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A RANK DECISION RULE FOR A COMBINED PROBLEM  
OF TESTING AND CLASSIFICATION

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I. INTRODUCTION

The problem of testing the null hypothesis  $H_0$  against the alternatives  $K_1, K_2, \dots, K_s$ , where under  $H_0$  the observations  $X_1, \dots, X_N$  are independent, identically distributed with the common density  $f \in \mathcal{F}$  (some family of density functions), and under  $K_i$  the observations  $X_1, \dots, X_N$  have the densities

$$(1) \quad f_1(x) = f(x, \Delta C_{i1}), \dots, f_N(x) = f(x, \Delta C_{iN})$$

with respect to the Lebesgue measure, respectively, for  $i = 1, \dots, s$ , where  $f(x, 0) = f(x)$ , has been considered in [7]. However, one sometimes encounters the situations where one has to decide which alternative of  $K_1, \dots, K_s$  is true when  $H_0$  has been rejected.

Therefore, let us construct a procedure, which allows us at first to test the hypothesis  $H_0$ , then if  $H_0$  has been rejected, to decide which of  $K_1, \dots, K_s$  is true. The problem was investigated by Pfanzagl [9]. The slippage problem – a special case of the combined problem of testing and classification was investigated by Mosteller [6], Paulson [8], Truax [11], Karlin - Truax [5], Hall - Kudo [3], Hall - Kudo - Yeh [4].

The most of procedures suggested by these authors are based directly on observations rather than on ranks. On the other hand, the procedure proposed in this work is based on ranks.

A combined decision rule for testing and classification may be characterized by a vector-valued function

$$\varphi(x) = \{\varphi_0(x), \varphi_1(x), \dots, \varphi_s(x)\}$$

where  $\varphi_0(x), \varphi_i(x)$  are the probabilities of accepting  $H_0$  and  $K_i$ , respectively,  $i = 1, \dots, s$ , when  $x$  is a realization of the random vector  $X = (X_1, \dots, X_N)$ . The

functions  $\varphi_i(x)$ ,  $i = 0, 1, \dots, s$ , have to satisfy the following conditions:

$$\varphi_i(x) \geq 0 \quad \text{for all } i, \quad \sum_{i=0}^s \varphi_i(x) = 1 \quad \text{for all } x.$$

Let  $P_0, P_{1,\Delta}, \dots, P_{s,\Delta}$ ;  $E_0, E_{1,\Delta}, \dots, E_{s,\Delta}$  be the probabilities and the expectations under  $H_0, K_1, \dots, K_s$ , respectively.

We say that a decision rule has the significance level  $1 - \alpha$  if

$$(2) \quad E_0 \varphi_0(x) = \int \varphi_0(x) dP_0(x) \geq 1 - \alpha.$$

We shall try to find a  $(1 - \alpha)$ -level decision rule  $\varphi(x)$  such that for some values of  $\Delta$

$$(3) \quad \sum_{i=1}^s E_{i,\Delta} \varphi_i(X) \geq \sum_{i=1}^s E_{i,\Delta} \varphi'_i(X)$$

for any other  $(1 - \alpha)$ -level decision rule  $\varphi'(x) = \{\varphi'_0(x), \varphi'_1(x), \dots, \varphi'_s(x)\}$ .

**Definition.** A decision rule satisfying (3) is said to be optimal for the combined problem of testing and classification.

## II. A GENERALIZATION OF NEYMAN-PEARSON'S LEMMA

Assume that the probability measures  $P_0, P_1, \dots, P_s$  have the densities  $f_0(x), f_1(x), \dots, f_s(x)$  with respect to a  $\sigma$ -finite measure  $\mu$  defined on the space  $\mathcal{X}$  of the sample values  $x = (x_1, \dots, x_N)$ .

Denote the expectations with respect to  $P_0, P_1, \dots, P_s$  by  $E_0, E_1, \dots, E_s$ . Consider a decision rule of the form:

$$(4) \quad \begin{aligned} \varphi_0(x) &= 1 - \xi_0(x), & 0 & \text{ if } \max_{1 \leq i \leq s} f_i(x) < C f_0(x), \\ \varphi_j(x) &= \xi_j(x), & 0 & \text{ if } \max_{1 \leq i \leq s} f_i(x) =, > f_j(x), \end{aligned}$$

for  $j = 1, \dots, s$ ,

where  $\xi_0(x), \xi_1(x), \dots, \xi_s(x)$  are arbitrary but subject to the condition that  $\varphi$  is a decision rule and  $C$  is some constant.

Let  $\varphi'$  be another decision rule. Then:

$$(i) \quad \text{If } E_0 \varphi'_0(X) \geq E_0 \varphi_0(X) \quad \text{then} \quad \sum_{i=1}^s E_i \varphi'_i(X) \leq \sum_{i=1}^s E_i \varphi_i(X).$$

(ii) If  $E_0 \varphi'_0(X) \geq E_0 \varphi_0(X)$  and  $\sum_{i=1}^s E_i \varphi'_i(X) = \sum_{i=1}^s E_i \varphi_i(X)$

then  $\varphi'$  has the form (4) a.e.. Furthermore,

$$E_0 \varphi'_0(X) = E_0 \varphi_0(X) \text{ unless } E_j \varphi_0(X) = 0 \text{ for all } j.$$

(iii) For every  $\alpha \in (0, 1)$  there is a decision rule of the form (4) with  $\xi_0(x)$  constant, say  $\xi_\alpha$ , such that

$$(5) \quad E_0 \varphi_0(X) = 1 - \alpha.$$

(See Theorem 1 in [3].)

### III. LOCALLY OPTIMAL RANK DECISION RULE

Let  $R = (R_1, \dots, R_N)$  be the vector of the ranks of  $X_1, \dots, X_N$  and  $r = (r_1, \dots, r_N)$  be a realization of  $R$ .

