

Ta Van Dinh

On multi-parameter error expansions in finite difference methods for linear Dirichlet problems

Aplikace matematiky, Vol. 32 (1987), No. 1, 16–24

Persistent URL: <http://dml.cz/dmlcz/104232>

Terms of use:

© Institute of Mathematics AS CR, 1987

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://dml.cz>

ON MULTI-PARAMETER ERROR EXPANSIONS
IN FINITE DIFFERENCE METHODS FOR LINEAR DIRICHLET
PROBLEMS

TA VAN DINH

(Received July 29, 1985)

Summary. The paper is concerned with the finite difference approximation of the Dirichlet problem for a second order elliptic partial differential equation in an n -dimensional domain.

Considering the simplest finite difference scheme and assuming a sufficient smoothness of the domain, coefficients of the equation, right-hand part, and boundary condition, the author develops a general error expansion formula in which the mesh sizes of an (n -dimensional) rectangular grid in the directions of the individual axes appear as parameters.

Keywords: finite difference method, Dirichlet problem, error expansion.

AMS classification: 65 N 15.

In finite difference methods the one-parameter error expansions have been studied by many authors (cf. for instance [1] and references therein). In this paper we investigate the multi-parameter expansions for solving elliptic linear Dirichlet problems on a multidimensional domain with smooth boundary.

1. THE DIFFERENTIAL PROBLEM

Let R^n be a real n -dimensional Euclidean space. Let Ω be a bounded domain in R^n and Γ its boundary. Denote by $x = (x_1, \dots, x_n)$ the point in R^n . Let functions of n variables x_1, \dots, x_n : $f(x)$, $p_i(x)$, $q(x)$ on $\bar{\Omega}$ and $g(x)$ on Γ , be given. Consider the differential operator

$$Lu \equiv \sum_{i=1}^n \frac{\partial}{\partial x_i} \left(p_i \frac{\partial u}{\partial x_i} \right) - qu, \quad x \in \Omega,$$

The differential problem is

$$(1.1) \quad Lu = f, \quad x \in \Omega,$$

$$(1.2) \quad u = g, \quad x \in \Gamma.$$

Assume that there exist a real number λ ($0 < \lambda < 1$), and a positive integer m so that (cf. [2])

$$(1.3) \quad \Gamma \in C^{2m+2+\lambda};$$

$$p_i \in C^{2m+1+\lambda}(\bar{\Omega}); \quad q, f \in C^{2m+\lambda}(\bar{\Omega}); \quad g \in C^{2m+2+\lambda}(\Gamma);$$

$$(1.4) \quad p_i \geq \text{const} > 0; \quad q \geq 0.$$

Then we have ([1])

Lemma 1. *The problem (1)–(4) has a unique solution*

$$(1.5) \quad u \in C^{2m+2+\lambda}(\bar{\Omega}).$$

2. THE GRID

Assume that $A_i, B_i, i = 1, \dots, n$ are real numbers such that

$$\Omega \subset D = \{x \mid A_i \leq x_i \leq B_i\}.$$

Let N_i be given positive integers. We put

$$h_i = (B_i - A_i)/N_i,$$

$$x_i(j_i) = A_i + j_i h_i; \quad j_i = 0, 1, 2, \dots$$

Then the points $(x_1(j_1), \dots, x_n(j_n))$, denoted by (j_1, \dots, j_n) , are called grid points in the rectangle D , and the grid over Ω , denoted by Ω_h , is defined by

$$\Omega_h = \{(j_1, \dots, j_n) \mid (j_1, \dots, j_n) \in \Omega\}.$$

Each point of Ω_h is called an interior grid point. Each interior grid point (j_1, \dots, j_n) has $2n$ neighbouring points which are

$$(2.1) \quad (j_1, \dots, j_{k-1}, j_k \pm 1, j_{k+1}, \dots, j_n), \quad k = 1, \dots, n.$$

If all points (2.1) belong to $\bar{\Omega}$ then the point (j_1, \dots, j_n) is called a regular interior grid point. If at least one point of (2.1) does not belong to $\bar{\Omega}$ then the point (j_1, \dots, j_n) is an irregular interior grid point. Denote respectively by $\Omega_{h,r}$ and $\Omega_{h,ir}$ the sets of regular and irregular interior grid points. Then we have $\Omega_h = \Omega_{h,r} \cup \Omega_{h,ir}$.

