^2 d\mathbf{x}\right)^{1/2}.$$

Let  $C^k(\overline{\Omega})$  denote the space of continuous functions, the derivatives of which up to the order k are also continuous

and continuously extendible onto  $\overline{\Omega}$  ,

$$[c^{k}(\overline{\Omega})]^{m} = \underline{c^{k}(\overline{\Omega}) \times ... \times c^{k}}(\overline{\Omega}),$$

with the norm

$$\|v\|_{\mathbb{C}^{2_{\kappa}}(\overline{\Omega})_{1}^{m}} = \max_{\substack{i=1,\dots,m}} (\max_{|\alpha| \leq k_{\kappa}} (\max_{x \in \overline{\Omega}} |D^{\infty} v_{1}(x)|)).$$

Let  $M \subset R_n$  . We denote by  $P_k(M)$  the space of all polynomials in n-variables of the order at most k with the domain M .

Let us consider the differential operator

$$\mathcal{A} u = -\sum_{i,j=1}^{m} \frac{\partial}{\partial x_{i}} \left( a_{ij} \frac{\partial u}{\partial x_{j}} \right) ,$$

satisfying the following conditions:

(1.1) 
$$a_{ij} \in L_{\infty}(\Omega)$$
,  $a_{ij}(x) = a_{ij}(x) \quad \forall i, j, \forall x \in \Omega$ 

$$(1.2) \qquad \exists \propto = const. > 0,$$

almost everywhere in  $\Omega$  .

Let the boundary  $\Gamma$  consist of three disjoint parts  $\Gamma_{u}$ ,  $\Gamma_{v}$ ,  $\mathcal{R}$  such that  $\Gamma_{u}$  is open in  $\Gamma$ ,  $\Gamma_{u} \neq \emptyset$ ,  $\operatorname{mes}_{n-1} \mathcal{R} = 0$ ,  $\Gamma_{v}$  either empty or open in  $\Gamma$  and

$$\Gamma = \Gamma_{\mu} \cup \Gamma_{\mathbf{q}} \cup \mathcal{R}$$
.

We shall solve the following problem:

where  $f \in L_2(\Omega)$ ,  $\overline{u} \in W^{1,2}(\Omega)$ ,  $g \in L_2(\Gamma_{Q_i})$  are assigned,

 $\mathbf{n_i}$  are components of the unit outward normal to  $\Gamma$  . We set:

$$V = \{v \mid v \in W^{1,2}(\Omega), v = 0 \text{ on } \Gamma_{M}\}.$$

A function  $u \in W^{1,2}(\Omega)$  will be called weak solution of the problem (1.3), if

$$u \in \overline{u} + V$$
,

$$\mathcal{L}(u) = \min_{v \in \overline{u} + V} \mathcal{L}(v)$$
,

where

$$\mathcal{L}(\mathbf{v}) = \frac{1}{2} \int_{\Omega} i \sum_{i,j=1}^{\infty} a_{ij} \frac{\partial v}{\partial x_i} \frac{\partial v}{\partial x_j} d\mathbf{x} - \int_{\Omega} \mathbf{f} \, \mathbf{v} \, d\mathbf{x} - \int_{\Gamma_{\mathbf{g}}} \mathbf{g} \, \mathbf{v} \, d\Gamma.$$

Denoting

$$\begin{split} \mathbf{H} &= \left[ \mathbf{L}_2(\Omega) \right]^m \;\;, \\ \| \, \boldsymbol{\lambda} \|^2 &= \sum_{i=1}^m \int_{\Omega} \boldsymbol{\lambda}_i^2 \, \mathrm{d} \mathbf{x} \;\;, \;\; \boldsymbol{\Lambda} = \left( \boldsymbol{\lambda}_1, \dots, \boldsymbol{\lambda}_m \right) \;, \end{split}$$

we define the bilinear form

$$(\lambda,\mu)_{H} = \sum_{i,j=1}^{n} \int_{\Omega} b_{ij} \lambda_{i} \mu_{j} dx$$
,  $\forall \lambda, \mu \in H$ ,

where  $b_{i,j}$  are the entries of the matrix [a<sup>-1</sup>] inverse to [a].