**Theorem 1.** Let  $H_0, K_1, \dots, K_s$  be the hypothesis and the alternatives defined by (1). Suppose that  $f(x, \theta)$  involved in (1) satisfies the following conditions:

$$(A_1) \quad \lim_{\theta \rightarrow 0} [f(x, \theta) - f(x)]/\theta = \dot{f}(x, 0)$$

holds and  $f(x, \theta)$  is absolutely continuous on some open interval containing the point 0.

$$(A_2) \quad \lim_{\theta \rightarrow 0} \int_{-\infty}^{\infty} |\dot{f}(x, \theta)| dx = \int_{-\infty}^{\infty} |\dot{f}(x, 0)| dx < \infty,$$

where  $\dot{f}(x, \theta) = \partial f(x, \theta)/\partial \theta$ .

Define the decision rule  $\varphi(R) = \{\varphi_0(R), \varphi_1(R), \dots, \varphi_s(R)\}$  by

$$(6) \quad \varphi_0(R) = 1, \xi_\alpha, 0 \text{ if } \max_{1 \leq i \leq s} T_i(R) < , = , > C_\alpha,$$

$$\varphi_j(R) = \xi_j(R), 0 \text{ if } \max_{1 \leq i \leq s} T_i(R) = , > T_j(R) \text{ for } j = 1, \dots, s,$$

where

$$(7) \quad T_i(r) = \sum_{k=1}^N C_{ik} E_0 \{ \dot{f}(X^{(r_k)}, 0) / f(X^{(r_k)}) \}$$

with  $X^{(1)} < X^{(2)} < \dots < X^{(N)}$  being the ordered observations  $X_1, X_2, \dots, X_N$ , and where  $C_\alpha, \xi_\alpha$ , are defined so that  $E_0 \varphi_0(R) = 1 - \alpha$ ,  $\xi_1(R), \dots, \xi_s(R)$  are arbitrary but subject to the condition that  $\varphi$  is a decision rule.

This decision rule is locally optimal within the class of all  $(1 - \alpha)$ -level rank decision rules in the sense that there exists an  $\varepsilon > 0$  such that  $\varphi$  maximizes

$\sum_{i=1}^s \mathbb{E}_i \varphi'_i(R)$  uniformly for all  $0 < \Delta \leq \varepsilon$  within the class  $\{\varphi'(R)\}$  of all possible decision rules depending only on the ranks of  $X_1, \dots, X_N$ .

*Proof.* First consider the combined problem of testing and classification of  $H_0$  against  $K_1, \dots, K_s$  with  $\Delta$  fixed. Put  $B_r = \{X; R = r\}$ . The sub- $\sigma$ -field generated by  $R$ , say  $\mathcal{B}_0$ , consists of all unions of such events, while the rest of the space  $\mathcal{X}$  where some coordinates coincide and  $R$  is not defined may be neglected, since its probability is zero under all distributions determined by densities.

We have, under  $H_0$ ,  $P_0\{B_r\} = P_0\{R = r\} = 1/N!$ .

Introduce on  $\mathcal{B}_0$  the so-called counting measure  $\mu$  which is defined by  $\mu(B_r) = 1$ . Then  $P_{i,\Delta}\{B_r\}$ ,  $i = 1, \dots, s$ ,  $P_0\{B_r\}$  may be regarded as a density of  $P_{i,\Delta}$  and  $P_0$  with respect to the counting measure  $\mu$  on the sub- $\sigma$ -field  $\mathcal{B}_0$ . Applying the above generalized Neyman - Pearson's Lemma we obtain the optimal decision rule within the class of all possible rules based on ranks for the combined problem of testing and classification with each  $\Delta$  fixed. The decision rule is given by:

$$(8) \quad \varphi_0(r) = 1, \xi_\alpha, 0 \quad \text{if} \quad \max_{1 \leq i \leq s} P_{i,\Delta}\{R = r\} < , = , > C'_\alpha,$$

$$\varphi_j(r) = \xi_j(r), 0 \quad \text{if} \quad \max_{1 \leq i \leq s} P_{i,\Delta}\{R = r\} = , > P_j\{R = r\} \quad \text{for} \quad j = 1, \dots, s.$$

On the other hand, if  $f(x, \theta)$  has the properties  $(A_1)$ ,  $(A_2)$  then, by the proof of Theorem 1 in [7], we obtain

$$P_{i,\Delta}\{R = r\} = 1/N! + (\Delta/N!) \sum_{k=1}^N C_{ik} \mathbb{E}_0[f(X^{(rk)}, 0)/f(X^{(rk)})] + o(\Delta)$$

$$= 1/N! + (\Delta/N!) T_i(r) + o(\Delta).$$

Consequently, there is an  $\varepsilon > 0$  such that (8) is equivalent to (6) for  $0 < \Delta \leq \varepsilon$ . This completes the proof.

#### IV. THE ASYMPTOTIC DETERMINATION OF CRITERIA

In general, the determination of the constants  $\xi_\alpha$  and  $C_\alpha$ , even the asymptotic determination, is very difficult. Therefore, let us try to make an asymptotic determination of the constants for some special cases, which are, however, important in practice, by examining the asymptotic behaviour of the distribution of the statistic  $\max_{1 \leq i \leq s} T_i(R)$ .

**1. The s-sample problem of slippage.** Let  $X_1, \dots, X_N$  be independent observations, and let  $f_1(x), \dots, f_N(x)$  be their densities, respectively, with respect to the Lebesgue measure.

Consider the hypothesis  $H_0$  and  $K_1, \dots, K_s$  where

$$(9) \quad H_0 : f_j(x) = f(x) \quad \text{for all } j = 1, \dots, N,$$

$$(10) \quad K_i : f(x) = f(x, \Delta) \quad \text{for all } j \in I_i, \\ = f(x) \quad \text{for all } j \notin I_i, \quad i = 1, \dots, s$$

with

$$I_1 = \{1, 2, \dots, n_1\}; \quad I_2 = \{n_1 + 1, n_1 + 2, \dots, n_1 + n_2\}, \dots, I_s = \\ = \{n_1 + \dots + n_{s-1} + 1, \dots, n_1 + \dots + n_s\}$$

where  $n_1 + \dots + n_s = N$ . Thus  $\text{card}(I_i) = n_i$ .