3. THE DISCRETE PROBLEM

3.1. Notation. We introduce the following notation:

1) $i \in I$ iff $i = (i_1, \dots, i_n)$, $i_k = \text{integer} \geq 0$.

2) If $i \in I$ then

$$|i| = i_1 + \dots + i_n,$$

$$w_{[i]} = w_{i_1 \dots i_n};$$

3) $h = (h_1, \dots, h_n)$, $h_k = (B_k - A_k)/N_k$, $|h| = \max \{h_1, \dots, h_n\}$.

3.2. Approximation of the differential operator. Let v be a function defined on $\Omega_h \cup \Gamma$. Then its value at a point P is denoted by $v(P)$ or $v(x_1(P), \dots, x_n(P))$, $x_k(P)$ being the k -coordinate of P . Now at $P \in \Omega_{h,r}$ we consider the discrete operator

$$L_h v \equiv \sum_{i=1}^n (a_i v_{\bar{x}_i})_{x_i} - qv$$

where

$$\begin{aligned} (a_i v_{\bar{x}_i})_{x_i} &= h_i^{-2} [a_i^{(+i)}(P)(v^{(+i)}(P) - v(P)) - a_i^{(-i)}(P)(v(P) - v^{(-i)}(P))], \\ a_i^{(\pm i)}(P) &= p_i(x_1(P), \dots, x_{i-1}(P), x_i(P) \pm 0.5h_i, x_{i+1}(P), \dots, x_n(P)), \\ v_i^{(\pm i)}(P) &= v(x_1(P), \dots, x_{i-1}(P), x_i(P) \pm h_i, x_{i+1}(P), \dots, x_n(P)). \end{aligned}$$

It is obvious that we have

Lemma 2. *The discrete operator L_h satisfies the maximum principle.*

Now by applying Taylor's formula we obtain

Lemma 3. *For any function $w \in C^{2l+2+\lambda}(\bar{\Omega})$ we have*

$$L_h w = Lw + \sum_{i=1}^n \sum_{k=1}^l h_i^{2k} F_{ik}(w) + r_1,$$

where $F_{ik}(w)$ depend only on w and on the derivatives of w up to order $2k + 2$, and $|r_1| \leq \text{const} \cdot |h|^{2l+\lambda}$.

Lemma 4. *For any $w_{[j]} \in C^{2m-2|j|+2+\lambda}(\bar{\Omega})$, $j \in I$, we have*

$$L_h(u + S_m) = Lu + \sum_{k=1}^m \sum_{|j|=k} h_1^{2j_1} \dots h_n^{2j_n} (Lw_{[j]} + G_{[j]}(u, \dots, w_{[i]}, \dots)) + r_2$$

where u satisfies (1.5),

$$(3.1) \quad S_m = \sum_{k=1}^m \sum_{|j|=k} h_1^{2j_1} \dots h_n^{2j_n} w_{[j]},$$

$G_{[j]}$ depends only on u and $w_{[i]}$ up to $|i| < |j|$, and $|r_2| \leq \text{const} \cdot |h|^{2m+\lambda}$.

Proof. We have

$$L_h(u + S_m) = L_h u + \sum_{k=1}^m \sum_{|j|=k} h_1^{2j_1} \dots h_n^{2j_n} L_h w_{[j]}.$$

Then the application of Lemma 3 to $L_h u$ and $L_h w_{[j]}$ completes the proof.