where

$$\|\lambda\|_{H}^{2}=(\lambda,\lambda)_{H}.$$

Moreover, we introduce

$$\begin{split} & \lambda_{1}(v) = \sum_{j=1}^{m} a_{1j} \frac{\partial v}{\partial x_{j}} \quad , \quad \lambda(v) = (\lambda_{1}(v), \dots, \lambda_{n}(v)), \\ & \Lambda_{1,g} = \{\lambda \mid \lambda \in H, \ B(\lambda,v) = \int_{\Omega} f \ v \ dx + \int_{\mathbb{S}} g \ v \ d\Gamma, \ \forall \ v \in V \} \end{split}$$
 where

$$B(\lambda, \mathbf{v}) = \sum_{i=1}^{m} \int_{0}^{\mathbf{v}} \lambda_{i} \frac{\partial \mathbf{v}}{\partial \mathbf{v}_{i}} d\mathbf{x}.$$

Theorem 1.1 (The minimum of complementary energy). Let u be a weak solution of the problem (1.3). Then the functional

$$\mathcal{G}(\mathcal{A}) = \frac{1}{2} \int_{\mathbb{R}^{3} \times \frac{1}{2} = 1}^{\infty} b_{ij} A_{i} A_{j} dx - B(\mathcal{A}, \overline{u})$$

attains its minimum on the set  $\Lambda_{\mathbf{f},\mathbf{Q}}$  , if and only if  $\lambda$  = =  $\lambda_{(u)}$  .

For the proof we refer to [1].

We have a variational problem of a minimum of a quadratic functional on a closed convex set  $\Lambda_{f,g} \subset H$ . As usual, the problem can be interved to a similar one, but on a linear space subspace  $\Lambda_{0.0} \equiv H_2 \subset H$ . In fact, we may write

$$\Lambda_{f,g} = \overline{\lambda} + \Lambda_{0,0} ,$$

where  $\overline{\lambda}$  is any fixed element of  $\Lambda_{\mathbf{f},\mathbf{g}}$  .

It is easy to show that the equivalent problem is to find  $\chi^{\circ}\in \mathrm{H}_{2}$  such that

$$\Phi(\chi^{\circ}) = \min_{\chi \in H_{2}} \Phi(\chi)$$

where

$$\begin{split} & \Phi(\chi) = \frac{1}{2} \left( \chi, \chi \right)_{\mathsf{H}} - F(\chi) \ , \\ & F(\chi) = - \int_{0}^{\infty} \sum_{i=1}^{\infty} \ell_{i,i} \, \overline{\lambda}_{i} \, \chi_{i,i} dx - B(\chi, \overline{\mu}) \ . \end{split}$$

Let  $h \in (0,1)$  and let  $\{V_h\}$  be a system of finite-dimensional subspaces of  $H_2$ . We define the following procedure:

(1.5) to find 
$$\chi_{\mathcal{A}}^{\circ} \in V_{\mathcal{A}}$$
 such that 
$$\Phi(\chi_{\mathcal{A}}^{\circ}) = \min_{\chi \in V_{\mathcal{A}}} \Phi(\chi).$$

Theorem 1.2. To every  $h \in (0,1)$  there exists precisely one  $\chi_{h}^{o} \in V_{h}$  satisfying (1.5) and it holds

$$(1.6) \|\chi^{0} - \chi^{0}_{h}\|_{H} \leq \inf_{\chi \in V_{h}} \|\chi^{0} - \chi\|_{H} \leq C_{2} \inf_{\chi \in V_{h}} \|\chi^{0} - \chi\|.$$

The proof can be found in [1] .

2. Construction of subspaces  $V_h$ . Let  $\Sigma = \{a_i\}_{i=1}^{n+1}$  be the set of (n+1) points in  $R_n$ ,  $(n \ge 2)$  such that their coordinates  $a_i = (a_{1i}, \dots, a_{ni})$  form a regular matrix

$$A = \begin{bmatrix} a_{11}, \dots & a_{1i}, \dots & a_{1n+1} \\ a_{21}, \dots & a_{2i}, \dots & a_{2n+1} \\ \vdots & \vdots & \vdots & \vdots \\ a_{n1}, \dots & a_{ni}, \dots & a_{nn+1} \\ 1, \dots & 1, \dots & 1 \end{bmatrix}$$

The closed convex hull of  $\Sigma$  will be called <u>n-simplex</u> K in R<sub>n</sub>, a<sub>i</sub>  $\in \Sigma$  its <u>vertices</u> and we write

$$K = \overline{\text{conv } \Sigma}$$
.