Assume that

$$(11) \quad \lim_{N \rightarrow \infty} n_i/N = \lambda_i \quad (0 < \lambda_i < 1 \text{ for all } i).$$

These alternatives are only a special case of the regression alternatives defined by (1) with

$$(12) \quad C_{ij} = 1 \quad \text{for all } j \in I_i, \\ = 0 \quad \text{for all } j \notin I_i; \quad i = 1, 2, \dots, s.$$

Applying Theorem 1 we obtain the locally optimal rank decision rule for the combined of testing and classification of  $H_0$  against  $K_1, \dots, K_s$ . The decision rule is defined by

$$(13) \quad \varphi_0(R) = 1, \xi_\alpha, 0 \quad \text{if } \max_{1 \leq i \leq s} T_i(R)/\sqrt{N} < , = , > C_\alpha, \\ \varphi_j(R) = \xi_j(R), 0 \quad \text{if } \max_{1 \leq i \leq s} T_i(R) = , > T_j(R) \quad \text{for } j = 1, \dots, s,$$

where

$$(14) \quad T_i(R) = \sum_{k \in I_i} E_0[f(X^{(rk)}, 0)/f(X^{(rk)})] = \sum_{k \in I_i} a_N(r_k, f)$$

with

$$(15) \quad a_N(k, f) = E \varphi(U^{(k)}, f), \quad k = 1, \dots, N, \\ \varphi(u, f) = f(F^{-1}(u), 0)/f(F^{-1}(u))$$

where  $U^{(1)} < \dots < U^{(N)}$  is the ordered sample from the uniform distribution on  $(0, 1)$ ,  $F(x)$  is the distribution function corresponding to  $f(x)$ ,  $F^{-1}(u) = \inf \{x; F(x) \geq u\}$ .

**Lemma 1.** Assume that

$$(16) \quad 0 < I(f) = \int_0^1 \varphi^2(u, f) du < \infty .$$

Then  $\{T_1(R)/\sqrt{N}, \dots, T_s(R)/\sqrt{N}\}$  is, under  $H_0$ , asymptotically degenerated  $s$ -variate normal with the mean vector zero and the covariance matrix  $\{\lambda_i(\delta_{ij} - \lambda_j)I(f)\}$  where  $\delta_{ij} = 1, 0$  as  $i = j, i \neq j$ , respectively.

*Proof.* Let  $Z_1, \dots, Z_N$  be the normal random vector with the mean vector zero and the covariance matrix defined in Lemma 1. According to Theorem V.2.1 in [2] the assertion of Lemma 1 will be proved if we can show that  $\sum_{i=1}^s \theta_i T_i(R)/\sqrt{N}$  converges in distribution to  $\sum_{i=1}^s \theta_i Z_i$  for any real numbers  $\theta_i$ 's.

Actually, it is easy to see that

$$\begin{aligned} E_0[T_i(R)] &= E Z_i = 0 \quad \text{for all } i, \\ \text{cov}(T_i(R)/\sqrt{N}, T_j(R)/\sqrt{N}) &\sim (n_i/N)(\delta_{ij} - n_j/N) N^{-1} \sum_{k=1}^N a_N^2(k, f) \end{aligned}$$

(see Theorem II.3.1.d in [2] and note that

$$\begin{aligned} \bar{a}_N &= N^{-1} \sum_{k=1}^N a_N(k, f) = \sum_{k=1}^N E\{\varphi(U_1, f) \mid R_1 = k\} P\{R_1 = k\} = \\ &= E \varphi(U_1, f) = \int_0^1 \varphi(u, f) du = \int_{-\infty}^{\infty} f(x, 0) dx = 0, \end{aligned}$$

by the conditions  $(A_1), (A_2)$ , where  $R_1, \dots, R_N$  are the ranks of the observations  $U_1, \dots, U_N$  from the uniform distribution on  $(0, 1)$ . Consequently,  $\text{cov}(T_i(R)/\sqrt{N}, T_j(R)/\sqrt{N})$  converges to  $\lambda_i(\delta_{ij} - \lambda_j)I(f) = \text{cov}(Z_i, Z_j)$  as  $N \rightarrow \infty$ . On the other hand, we have

$$\sum_{i=1}^s \theta_i T_i(R)/\sqrt{N} = \sum_{k=1}^N C_k(\theta) a_N(R_k, f) \quad \text{where} \quad C_k(\theta) = \sum_{i=1}^s \theta_i C_{ik}/\sqrt{N}$$

with  $C_{ik}$ 's given by (12). Furthermore,

$$\begin{aligned} \sum_{k=1}^N [(C_{ik} - \bar{C}_i)/\sqrt{N}][(C_{jk} - \bar{C}_j)/\sqrt{N}] &= (n_i/N)(\delta_{ij} - n_j/N) \rightarrow \lambda_i(\delta_{ij} - \lambda_j), \\ \max_{1 \leq k \leq N} (C_{ik} - \bar{C}_i)^2/N &\rightarrow 0 \quad \text{as } N \rightarrow \infty, \quad \text{with } \bar{C}_i = \sum_{k=1}^N C_{ik}/N \quad \text{for all } i, j = 1, \dots, s. \end{aligned}$$

Thus the conditions of Corollary 5 in [7] are fulfilled, and by this corollary

$\sum_{i=1}^s \theta_i T_i(R)/\sqrt{N}$  is asymptotically normal with the mean zero and the variance  $\sum_{i,j=1}^s \theta_i \theta_j \lambda_i(\delta_{ij} - \lambda_j)I(f)$ , which are the mean and the variance of the normally distributed random variable  $\sum_{i=1}^s \theta_i Z_i$ . Q.E.D.