Lemma 5. *Under the assumptions (1.3) (1.4) there exist functions $w_{[j]} \in C^{2m-2k+2+\lambda}(\bar{\Omega})$, $|j| = k$, $k = 1, \dots, m$, independent of h so that*

$$L_h(u + S_m) = Lu + r_3$$

where S_m has the form (3.1) and $|r_3| \leq \text{const} \cdot |h|^{2m+\lambda}$.

Proof. We can write the conditions that make the coefficients of $h_1^{2j_1} \dots h_n^{2j_n}$ in Lemma 4 equal to zero:

$$Lw_{[j]} = -G_{[j]}, \quad x \in \Omega; \quad w_{[j]} = 0, \quad x \in \Gamma.$$

Then, according to Lemma 1, the functions $w_{[j]}$ are successively determined for $|j| = 1$ to $|j| = m$ and belong to $C^{2m-2|j|+2+\lambda}(\bar{\Omega})$.

3.3. Approximation of the boundary condition. Now let $P \in \Omega_{h,ir}$. We shall calculate the value $v(P)$ with the help of Lagrange's interpolating polynomials starting with the values of v on the boundary Γ and at some points of $\Omega_{h,r}$ ([1]). First, in a way analogous to [1] consider the quantity

$$B(d) = \sum_{k=1}^{2m} \frac{(2m)!}{k!(2m-k)!} \cdot \frac{d}{d+k}, \quad d > 0.$$

We observe that $B(d)$ decreases when d decreases and tends to zero when d tends to zero. So there exists $\delta > 0$ such that

$$B(d) \leq B(\delta) < 1, \quad d < \delta.$$

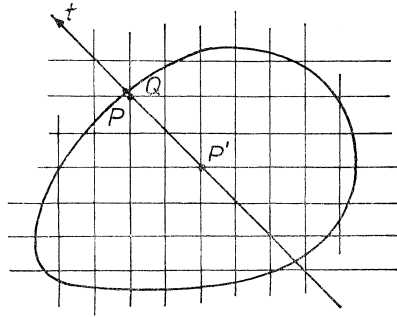


Fig. 1.

Let $P \in \Omega_{h,ir}$. Consider a fixed point P' (fig. 1) of $\Omega_{h,r}$. As the grid is uniform along each coordinate direction, the line PP' , which can but need not be parallel to a coordinate direction, passes through many equally spaced grid points of $\Omega_{h,r}$. Let η be the distance between these equally spaced points. Denote by Pt the axis obtained by orienting the line PP' from the origin P to the exterior of Ω . Let Q be the intersection of Pt with the boundary Γ . Let $PQ = \sigma\eta$ with some positive σ . Let μ be the smallest positive integer satisfying $\mu \geq \sigma/\delta$ and $H = \mu\eta$. Then $PQ = dH$ with $d = \sigma/\mu \leq \delta$. Consider the points on Pt with the abscissae

$$(3.2) \quad -2mH, \quad -(2m-1)H, \quad \dots, \quad -2H, \quad -H, \quad dH,$$

under the assumption that all these points belong to $\bar{\Omega}$. This assumption is satisfied when h is small enough. Then these points belong to $\Omega_{h,r} \cup \Gamma$.

Now let $w(t)$ be a smooth enough function on $[-2mH, dH]$. Consider the interpolating polynomial $P_{2m}(t)$ of degree $2m$ at the nodes (3.2), so that

$$P_{2m}(-kH) = w(-kH), \quad k = 1, \dots, 2m; \quad P_{2m}(dH) = w(dH).$$

Then we get

$$w(P) = w(0) = J_d w(0) + A_d w(dH) + R(0),$$

where

$$J_d w(0) = \sum_{k=1}^{2m} (-1)^k \frac{(2m)!}{k!(2m-k)!} \cdot \frac{d}{d+k} \cdot w(-kH),$$

$$A_d w(dH) = A_d w(Q) = \sum_{k=1}^{2m} \frac{k}{d+k}.$$

(The above formulae for the operators J_d, A_d have been introduced in [1].) Concerning the remaining term $R(0)$ we have

Lemma 6. *If $w(t) \in C^{M+1}[-2mH, dH]$, $M \leq 2m$, then*

$$|R(0)| \leq H^{M+1} \frac{d}{M+1} \max_{t \in [-2mH, dH]} |w^{(M+1)}(t)|.$$

The proof can be done by repeated application of Rolle's theorem.