The assumption on the matrix A yields that the system

$$x_{i} = \sum_{j=1}^{m+1} a_{ij} \lambda_{j}(x) ,$$

$$1 = \sum_{j=1}^{m+1} \lambda_j(x)$$

has a unique solution  $\lambda(x) = (\lambda_1(x), \ldots, \lambda_{n+1}(x))$  for any point  $x \in \mathbb{R}_n$ . The components  $\lambda_1(x)$  will be called barycentric coordinates of the point x with respect to the vertices  $a_1, \ldots, a_{n+1}$ . Thus the n-simplex K can be characterized by means of the barycentric coordinates:

$$x \in \mathbb{K} \iff 0 \leq \lambda_{\mathbf{i}}(x) \leq 1$$
  $i = 1, ..., n + 1$ 

$$\sum_{i=1}^{m+1} \lambda_{\mathbf{i}}(x) = 1$$

By (n-1)-dimensional <u>side</u> of K we call the closed convex hull of an arbitrary n-tuple of points of  $\Sigma$ . Consequently, the total number of (n-1)-dimensional sides of K equals

$$\binom{n+1}{n} = n+1.$$

Each vertex  $a_1$  belongs to n sides of K. It is well known that the set  $\Sigma$  is  $P_1(K)$ -unisolvent, i.e. for any  $\alpha_1, \ldots, \alpha_{n+1} \in R_1$  there exists precisely one polynomial  $p \in P_1(K)$  such that  $p(a_1) = \alpha_1$ ,  $i = 1, \ldots, n+1$ .

Let 
$$\Sigma^{i} = \{a_{i,j}\}_{j=1}^{n}$$
, where  $a_{i,j} \in \Sigma$ . Then  $S_{i,j} = S_{i,j}$ 

=  $conv \Sigma^{-1}$  is a (n-1)-dimensional side of K.

We define a mapping  $T_1 \in \mathcal{L} ([W^{1,2}(K)]^m, L_2(S_1))$  by

the relation

$$T_{1} = V |_{S_{1}} \cdot n^{(1)} = \sum_{j=1}^{m} V_{j} n_{j}^{(1)}$$
,

where  $v|_{S_i}$  denotes the trace of v on  $S_i$  and  $n^{(i)}$  is the unit outward normal to  $S_i$ .

Lemma 2.1 Let  $\gamma_j^{(i)}$  be (n+1)n real numbers  $(i=1,\ldots,n+1)$  and  $j=1,\ldots,n$ . Then there exists a unique  $v \in [P_1(K)]^m$  such that

(2.1) 
$$T_{i}v(a_{i_{j}}) = \gamma_{j}^{(i)}$$
,  $a_{i_{j}} \in \Sigma^{i}$ .

<u>Proof.</u> Let  $a_i \in \Sigma$ , be a vertex of the simplex K, and  $S_{i_1}$ ,  $S_{i_2}$ ,..., $S_{i_n}$  the (n-1)-dimensional sides of K, containing  $a_i$ . We choose the equations from (2.1), concerning the vertex  $a_i$  only:

(2.2) 
$$v(a_i) \cdot n^{(i_j)} = \gamma_i^{(i_j)}$$

(suppose that  $a_i$  represents the i-th element in every  $\sum_{i=1}^{i}$ ). As the vectors  $n^{(i,j)}$ ,  $j=1,\ldots,n$  are linearly independent, there exists a unique solution  $v(a_i)=(v_1(a_i),\ldots,v_n(a_i))$ . From the  $P_1(K)$ -unisolvability of  $\Xi$  it folows the existence of unique polynomials  $v_j\in P_1(K)$ , corresponding to the values  $\{v_j(a_i)\}_{i=1}^{m+1}$ ,  $j=1,\ldots,n$ .