Let us now return to the asymptotic determination of  $C_\alpha$  involved in (13) such that  $E_0 \varphi_0(R) = 1 - \alpha$ . It follows from Lemma 1 that

$$(17) \quad \lim_{N \rightarrow \infty} P\left\{ \max_{1 \leq i \leq s} T_i(R)/\sqrt{N} < C_\alpha \right\} = P\left\{ \max_{1 \leq i \leq s} Z_i < C_\alpha \right\}.$$

With no loss of generality we can suppose that  $I(f) = 1$ . The correlation coefficient between  $Z_i$  and  $Z_j$  is equal to

$$(18) \quad \rho_{ij} = -\lambda_i \lambda_j / [\lambda_i(1 - \lambda_i) \lambda_j(1 - \lambda_j)]^{1/2} < 0.$$

Hence, according to Slepian's result [10] and Bonferroni's inequality, we obtain:

$$(19) \quad 1 - \sum_{i=1}^s P\{Z_i/\sigma_i \geq C'_i\} \leq P\{Z_1 < C'_1\sigma_1, \dots, Z_s < C'_s\sigma_s\} \leq \prod_{i=1}^s P\{Z_i/\sigma_i < C'_i\}$$

with  $\sigma_i^2 = \text{var}(Z_i) = \lambda_i(1 - \lambda_i)$ .

Let  $\Phi(x)$  be the standardized normal distribution function. Then  $Z_i/\sigma_i$  has the distribution function  $\Phi(x)$ . Putting  $C' = C/\sigma_i$  we obtain

$$(20) \quad 1 - \sum_{i=1}^s [1 - \Phi(C/\sigma_i)] \leq P\{Z_1 < C, \dots, Z_s < C\} \leq \prod_{i=1}^s \Phi(C/\sigma_i).$$

Let  $C_\alpha, C_\alpha^{(1)}, C_\alpha^{(2)}$  be the constants defined so that

$$(21) \quad \begin{aligned} P\left\{ \max_{1 \leq i \leq s} Z_i < C_\alpha \right\} &= 1 - \alpha, \\ 1 - \sum_{i=1}^s [1 - \Phi(C_\alpha^{(1)}/\sigma_i)] &= 1 - \alpha, \\ \prod_{i=1}^s \Phi(C_\alpha^{(2)}/\sigma_i) &= 1 - \alpha; \end{aligned}$$

then we have

$$(22) \quad C_\alpha^{(1)} \geq C_\alpha \geq C_\alpha^{(2)}.$$

We can expect that, with  $\alpha$  sufficiently small,  $C_\alpha^{(1)}, C_\alpha^{(2)}$  differ from each other very little. Hence choosing, for example,  $C_\alpha = C_\alpha^{(1)}$  we obtain

$$(23) \quad P\left\{ \max_{1 \leq i \leq s} T_i(R)/\sqrt{N} < C_\alpha \right\} \doteq 1 - \alpha$$

if  $N$  is sufficiently large.

The following table provides a comparison of differences between  $C_\alpha^{(1)}$  and  $C_\alpha^{(2)}$  for the case where  $n_1 = n_2 = \dots = n_s$  (then  $\sigma_i^2 = \lambda_i(1 - \lambda_i) = (1 - 1/s)/s$ ) at the significance levels  $1 - \alpha = 95\%$  and  $1 - \alpha = 90\%$ . In this case the constants  $C_\alpha^{(1)}, C_\alpha^{(2)}$  are defined by the equations

$$(24) \quad \begin{aligned} \Phi[C_\alpha^{(1)} \cdot s/\sqrt{(s-1)}] &= 1 - \alpha/s, \\ \Phi[C_\alpha^{(2)} \cdot s/\sqrt{(s-1)}] &= (1 - \alpha)^{1/s}. \end{aligned}$$



Table of values  $C_\alpha^{(1)}$ ,  $C_\alpha^{(2)}$  with  $1 - \alpha = 95\%$ ,  $90\%$ , and  $s = 2$  (1) 10,  $n_1 = n_2 = \dots = n_s$

s	$1 - \alpha = 95\%$		$1 - \alpha = 90\%$	
	$C_\alpha^{(1)}$	$C_\alpha^{(2)}$	$C_\alpha^{(1)}$	$C_\alpha^{(2)}$
2	0.9800	0.9776	0.8224	0.8156
3	1.0073	1.0040	0.8652	0.8561
4	0.9735	0.9694	0.8487	0.8404
5	0.9305	0.9280	0.8210	0.8140
6	0.8994	0.8956	0.7972	0.7860
7	0.8628	0.8593	0.7653	0.7561
8	0.8306	0.8289	0.7422	0.7339
9	0.8040	0.8024	0.7238	0.7159
10	0.7728	0.7713	0.6979	0.6913

**2. The shift problem.** Consider the combined problem of testing and classification where we test the hypothesis  $H_0$  against the alternatives  $K_1, \dots, K_{N-1}$  defined as follows:

Let  $X_1, \dots, X_N$  be independent random observations, which have the absolutely continuous distribution functions with the densities  $f_1(x), \dots, f_N(x)$ , respectively. Let

$$H_0 : f_1(x) = \dots = f_N(x) = f(x),$$

and let  $K_i, i = 1, \dots, N - 1$ , be the alternatives under which the shift in a parameter involved in the distribution function of  $X$ 's occurs at the  $i$ -th time point. That is, the alternatives are defined by

$$(25) \quad \begin{aligned} K_i : f_1(x) = \dots = f_i(x) = f(x), \\ f_{i+1}(x) = \dots = f_N(x) = f(x, \Delta), \end{aligned}$$

where  $f(x, 0) = f(x)$ .