If $P \in \Omega_{h,ir}$ we put, analogously to [1]:

$$v(P) = J_d v(P) + A_d v(Q).$$

Then Lemma 6 yields

Lemma 7. *If $w \in C^{M+1}(\bar{\Omega})$, $M \leq 2m$ then*

$$w(P) - J_d w(P) - A_d w(Q) = H^{M+1} r_4,$$

where $|r_4| \leq \text{const}$ (independent of h).

3.4. The discrete problem. We introduce the following discrete problem:

$$(3.3) \quad L_h v(P) = f(P), \quad P \in \Omega_{h,r},$$

$$(3.4) \quad v(P) = J_d v(P) + A_d v(Q), \quad P \in \Omega_{h,ir},$$

$$(3.5) \quad v(P) = g(P), \quad P \in \Gamma.$$

4. THE ASYMPTOTIC ERROR EXPANSION

4.1. Theorem 1. *The discrete problem (3.3)–(3.5) has a unique solution v which is the limit of $v^{(v)}$ calculated by the iterations*

$$L_h v^{(v)} = f(P), \quad P \in \Omega_{h,r},$$

$$\begin{aligned} v^{(v)} &= J_d v^{(v-1)}(P) + A_d v^{(v-1)}(Q), \quad P \in \Omega_{h,ir}, \\ v^{(v)} &= g(P), \quad P \in \Gamma. \end{aligned}$$

Proof. We have

$$(4.1) \quad L_h(v^{(v+1)} - v^{(v)}) = 0, \quad P \in \Omega_{h,r},$$

$$(4.2) \quad v^{(v+1)} - v^{(v)} = J_d(v^{(v)} - v^{(v-1)}), \quad P \in \Omega_{h,ir}.$$

We define the norms

$$\|w\|_h = \max_{P \in \Omega_h} |w(P)|, \quad \|w\|_{h,ir} = \max_{P \in \Omega_{h,ir}} |w(P)|.$$

By virtue of the maximum principle (Lemma 2) we deduce from (4.1), (4.2)

$$\begin{aligned} \|v^{(v+1)} - v^{(v)}\|_h &\leq \|v^{(v+1)} - v^{(v)}\|_{h,ir} = \\ &= \|J_d(v^{(v)} - v^{(v-1)})\|_{h,ir} \leq B(\delta) \|v^{(v)} - v^{(v-1)}\|_h. \end{aligned}$$

Therefore

$$(4.3) \quad \|v^{(v+1)} - v^{(v)}\|_h \leq \varrho \|v^{(v)} - v^{(v-1)}\|_h$$

where $\varrho = B(\delta) < 1$.

Hence the discrete problem (3.3)–(3.5) has a unique solution which is the limit when $v \rightarrow \infty$ of $v^{(v)}$ for any $v^{(0)}$.

4.2. Theorem 2. *There exist functions $w_{[j]} \in C^{2m-2k+2+\lambda}(\bar{\Omega})$, $j \in I$, $|j| = k$, $k = 1, \dots, m$, independent of h , so that we have the asymptotic error expansion*

$$v^{(v)}(P) = u(P) + S_m + r_s,$$

where v and u are solutions of the discrete and differential problems, respectively, S_m has the form (3.1) and $|r_s| \leq \text{const}$ (independent of h). $|h|^{2m+\lambda}$.