Let  $S_1$  be a (n-1)-dimensional side of K. We say that  $\lambda_1^{(i)}, \dots, \lambda_n^{(i)}$  are the <u>basic functions of the side</u>  $S_1$ , if  $1^0 \qquad \lambda_j^{(i)} \in P_1(S_1), \ j=1,\dots,n \ ,$   $2^0 \qquad \lambda_j^{(i)} \quad (a_{i_k}) = \sigma_{jk} \ , \quad a_{i_k} \in \Sigma^i \ .$ 

From the  $P_1(S_1)$ -unisolvability of every set  $\Sigma^i$  and from the definition of  $\mathcal{X}_{\mathcal{A}}^{(i)}$  it follows:

An easy calculation leads to the relation

$$\int_{S_{i}} \lambda_{i}^{(i)} dS = \int_{S_{i}} \lambda_{k}^{(i)} dS \qquad \forall j,k = 1,...,n.$$

Consequently, using also (2.3) we derive that

$$\operatorname{mes}_{n-1}(S_{i}) = \int_{S_{i}} (\sum_{j=1}^{n} \lambda_{j}^{(i)}) dS = n \cdot \int_{S_{i}} \lambda_{1}^{(i)} dS ,$$

(2.4) 
$$\int_{S_{i}} \lambda_{j}^{(i)} dS = \frac{1}{m} \operatorname{mes}_{n-1}(S_{i}), \quad j = 1, ..., n.$$

Henceforth we denote

$$(f,g) = \int_{S} f g dS$$

for any  $f, g \in L_2(S_1)$ .

Theorem 2.1 Let  $v \in [W^{1,2}(K)]^m$ . Then the equations

define a mapping  $\Pi \in \mathcal{L}([W^{1,2}(K)]^m, [P_1(K)]^m) \cap$ 

$$n \mathcal{L}([C(K)]^m, [P_1(K)]^m)$$
.

Proof. The numbers  $\alpha_{g_k}^{(i)}$  are uniquely determined by

(\*), because the matrix (Gramm's) A, with entries

$$(A_i)_{st} = (A_b^{(i)}, A_t^{(i)}), s, t = 1,2,...,n$$

is regular. Solving the system (\*) we obtain altogether (n+1) . n parameters  $\alpha_{\Re}^{(i)}$  . Lemma 2.1 yields the existence and uniqueness of a vector  $\varphi \in \mathbb{P}_1(\mathbb{K})^n$ , for which

$$T_{i} \varphi (a_{i,j}) = \alpha_{i,j}^{(i)}$$
.

We set  $\bigcap v = g$ . Obviously, the mapping  $\bigcap$  is linear. Let  $\alpha_{j,n}^{i}$  and  $\alpha_{j}^{(i)}$  be the solution of (\*) with the right hand sides  $(\mathbf{T_{i}}\mathbf{v_{n}}, \lambda_{k}^{(i)})$  and  $(\mathbf{T_{i}}\mathbf{v}, \lambda_{k}^{(i)})$ , respectively,  $(k = 1, \ldots, n)$  and let  $\mathbf{v_{n}} \rightarrow \mathbf{v}$  in  $[\mathbf{W}^{1,2}(\mathbf{K})]^{m}$ . From the theorem of traces (see [2]) and the Crammer's rule

$$\lim_{m \to \infty} \alpha_{j,m}^{(i)} = \alpha_{j}^{(i)}$$

follows. The rest of the proof is obvious.

Consequently, there exists a constant c > 0 such that  $\| \| v \|_{C(K)} \le c \| v \|_{C(K)}$ .

The magnitude of c will be estimated in the following

Theorem 2.2 Let us define 
$$\Pi$$
 by  $(*)$  and  $(**)$ . Then
$$\|\Pi v\|_{C(K)} \leq \frac{c_0}{\min \left\{ \det \left( m^{(i_1)}, \dots, m^{(i_m)} \right) \right\}} \|v\|_{C(K)}$$

where  $c_0$  is an absolute constant and the minimum is taken over the set of all n+1 n-tuples of numbers  $(i_1,\ldots,i_n)$ , chosen from the set  $\{1,\ldots,n+1\}$ .

<u>Proof.</u> Let  $\hat{K}$  represent the reference n-simplex in  $R_n$ , with the vertices  $(0,\ldots,0), (1,0,\ldots,0),\ldots, (0,\ldots,1)$ .