Suppose that  $f(x, \theta)$  satisfies the conditions  $(A_1), (A_2)$  of Theorem 1. The alternatives have the form of the regression alternatives considered in Theorem 1 with the regression constants defined by

$$(26) \quad C_{ij} = 0, \quad 1 \text{ if } j \leq i, \quad j \geq i + 1, \quad \text{respectively, } i = 1, \dots, N - 1.$$

Applying Theorem 1 we obtain the locally optimal decision rule at the significance level  $1 - \alpha$ . The decision rule is given by

$$(27) \quad \begin{aligned} \varphi_0(R) = 1, \quad \xi_\alpha, \quad 0 \quad \text{if } A_N^{-1} \max_i T_i(R) < , = , > C_\alpha, \\ \varphi_j(R) = \xi_j(R), \quad 0 \quad \text{if } \max_i T_i(R) = , > T_j(R) \quad \text{for } j = 1, \dots, N - 1, \end{aligned}$$

where  $T_i(R)$  are defined by

$$(28) \quad T_i(R) = \sum_{k=i+1}^N a_N(R_k, f)$$

with  $a_N(j, f)$  defined by (15) and where

$$(29) \quad A_N^2 = \sum_{j=1}^N a_N^2(j, f).$$

In order to determine asymptotically  $C_\alpha$  so that  $E_0 \varphi_0(R) = 1 - \alpha$ , let us prove the following lemma:

Consider the stochastic process

$$(30) \quad T_{N,t}(R) = \sum_{j=1}^N C_N(j, t) a_N(R_j, f)$$

where  $0 \leq t \leq 1$  and

$$(31) \quad \begin{aligned} C_N(j, t) &= 0 && \text{if } j \leq tN, \\ &= j - tN && \text{if } tN \leq j < tN + 1, \\ &= 1 && \text{if } tN + 1 \leq j. \end{aligned}$$

Then  $T_{N,t}(R)$  determines a probability distribution on the space  $(Z, \mathcal{C})$  where  $Z$  is the space of all continuous functions on  $[0, 1]$  with the usual metric

$$\|z_1 - z_2\| = \max_{0 \leq t \leq 1} |z_1(t) - z_2(t)|, \quad z_1, z_2 \in Z$$

and  $\mathcal{C}$  denotes the sigma-field of Borel subsets of  $Z$ , i.e. the smallest sigma-field containing all open subsets (see Sections V.3.1 and V.3.5 in [2]).

**Lemma 2.** *Assume that the function  $\varphi(u, f)$  given by (15) is square integrable on  $(0, 1)$ , non-constant,*

$$\int_0^1 \varphi^2(u, f) du < \infty,$$

and that

$$(32) \quad N^{-1} \max_{1 \leq j \leq N} a_N^2(j, f) \rightarrow 0.$$

Then the stochastic process  $A_N^{-1} T_{N,t}(R)$  converges, under  $H_0$ , in distribution in  $(Z, \mathcal{C})$  to the Brownian bridge  $z_\omega(t)$ .

Proof. First note that the stochastic process may be written in the form

$$(33) \quad T_{N,t}(R) = \sum_{j=1}^N C_N(D_j, t) a_N(j, f)$$

where  $D_1, \dots, D_N$  are the antiranks of  $X_1, \dots, X_N$  defined as follows:

$$D_j = k \quad \text{if and only if} \quad R_k = j.$$

The vector of antiranks  $(D_1, \dots, D_N)$  has, under  $H_0$ , the same distribution as  $(R_1, \dots, R_N)$ , i.e.  $(D_1, \dots, D_N)$  is also uniformly distributed. We observe that the stochastic process  $A_N^{-1} T_{N,t}(R)$  takes on the form of the stochastic process given by (2) of Section V.3.5. in [2], where our  $a_N(j, f)$ ,  $C_N(D_j, t)$  play the role of Hájek - Šidák's  $C_j - \bar{C}$ ,  $a_N(R_j, t)$ , respectively, since

$$\sum_{j=1}^N a_N(j, f) = N \int_0^1 \varphi(u, f) du = N \int_{-\infty}^{\infty} f(x, 0) dx = 0,$$

by the conditions  $(A_1)$ ,  $(A_2)$ .

Note that, by (32),

$$(34) \quad A_N^{-2} \max_j a_N^2(j, f) \sim \max_j a_N(j, f)/N \int_0^1 \varphi^2(u, f) du \rightarrow 0$$

(see (18) of Theorem V.1.4.b in [2]), hence the conditions of Theorem V.3.5 in [2] are satisfied and it follows from the cited theorem that the stochastic process  $T_{N,t}(R)/A_N$  converges in distribution in  $(Z, \mathcal{C})$  to the Brownian bridge  $z_\omega(t)$ . Q.E.D.

Let us now return to the problem of asymptotic determination of  $C_\alpha$  such that  $E_0 \varphi_0(R) = 1 - \alpha$ . Note that

$$T_{N,0}(R) = \sum_{j=1}^N a_N(R_j, f) = 0,$$

$$T_{N,t}(R) = \sum_{j=k+1}^N a_N(R_j, f) + (k - tN) a_N(R_k, f)$$

for all  $t \in [(k-1)/N, k/N]$ ,  $k = 1, \dots, N$ ; therefore

$$(35) \quad \max_{0 \leq t \leq 1} T_{N,t}(R) = \max \{0, T_1(R), \dots, T_{N-1}(R)\}.$$

It follows from (35) that if  $C_\alpha \geq 0$  then

$$(36) \quad \lim_{N \rightarrow \infty} P \left\{ \max_{1 \leq i \leq N-1} T_i(R)/A_N < C_\alpha \right\} =$$

$$= \lim_{N \rightarrow \infty} P \left\{ \max_{0 \leq t \leq 1} T_{N,t}(R)/A_N < C_\alpha \right\} =$$

$$= P \left\{ \max_{0 \leq t \leq 1} z_\omega(t) < C_\alpha \right\} = 1 - \exp(-2C_\alpha^2)$$

(see, for example, Doob [1]). Consequently, defining

$$(37) \quad C_\alpha = [(-1/2) \ln \alpha]^{1/2} \quad \text{for} \quad 0 < \alpha < 1,$$

we obtain from (36)

$$(38) \quad E_0 \varphi_0(R) \approx P\left\{ \max_{1 \leq i \leq N-1} T_i(R)/A_N < C_\alpha \right\} \approx 1 - \alpha$$

for  $N$  sufficiently large.