Proof. From (4.3) we deduce

$$\|v^{(v+1)} - v^{(v)}\|_h \leq \varrho^v \|v^{(1)} - v^{(0)}\|_h,$$

hence

$$\|v^{(v)} - v^{(0)}\|_h \leq \frac{1}{1 - \varrho} \|v^{(1)} - v^{(0)}\|_h.$$

Therefore

$$\|v - v^{(0)}\|_h \leq \frac{1}{1 - \varrho} \|v^{(1)} - v^{(0)}\|_h$$

and we choose

$$v^{(0)} = u + S_m = u + \sum_{k=1}^m \sum_{|j|=k} h_1^{2j_1} \dots h_n^{2j_n} w_{[j]}$$

where $w_{[j]}$ are determined in Lemma 5 in which u is the solution of the differential problem.

In order to evaluate $\|v^{(1)} - v^{(0)}\|_h$ we write

$$\begin{aligned} L_h v^{(1)} &= f(P), \quad P \in \Omega_{h,r}, \\ v^{(1)} &= J_d v^{(0)}(P) + A_d v^{(0)}(Q), \quad P \in \Omega_{h,ir}. \end{aligned}$$

On the other hand, by Lemma 5 we have

$$L_h v^{(0)} = L_h(u + S_m) = Lu + r_3.$$

So putting $v^{(1)} - v^{(0)} = z$ we have

$$\begin{aligned} L_h z &= -r_3, \quad P \in \Omega_{h,r}, \\ z &= J_d v^{(0)}(P) + A_d v^{(0)}(Q) - v^{(0)}(P), \quad P \in \Omega_{h,ir}. \end{aligned}$$

Since $v^{(0)} = u + S_m$ we have at $P \in \Omega_{h,ir}$

$$\begin{aligned} z &= J_d u(P) + A_d u(Q) - u(P) + \sum_{k=1}^m \sum_{|j|=k} h_1^{2j_1} \dots h_n^{2j_n} \times \\ &\quad \times (J_d w_{[j]}(P) + A_d w_{[j]}(Q) - w_{[j]}(P)). \end{aligned}$$

Then, taking into account the smoothness of $w_{[j]}$ and Lemma 7 we have at $P \in \Omega_{h,ir}$

$$(4.4) \quad z = r, \quad |r| \leq \text{const} \cdot |h|^{2m+1}.$$

So z satisfies

$$(4.5) \quad \begin{aligned} L_h z &= \alpha, \quad P \in \Omega_{h,r}, \\ z &= r, \quad P \in \Omega_{h,ir}, \\ z &= 0, \quad P \in \Gamma, \\ |\alpha| &\leq c \cdot |h|^{2m+\lambda} \end{aligned}$$

where

$$c = \text{const} (\text{independent of } h).$$

Let us put

$$(4.6) \quad z = z_1 + z_2$$

with

$$(4.7) \quad L_h z_1 = 0, \quad P \in \Omega_{h,r},$$

$$(4.8) \quad z_1 = r, \quad P \in \Omega_{h,ir}; \quad z_1 = 0, \quad P \in \Gamma,$$

$$(4.9) \quad L_h z_2 = \alpha, \quad P \in \Omega_{h,r},$$

$$(4.10) \quad z_2 = 0, \quad P \in \Omega_{h,ir} \cup \Gamma.$$

By the maximum principle (Lemma 2) we get from (4.7), (4.8)

$$(4.11) \quad \|z_1\|_h \leq \|r\|_{h,ir}.$$

To evaluate z_2 we consider the differential problem

$$\begin{aligned}Lw &= -2, \quad P \in \Omega, \\w &= 2, \quad P \in \Gamma.\end{aligned}$$

Thus w exists by Lemma 1 and

$$(4.12) \quad 0 < w \leq K = \text{const} \text{ (independent of } h \text{)}.$$

At the same time

$$(4.13) \quad \text{for } h \text{ small enough}$$

we have

$$\begin{aligned}L_h w &\leq -1, \quad P \in \Omega_{h,r}, \\w &\geq 1, \quad P \in \Omega_{h,ir} \cup \Gamma.\end{aligned}$$