Let  $F(\hat{x}) = B\hat{x} + b$  be a regular affine mapping, of  $\hat{K}$  onto K (see [3]). Then  $S_1 = F(\hat{S})$ , where  $\hat{S}$  is a (n-1)-dimensional side of  $\hat{K}$ . Using the integral mean value theorem we obtain

$$\begin{split} &\int_{\mathcal{S}_{i}} \lambda_{j}^{(i)} \ \lambda_{k}^{(i)} \, d\mathcal{S} = J. \int_{\hat{\mathcal{S}}} \hat{\lambda}_{j}^{(i)}(\hat{x}) \ \lambda_{k}^{(i)}(\hat{x}) \, d\hat{\mathcal{S}} = \\ &= J. \ \hat{\lambda}_{j}^{(i)}(\hat{\xi}_{j}^{i}). \ \hat{\lambda}_{k}^{(i)}(\hat{\xi}_{k}^{i}). \ mes\left(\hat{\mathcal{S}}\right) = \\ &= \hat{\lambda}_{j}^{(i)}(\hat{\xi}_{j}^{i}) \ \hat{\lambda}_{k}^{(i)}(\hat{\xi}_{k}^{i}) \ mes\left(\mathcal{S}_{i}\right) \end{split}$$

where  $\lambda_{\dot{j}}^{(i)}(\hat{x}) = \lambda_{\dot{j}}^{(i)}(F \hat{x}), \hat{x} \in \hat{S}, \hat{\xi}_{\dot{j}}^{i} \in \hat{S}$  and J = const > 0 is the Jacobian of the transformation  $\hat{S} \longleftrightarrow S_{i}$ .

Hence

$$(\lambda_{\dot{i}}^{(i)}, \lambda_{k}^{(i)}) = c_{\dot{j}k}^{(i)} mes(S_{\dot{i}}),$$

with a constant  $c_{jk}^{(1)}$  independent of  $S_1$ . Consequently,

$$\det A_{1} = \overline{c}_{1}(\operatorname{mes}(S_{1}))^{n} , \quad \overline{c}_{1} \neq 0 ,$$

where  $\overline{c}_i$  is a linear combination of product of  $c_{ik}^{(i)}$ .

Using the Crammer's rule and a similar estimate of the determinant in the numerator, we are led to the estimate

(2.5) 
$$|\alpha_{i}^{(i)}| \leq c_{i} ||v||_{C(K)}$$

where  $c_i$  is an absolute constant. Solving the system (\*\*) we get  $\prod v(a_i) = (\varphi_1(a_i), \ldots, \varphi_n(a_i))$ . Using again the Crammer's rule and (2.5), we obtain

$$|q_{3}(a_{2})| = \frac{c_{0}}{\min\{|\det(m^{(2_{1})},...,m^{(2_{m})}|^{2}\}} \|v\|_{C(K)},$$

where  $c_0$  is an absolute constant and the denominator is defined in the Theorem. As  $\square v \equiv \varphi \in [P_1(K)]^m$ , the assertion follows immediately from the last inequality.

Let us denote

$$\mathcal{M}(K) = \{ \mathbf{v} = (\mathbf{v}_1, \dots, \mathbf{v}_n) \in [P_1(K)]^n, div \mathbf{v} = 0 \}.$$

It is readily seen that  $\dim \mathcal{M}(K) = (n+1) \cdot n - 1$ .

Lemma 2.2 
$$\forall \in \mathcal{M}(K) \iff \forall \in [P_{\gamma}(K)]^{\mathcal{M}} \&$$

& 
$$\int_{\partial K} \nabla \cdot \mathbf{n} \, dS = 0$$
.

Proof. Let 
$$\mathbf{v} \in [P_1(K)]^m$$
. Then  $\mathbf{div} \mathbf{v} \in P_0(K)$  and  $\mathbf{div} \mathbf{v} = 0 \iff \int_{\mathbb{R}} \mathbf{div} \mathbf{v} d\mathbf{x} = 0$ .

Hence the Green's theorem

$$\int_{K} div \ v \ dx = \int_{2K} v \cdot n \ dS$$

yields the assertion.