**Remark.** The condition (32) is always satisfied whenever  $\varphi(u, f)$  is bounded. The following lemma states that the condition (32) is fulfilled under rather smooth restriction placed on  $\varphi(u, f)$  which generates the scores  $a_N(j, f)$ .

**Lemma 3.** *Assume that the function  $\varphi(u)$ ,  $0 < u < 1$ , may be expressed as the finite sum of monotone, square integrable functions. Then the following relations hold for the scores  $a_N^q(j) = E \varphi(U^{(j)})$  and the so-called approximate scores  $a_N(j) = \varphi(j/(N+1))$ :*

$$(39) \quad N^{-1} \max_{1 \leq j \leq N} [a_N^q(j)]^2 \rightarrow 0,$$

$$(40) \quad N^{-1} \max_{1 \leq j \leq N} a_N^2(j) \rightarrow 0.$$

**Proof.** First, let us prove the relation (40) for the function  $\varphi$  which is supposed to be monotone, square integrable. We may also assume naturally that  $\varphi$  is non-decreasing and that

$$\lim_{u \rightarrow 0} \varphi(u) < 0, \quad \lim_{u \rightarrow 1} \varphi(u) > 0.$$

In such a case we have

$$\varphi(1/(N+1)) < 0, \quad \varphi(N/(N+1)) > 0$$

for  $N$  large enough and

$$(41) \quad N^{-1} \max_j (a_N^2(j)) = ((N+1)/N) \max \left\{ \frac{\varphi^2(1/(N+1))}{(N+1)}, \frac{\varphi^2(N/(N+1))}{(N+1)} \right\} \leq \\ \leq ((N+1)/N) \max \left\{ \int_0^{1/(N+1)} \varphi^2(u) du, \int_{N/(N+1)}^1 \varphi^2(u) du \right\} \rightarrow 0$$

since

$$\int_0^1 \varphi^2(u) du < \infty.$$

Consider the case where

$$\varphi(u) = \sum_{i=1}^r \varphi_i(u)$$

with  $\varphi_i(u)$  monotone, square integrable. Then

$$N^{-1} \max_{1 \leq j \leq N} a_N^2(j) = N^{-1} \max_{1 \leq j \leq N} \left[ \sum_{i=1}^r \varphi_i(j/(N+1)) \right]^2 \leq r \sum_{i=1}^r N^{-1} \max_{1 \leq j \leq N} \varphi_i^2(j/(N+1)) \rightarrow 0$$

by the above result. Let  $[y]$  denote the entier of real number  $y$ .

In order to prove (39), note that, according to Theorem V.1.4.b and Lemma V.1.6.a in [2],

$$\begin{aligned} \int_0^1 [a_N^g(1 + [uN]) - a_N(1 + [uN])]^2 du &\leq 2 \int_0^1 [a_N^g(1 + [uN]) - \varphi(u)]^2 du + \\ &+ 2 \int_0^1 [a_N(1 + [uN]) - \varphi(u)]^2 du \rightarrow 0. \end{aligned}$$

It follows from this that

$$\begin{aligned} N^{-1} \max_j [a_N^g(j)]^2 &\leq 2N^{-1} \max_j [a_N^g(j) - a_N(j)]^2 + 2N^{-1} \max_j a_N^2(j) \leq \\ &\leq 2N^{-1} \sum_{j=1}^N [a_N^g(j) - a_N(j)]^2 + 2N^{-1} \max_j a_N^2(j) = \\ &= \int_0^1 [a_N^g(1 + [uN]) - a_N(1 + [uN])]^2 du + 2N^{-1} \max_{1 \leq j \leq N} a_N^2(j) \rightarrow 0. \end{aligned}$$

## V. LOCALLY OPTIMAL RANK DECISION RULE FOR TESTING THE HYPOTHESIS WITH SYMMETRIC DENSITY

Let us consider the combined problem of testing and classification where the density under the hypothesis is symmetric.

Suppose that the independent observations  $X_1, \dots, X_N$  have the densities  $f_1(x), \dots, f_N(x)$  with respect to the Lebesgue measure. Let  $H_0^*$  and  $K_1^*, \dots, K_s^*$  be the hypothesis and the alternatives where

$$(42) \quad \begin{aligned} H_0^* : f_1(x) &= \dots = f_N(x) = f(x) \quad \text{with} \quad f(x) = f(|x|), \\ K_i^* : f_1(x) &= f(x, \Delta C_{i1}), \dots, f_N(x) = f(x, \Delta C_{iN}) \end{aligned}$$

with  $f(x, 0) = f(x)$  and  $i = 1, \dots, s$ .

Denote the probability measures and the expectations under  $H_0^*, K_1^*, \dots, K_s^*$  by  $P_0^*, P_{1,\Delta}^*, \dots, P_{s,\Delta}^*$ ;  $\mathbf{E}_0^*, \mathbf{E}_{1,\Delta}^*, \dots, \mathbf{E}_{s,\Delta}^*$  and denote the ranks of  $|X_1|, \dots, |X_N|$  by  $R_1^+, \dots, R_N^+$ . Let  $r = (r_1, \dots, r_N)$ ,  $v = (v_1, \dots, v_N)$  be a realization of the vector of ranks  $R^+ = (R_1^+, \dots, R_N^+)$  and the vector sign  $X = (\text{sign } x_1, \dots, \text{sign } x_N)$ .