Now we consider another differential problem

$$\begin{aligned}LW &= -2K', \quad P \in \Omega, \\W &= 2K', \quad P \in \Gamma\end{aligned}$$

where

$$(4.14) \quad K' = \max |\alpha(P)|, \quad P \in \Omega_{h,r}.$$

So W exists and, in view of (4.12),

$$(4.15) \quad 0 < W \leq KK'.$$

At the same time under the condition (4.13) we have

$$\begin{aligned}L_h W &\leq -K', \quad P \in \Omega_{h,r}, \\W &\geq K', \quad P \in \Omega_{h,ir} \cup \Gamma.\end{aligned}$$

Therefore (4.9), (4.10) give

$$\begin{aligned}L_h(W \pm z_2) &\leq 0, \quad P \in \Omega_{h,r}, \\W \pm z_2 &\geq 0, \quad P \in \Omega_{h,ir} \cup \Gamma.\end{aligned}$$

By the maximum principle we have

$$W \pm z_2 \geq 0, \quad P \in \Omega_h,$$

that is, in view of (4.15),

$$|z_2| \leq W \leq KK', \quad P \in \Omega_h.$$

Taking into account the relations (4.14) and (4.5) we get

$$(4.16) \quad \|z_2\|_h \leq \text{const} \cdot |h|^{2m+\lambda}.$$

Finally, the relations (4.6), (4.11), (4.4), (4.16) give

$$\|z\|_h \leq \text{const (independent of } h) \cdot |h|^{2m+\lambda}$$

and the theorem is proved.

Note 1. If $p_i = \text{const}$ then the restriction (4.13) is not necessary.

Note 2. The previous results still hold in the case when the term qu in Lu is replaced by $q(x, u)$ where q is smooth enough and $\partial q / \partial u \geq 0$.

References

- [1] Г. И. Марчук, В. В. Шайдуров: Повышение точности решений разностных схем. Москва, Наука, 1979.
- [2] О. А. Ладыженская, Н. Н. Уральцева: Линейные и квазилинейные уравнения эллиптического типа. Москва, Наука, 1973.

Souhrn

O VÍCEPARAMETRICKÝCH ROZVOJÍCH CHYBY U SÍŤOVÝCH METOD PRO LINEÁRNÍ DIRICHLETOVU ÚLOHU

TA VAN DINH

Práce je věnována studiu diferenční aproximace Dirichletovy okrajové úlohy pro eliptickou parciální diferenciální rovnici druhého řádu v n -rozměrné oblasti.

K nejjednoduššímu diferenčnímu schématu odvozuje autor obecný rozvoj chyby, v němž jako parametry vystupují kroky (n -rozměrné) obdélníkové sítě ve směrech jednotlivých souřadnicových os. Předpokládá se přítom dostatečná hladkost oblasti, koeficientů rovnice, pravé strany a okrajové podmínky.

Резюме

О МНОГОПАРАМЕТРИЧЕСКИХ ФОРМУЛАХ ДЛЯ ПОГРЕШНОСТИ МЕТОДА СЕТОК ПРИ РЕШЕНИИ ЛИНЕЙНОЙ ЗАДАЧИ ДИРИХЛЕ

TA VAN DINH

Статья посвящена конечно-разностной аппроксимации краевой задачи Дирихле для эллиптического дифференциального уравнения второго порядка на n -мерной области.

Используя простейшую разностную схему и предполагая достаточную гладкость области, коэффициентов уравнения, правой части и краевого условия, автор выводит общую формулу для погрешности, в которой в качестве параметров выступают шаги (n -мерной) прямоугольной сетки по направлениям отдельных осей координат.

Author's address: Ta Van Dinh, Khoa Toan ly, Truong dai hoc bach khoa Hanoi (Department of Mathematics and Physics, Polytechnical Institute of Hanoi) Vietnam.