Lemma 2.3 
$$\mathbf{v} \in \mathcal{M}(\mathbf{K}) \Longleftrightarrow \mathbf{v} \in [P_1(\mathbf{K})]^m \& \sum_{i=1}^{m+1} \sum_{k=1}^{m} \propto \mathbf{k}^{(i)} \operatorname{mes}(S_1) = 0$$
,

where 
$$\alpha_{k}^{(i)} = T_1 \vee (a_{i_k}), a_{i_k} \in \Sigma^i$$
.

Proof. We have

$$\int_{\partial K} \mathbf{v} \cdot \mathbf{n} \, d\mathbf{S} = \sum_{i=1}^{m+1} \int_{\mathbf{S}_{i}} \mathbf{T}_{i} \, \mathbf{v} \, d\mathbf{S} \cdot \mathbf{T}_{i} \mathbf{v} = \sum_{k=1}^{m} \propto_{k}^{(i)} \lambda_{k}^{(i)} \cdot$$

Using also (2.4), we may write

$$\int_{\partial K} \mathbf{v} \cdot \mathbf{n} \, d\mathbf{S} = \frac{1}{m} \sum_{i=1}^{m+1} \sum_{k=1}^{m} \alpha_k^{(i)} \operatorname{mes}(\mathbf{S}_i) ,$$

and the assertion follows from Lemma 2.2.

Let us define

$$V(K) = \{ v \in [W^{1,2}(K)]^m, \text{ div } v = 0 \}.$$

Theorem 2.3 Let the mapping  $\Pi$  be defined by (\*) and (\*\*). Then

$$\Pi \in \mathcal{L}(V(K), \mathcal{M}(K))$$
,

$$(2.6) \qquad \qquad \Pi \mathbf{v} = \mathbf{v} \qquad \forall \mathbf{v} \in [P_1(K)]^m.$$

<u>Proof.</u> Adding the equations (\*) for k = 1,...,n we get

$$(T, v, \sum_{k=1}^{n} \lambda_{k}^{(i)}) = \sum_{j=1}^{n} \alpha_{j}^{(i)} (\lambda_{j}^{(i)}, \sum_{k=1}^{n} \lambda_{k}^{(i)})$$
.

From (2.3) and (2.4) it follows

$$\int_{S_{i}} T_{i} v \, dS = \sum_{j=1}^{m} \alpha_{j}^{(i)}(\lambda_{j}^{(i)}, 1) = \frac{1}{m} \sum_{j=1}^{m} \alpha_{j}^{(i)} mes(S_{i}).$$

If  $v \in V(K)$ , then we have

$$0 = \int_{\partial K} v \cdot m \, dS = \sum_{i=1}^{m+1} \int_{S_{2}} T_{i} v \, dS = \frac{1}{m} \sum_{i=1}^{m+1} \sum_{j=1}^{m} \alpha_{j}^{(i)} mes(S_{i}).$$

As  $\alpha_{\dot{j}}^{(i)} = T_1 \cap v(a_{\dot{1}_1})$ ,  $a_{\dot{1}_1} \in \Sigma^i$ , Lemma 2.3 yields

 $\sqcap$  v  $\in$  m (K). The assertion (2.6) is an immediate consequence of Lemma 2.1, because for v  $\in$   $\Gamma P_1(K) 1^m$ 

$$\alpha_{k}^{(i)} = T_{i} v(a_{i_{k}}) \equiv v(a_{i_{k}}) \cdot n^{(i)}$$

Theorem 2.4 Let  $\mathbf{v} \in [C^2(K)]^n$  and  $\mathbf{h} = \text{diam } K$ . Then

(2.7)  $\|\mathbf{v} - \mathbf{v}\|_{C(K)} \leq \frac{\mathbf{c}}{m \ln 1 |\det (m^{(i_1)}, ..., m^{(i_n)})|_3} h^2 \|\mathbf{v}\|_{C^2(K)}$ 

where c is an absolute constant and the denominator was defined in Theorem 2.2.