**Theorem 2.** *Suppose that the function  $f(x, \theta)$  involved in  $K_i^*$  satisfies the following conditions:*

$$(B 1) \quad \lim_{\theta \rightarrow 0} [f(x, \theta) - f(x)]/\theta = f(x, 0) \quad a.e..$$

Further, there exist two functions  $t(x)$  defined only for  $x \geq 0$  and  $u(x)$  ( $u(x)$  is not necessarily defined for  $x \neq \pm 1$ ) such that  $f(x, 0)$  may be expressed in the form:  $f(x, 0) = u(\text{sign } x) t(|x|)$ . Besides it  $f(x, \theta)$  is supposed to be absolutely continuous in  $\theta$  on some interval containing the point zero.

$$(B 2) \quad \lim_{\theta \rightarrow 0} \int_{-\infty}^{\infty} |f(x, \theta)| dx = \int_{-\infty}^{\infty} |f(x, 0)| dx < \infty$$

with  $f(x, \theta) = \partial f(x, \theta) / \partial \theta$ .

Define a  $(1 - \alpha)$ -level rank decision rule by

$$(43) \quad \begin{aligned} \varphi_0(R^+, \text{sign } X) &= 1, \xi_\alpha, & 0 & \text{ if } \max_{1 \leq i \leq s} T_i(R^+, \text{sign } X) < , = , > C_\alpha, \\ \varphi_j(R^+, \text{sign } X) &= \xi_j(R^+, \text{sign } X), 0 & \text{ if } \max_{1 \leq i \leq s} T_i(R^+, \text{sign } X) = , > T_j(R^+, \text{sign } X) \end{aligned}$$

where

$$(44) \quad T_j(r, \text{sign } X) = \sum_{k=1}^N C_{jk} u(\text{sign } X_k) E_0^* [t(|X|^{(r_k)}) / f(|X|^{(r_k)})]$$

for  $j = 1, \dots, s$ .

Then there exists an  $\varepsilon > 0$  such that

$$\sum_{i=1}^s E_{i,\Delta}^* \varphi_i(R^+, \text{sign } X)$$

is maximum within the class of all  $(1 - \alpha)$ -level decision rules depending only on  $R^+$  and  $\text{sign } X$  for all  $0 < \Delta \leq \varepsilon$ .

Proof. Note that  $R^+$  and  $\text{sign } X$  are mutually independent under  $H_0^*$  and  $P_0^* \{R^+ = r, \text{sign } X = v\} = 1 / (N! 2^N)$ , hence, applying the generalized Neyman - Pearson's Lemma, we obtain the optimal decision rule within the class of all  $(1 - \alpha)$ -level decision rules depending only on  $R^+$  and  $\text{sign } X$  for the combined problem of testing and classification of  $H_0^*$  against  $K_1^*, \dots, K_s^*$  with each  $\Delta$  fixed. The decision rule is defined by:

$$(45) \quad \begin{aligned} \varphi_0(r, v) &= 1, \xi_\alpha, & 0 & \text{ if } \max_{1 \leq i \leq s} P_{i,\Delta}^* \{R^+ = r, \text{sign } X = v\} < , = , > C_\alpha, \\ \varphi_j(r, v) &= \xi_j(r, v), 0 & \text{ if } \max_{1 \leq i \leq s} P_{i,\Delta}^* \{R^+ = r, \text{sign } X = v\} \\ & & & = , > P_{j,\Delta}^* \{R^+ = r, \text{sign } X = v\} \end{aligned}$$

for  $j = 1, \dots, s$ .

In the same way as in the proof of Theorem 2 in [7] we easily obtain

$$\lim_{\Delta \rightarrow 0} [2^N N! P_{i,\Delta}^* \{R^+ = r, \text{sign } X = v\} - 1] / \Delta = T_i(r, v).$$

Consequently there exists an  $\varepsilon > 0$  such that (45) is equivalent to (43) for all  $0 < \Delta \leq \varepsilon$ . Q.E.D.

**Corollary 1.** Put in (42)  $f(x, \theta) = f(x - \theta)$  and suppose that

(B 1\*)  $f(x)$  is absolutely continuous and  $f(x) = f(|x|)$ ,

(B 2\*)  $\int_{-\infty}^{\infty} |f'(x)| dx < \infty$  where  $f'(x)$  denotes the a.e. derivative of  $f(x)$ .

Then the rank decision rule defined by (43) with (44) replaced by

$$(46) \quad T_j(r, \text{sign } X) = \sum_{k=1}^N C_{jk} \text{sign } X_k \mathbf{E}_0^*[-f'(|X|^{(r_k)})/f(|X|^{(r_k)})]$$

is locally optimal within the class of all  $(1 - \alpha)$ -level decision rules depending only on  $R^+$  and sign  $X$  for the combined problem of testing and classification of  $H_0^*$  against  $K_1^*, \dots, K_s^*$ .

*Proof.* It is easy to verify that the conditions (B 1), (B 2) are satisfied with  $u(x) = x$ ,  $t(x) = f'(x)$  provided the conditions (B 1\*), (B 2\*) hold, since  $f'(x) = (\text{sign } x) \cdot f'(|x|)$ . Consequently, Corollary 1 follows from Theorem 2.

**Corollary 2.** Put in (42)  $f(x, \theta) = \exp(-\theta)f(x \exp(-\theta))$  and suppose that the condition (B 1\*) and

$$(B 2^{**}) \quad \int_{-\infty}^{\infty} |x f'(x)| dx < \infty$$

hold. Then the rank decision rule defined by (43) with (44) replaced by

$$(47) \quad T_j(r, \text{sign } X) = \sum_{k=1}^N C_{jk} \mathbf{E}_0^*[-1 - |X|^{(r_k)} f'(|X|^{(r_k)})/f(|X|^{(r_k)})] \\ = T_j^+(r), \quad \text{say, for } j = 1, \dots, s,$$

is locally optimal in the sense described in Corollary 1.

*Proof.* Suppose that the conditions (B 1\*) and (B 2\*\*) hold, then (B 1) and (B 2) are satisfied with  $u(x) = 1$ ,  $t(x) = -1 - x f'(x)/f(x)$  since  $f(x, 0) = f(|x|, 0) = -1 - x f'(|x|)/f(|x|)$ . Consequently, the assertion of Corollary 2 follows from Theorem 2.

*Remark.* It is easy to verify that (46), (47) may be written in the form

$$(48) \quad T_j(r, \text{sign } X) = \sum_{k=1}^N C_{jk} \text{sign } X_k a_{1N}^+(r_k, f),$$

$$(49) \quad T_j^+(r) = \sum_{k=1}^N C_{jk} a_{2N}^+(r_k, f),$$

where

$$a_{1N}^+(k, f) = E \varphi_1(\frac{1}{2}U^{(k)} + \frac{1}{2}, f) \quad \text{with} \quad \varphi_1(u, f) = -f'(F^{-1}(u)) [f(F^{-1}(u))]^{-1},$$

$$a_{2N}^+(k, f) = E \varphi_2(\frac{1}{2}U^{(k)} + \frac{1}{2}, f) \quad \text{with} \quad \varphi_2(u, f) =$$

$$= -1 - F^{-1}(u) f'(F^{-1}(u)) / f(F^{-1}(u)),$$

for  $k = 1, \dots, N$  and for  $0 < u < 1$ .

In order to determine asymptotically the constant  $C_\alpha$  such that the rank decision rule given by (43) with  $T_j(r, \text{sign } X)$  defined by (48), (49) has the significance level  $1 - \alpha$ , let us note that if  $K_1^*, \dots, K_s^*$  are the  $s$ -sample slippage or shift alternatives, i.e. the regression constants  $C_{jk}$  take on the form (12) or (26), then the method of the asymptotic determination of  $C_\alpha$  in Paragraph IV remains valid for the rank decision rule defined by (43) or (49) since  $R^+$  is, under  $H_0^*$ , uniformly distributed.

As to the signed rank decision rule defined by (43) and (48), it is difficult to determine  $C_\alpha$  for the regression constants of the form (26). On the contrary, it is easy to determine  $C_\alpha$  for  $C_{jk}$  of the form (12).

Actually, suppose that  $C_{jk}$  take on the form (12), then (48) reduces to

$$(50) \quad T_j(r, \text{sign } X) = \sum_{k \in I_j} \text{sign } X_k a_{1N}^+(r_k, f).$$

We have, for  $i \neq j$

$$\begin{aligned} & \text{cov}(T_i(R^+, \text{sign } X), T_j(R^+, \text{sign } X)) = \\ & = \sum_{m \in I_i} \sum_{k \in I_j} E_0^* \{ \text{sign } X_m \text{sign } X_k a_{1N}^+(R_m^+, f) a_{1N}^+(R_k^+, f) \} = 0 \end{aligned}$$

since  $\text{sign } X_m, \text{sign } X_k, R^+$  are mutually independent for  $m \neq k$  and  $E_0^* \text{sign } X_k = 0$  because  $f(x)$  is symmetric about zero. Furthermore it is easy to see that the joint distribution of the vector  $(T_1(R^+, \text{sign } X)/\sqrt{N}, \dots, T_s(R^+, \text{sign } X)/\sqrt{N})$  converges to the  $s$ -variate normal distribution with the mean zero and the covariance matrix  $\{\sigma_{ij}\}$  where  $\sigma_{ij} = 0$  for  $i \neq j$  and  $\sigma_{ii} = \lambda_i I(f)$  for all  $i, j = 1, \dots, s$ .

Consequently,

$$(51) \quad \lim_{N \rightarrow \infty} P \{ \max_{1 \leq j \leq s} T_j(R^+, \text{sign } X) / \sqrt{N} < C_\alpha \} =$$

$$= P \{ \max_{1 \leq j \leq s} Z'_j < C_\alpha \} = \prod_{j=1}^s P \{ Z'_j < C_\alpha \} = \prod_{j=1}^s \Phi(C_\alpha / \sqrt{(\lambda_j I(f))})$$

where  $Z'_1, \dots, Z'_s$  denote the normally distributed independent random variables with the mean zero and the variances  $\lambda_1 I(f), \dots, \lambda_s I(f)$ , respectively. It follows



from (51) that  $C_x$  may be defined so that

$$E_0^* \varphi_0(R^+, \text{sign } X) \approx P\left\{ \max_{1 \leq j \leq s} T_j(R^+, \text{sign } X) < C_x \right\} \approx 1 - \alpha$$

for  $N$  large enough.

Remark. Omitting the classification of  $K_1, \dots, K_s$  and of  $K_1^*, \dots, K_s^*$  we obtain rank tests from the locally optimal decision rules given by (6), (7) and (43), (44). The rank tests are defined as follows:

$$(52) \quad \psi(R) = 1 - \varphi_0(R) = 1, \xi_x, 0 \quad \text{if} \quad \max_{1 \leq i \leq s} T_i(R) >, =, < C_x,$$

$$(53) \quad \psi(R^+, \text{sign } X) = 1 - \varphi_0(R^+, \text{sign } X) = 1, \xi_x, 0 \quad \text{if} \\ \max_{1 \leq i \leq s} T_i(R^+, \text{sign } X) >, =, < C_x.$$

We expect that the rank tests for testing  $H_0, H_0^*$  against  $K_1, \dots, K_s$  and  $K_1^*, \dots, K_s^*$ , respectively, will have some good properties. However, the investigation of the properties of the above rank tests is out of the framework of this article.

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## Souhrn

### POŘADOVÁ ROZHODOVACÍ PROCEDURA PRO KOMBINOVANÝ PROBLÉM TESTOVÁNÍ A KLASIFIKACE

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Článek se týká problému testování hypotézy náhodnosti proti skupině regresních alternativ, kombinovaného s následujícím rozhodnutím, která z alternativ platí. Jsou navrženy pořadové rozhodovací procedury pro tento problém, které jsou lokálně optimální. V některých speciálních případech jsou též studována asymptotická rozložení testovacích statistik.

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