<u>Proof.</u> Let  $x_0 \in K$  be an arbitrary fixed point. Using the Taylor's theorem we obtain

(2.8) 
$$v(x) = v(x_0) + Dv(x_0)(x - x_0) + D^2v(\theta)(x - x_0)^2$$
,

with  $\theta \in \overline{x_0x}$ . Applying  $\Pi$  to (2.8), using its linearity and (2.6), we derive

Hence we may write

$$\| \mathbf{v} - \mathbf{u} \|_{C(K)} \leq \| \mathbf{D}^2 \mathbf{v}(\theta) (\mathbf{x} - \mathbf{x}_0)^2 \|_{C(K)} + \| \mathbf{u} \mathbf{D}^2 \mathbf{v}(\theta) (\mathbf{x} - \mathbf{x}_0)^2 \|_{C(K)}.$$

The estimate (2.7) follows from Theorem 2.2 and  $\|x - x_0\| \le h$ .

Remark 2.1 For n = 2 we have

$$|\det(n^{(i_1)}, n^{(i_2)})| = |n^{(i_1)} \times n^{(i_2)}| = \sin \alpha_{12}$$
,

where  $\alpha_{12}$  is the angle between vectors  $n^{(i_1)}$ ,  $n^{(i_2)}$ . Hence

$$\| v - \Pi v \|_{C(K)} \leq \frac{c}{\sin \alpha} \| v \|_{C^{2}(K)},$$

where  $\infty$  is the minimal angle of the triangle K .

For n = 3 there holds

$$|\det(n^{(i_1)}, n^{(i_2)}, n^{(i_3)})| = |n^{(i_1)} \cdot (n^{(i_2)} \times n^{(i_3)})|$$

which equals the volume of the parallelepiped, being determined by the three (unit) vectors  $n^{(i_1)}$ ,  $n^{(i_2)}$  and  $n^{(i_3)}$ .

Let us consider a bounded polyhedral domain  $\Omega\subset R_n$ . Let h be a parameter, h  $\epsilon$  (0.1 > ,  $T_n$  a finite division of  $\Omega$  , satisfying the usual conditions concerning the mutual position of any couple of n-simplexes K, K'  $\epsilon$   $T_n$  , h =

= max (diam K) .
Ke Ti

Let K and K' have a common (n-1)-dimensional side  $S_1$ ,  $\forall$   $\in$   $[W^{1,2}(\Omega)]^m$ . Denote

$$T_{i,K}v = v \mid_{S_4} \cdot n_K^{(i)}$$
,  $T_{i,K}v = v \mid_{S_4} \cdot n_{K'}^{(i)}$ ,

where  $n_K^{(1)}$  and  $n_{K'}^{(1)}$ , is the unit outward normal with respect to K and K', respectively, at a point  $x \in S_1$ .

We say that the condition (R) is satisfied on S4, if

(2.9) 
$$T_{i,K}^{v} + T_{i,K'}^{v} = 0$$
 on  $S_{i}$ .

Denote

$$V(\Omega) = iv \in [W^{1,2}(\Omega)]^m$$
, div  $v = 0$ ,

$$\mathcal{N}_{h}(\Omega) = \{v,v|_{K} \in \mathcal{M}(K), \forall K \in \mathcal{T}_{h}, \text{ and }$$

(R) is satisfied on every common side in  $\mathcal{T}_h$  ? .

Let us define a mapping  $r_h$  of  $[W^{1,2}(\Omega)]^m$  as follows:

where  $\Pi_K$  has been defined in Theorem 2.1 through (\*) and (\*\*) on every K  $\in \mathcal{T}_h$ .

We say that a family of division  $\{T_h, \}$ , he (0,1) is regular, if a constant  $\infty_o > 0$  exists such that for every K  $\in T_h$  and any he (0,1)

(2.11) 
$$\min \{ |\det (n_{K}^{(i_{1})}, ..., n_{K}^{(i_{m})}| \} \ge \alpha_{o} ,$$

the minimum being defined in Theorem 2.2.

The condition (2.11) implies for n=2 and n=3 that the corresponding angles and volumes, respectively, cannot converge to zero with  $h \rightarrow 0$  (see Remark 2.1).

Theorem 2.5 Let  $\{T_h\}$ ,  $h \in (0,1)$  be a regular family of division. Define the mapping  $r_h$  as in (2.10). Then

(2.12) 
$$r_h \in \mathcal{L}(V(\Omega), \mathcal{N}_h(\Omega))$$
,

(2.13) 
$$\| \mathbf{v} - \mathbf{r}_{\mathbf{h}} \mathbf{v} \|_{0,0} \le c \mathbf{h}^2 \| \mathbf{v} \|_{\mathbf{C}^2(\overline{\Omega})}$$
.

Proof. From Theorem 2.3 it follows

$$\mathbf{r}_{h}\mathbf{v}|_{K} \in \mathcal{M}(K) \quad \forall \mathbf{v} \in \mathbf{V}(\Omega), \quad \forall K \in \mathcal{I}_{h}$$
.

Hence it suffices to verify the condition (R) on every common (n-1)-dimensional side  $S_i$  in  $\mathcal{T}_h$ . As  $T_{i,K}(\sqcap_{K^v})$  and  $T_{i,K}(\sqcap_{K^v})$  belong to  $P_1(S_i)$ , it suffices to verify that

$$T_{i,K}(\bigcap_{K^{\vee}})(a_{i,j}) + T_{i,K^{\vee}}(\bigcap_{K^{\vee}})(a_{i,j}) = 0 \quad \forall a_{i,j} \in \Sigma^{i} \subset S_{i}.$$

This follows from (\*), (\*\*), because  $n_{K}^{(1)} = -n_{K'}^{(1)}$ , and therefore

$$T_{\mathbf{i},K}(\sqcap_{K^{\vee}})(\mathbf{a}_{\mathbf{i}_{\mathbf{j}}}) = \alpha_{\mathbf{j}}^{(i)}$$

$$T_{\mathbf{i},K'}(\sqcap_{K'^{\vee}})(\mathbf{a}_{\mathbf{i}_{\mathbf{j}}}) = -\alpha_{\mathbf{j}}^{(i)}.$$

The estimate (2.13) can be obtained in a usual way:

 $\| \mathbf{v} - \mathbf{r}_{h} \mathbf{v} \|_{0,\Omega}^{2} = \sum_{K \in \mathcal{T}_{h}} \| \mathbf{v} - \Pi_{K} \mathbf{v} \|_{0,K}^{2} \le ch^{4} \| \mathbf{v} \|_{C^{2}(\overline{\Omega})}^{2},$ where (2.7) and (2.11) have been employed.

Remark 2.2 Any  $v \in \mathcal{N}_h(\Omega)$  satisfies the equation div v = 0 in the sense of distributions.

In fact, let  $\varphi \in \mathcal{D}(\Omega)$  (i.e., an infinitely differentiable function with compact support). Then

defines the subspace  $V_h$  of  $H_2$  . Then Theorems 1.2 and (2.13) lead to the following

Theorem 2.7 Let the solution  $\chi^{\circ}$  of (1.4) belong to  $C^2(\overline{\Omega})$  and  $\{\mathcal{F}_h\}$ ,  $h\in (0,1)$  be a regular family of divisions consistent with  $\Gamma_g$ . Then

$$\|\chi^{\circ} - \chi^{\circ}_{A}\|_{0,\Omega} = o(h^{2}), h \rightarrow 0$$

where  $\chi^{o}_{\mathcal{R}}$  is the solution of (1.5).

Remark 2.3 The principle of complementary energy (Theo-

rem 1.1) can be extended to the mixed boundary-valued problem including the Newton's condition (see [1] - Appendix). The same subspaces  $\mathcal{N}_{\mathbf{h}}(\Omega)$  are applicable and an analogue of Theorem 2.7 holds.

Remark 2.4 As  $V_h$  belong to  $\Lambda_{0,0} = H_2$ , the dual method described above can be used to get (i) a posteriori error estimates and (ii) the solutions by the method of hypercircle (cf. [11]).

#### References

- [1] J. HASLINGER and I. HLAVAČEK: Convergence of a finite element method based on the dual variational formulation, Aplikace matematiky (to appear).
- [2] J. NEČAS: Les méthodes directes en théorie des équations elliptiques, Academia, Prague 1967.
- [3] P.G. CIARLET and P.A. RAVIART: General Lagrange and Hermite interpolation in R<sup>n</sup> with applications to finite element methods, Arch.Rat.Mech.Aval. 46(1972), 177-199.

Matematický ústav ČSAV Katedra matem.analýzy MFF KU
Žitná 25 Sokolovská 83

11567 Praha 1 18600 Praha 8
Československo Československo

(Oblatum 11.3.1975)