

Josef Niederle

Conditions for transitive principal tolerances

Czechoslovak Mathematical Journal, Vol. 39 (1989), No. 2, 380–381

Persistent URL: <http://dml.cz/dmlcz/102309>

Terms of use:

© Institute of Mathematics AS CR, 1989

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://dml.cz>

CONDITIONS FOR TRANSITIVE PRINCIPAL TOLERANCES

JOSEF NIEDERLE, Brno

(Received November 15, 1987)

By a *principal tolerance* on an algebra $\mathfrak{A} = (A, F)$ we mean the least compatible symmetric reflexive relation on \mathfrak{A} containing a given pair $[a, b] \in A \times A$. Such a relation exists for any pair $[a, b] \in A \times A$.

An algebra \mathfrak{A} is said to have *transitive (alias trivial) principal tolerances* if each principal tolerance on \mathfrak{A} is transitive, i.e. it is a principal congruence. A class of algebras \mathcal{V} is said to have *transitive principal tolerances* if any algebra in \mathcal{V} has transitive principal tolerances.

Let (*) and (**) denote the following systems of identities:

$$\begin{aligned}
 (*) \quad & \begin{cases} f_1(s(x_1, \dots, x_n), t(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g(u(x_1, \dots, x_n), v(x_1, \dots, x_n), x_1, \dots, x_n) \\ f_2(t(x_1, \dots, x_n), s(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g(v(x_1, \dots, x_n), u(x_1, \dots, x_n), x_1, \dots, x_n), \end{cases} \\
 (**) \quad & \begin{cases} f_1(t(x_1, \dots, x_n), s(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g_1(u(x_1, \dots, x_n), v(x_1, \dots, x_n), x_1, \dots, x_n) \\ f(s(x_1, \dots, x_n), t(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g_1(v(x_1, \dots, x_n), u(x_1, \dots, x_n), x_1, \dots, x_n) \\ f(t(x_1, \dots, x_n), s(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g_2(u(x_1, \dots, x_n), v(x_1, \dots, x_n), x_1, \dots, x_n) \\ f_2(s(x_1, \dots, x_n), t(x_1, \dots, x_n), x_1, \dots, x_n) = \\ = g_2(v(x_1, \dots, x_n), u(x_1, \dots, x_n), x_1, \dots, x_n). \end{cases}
 \end{aligned}$$

Theorem. Let \mathcal{V} be a variety of algebras. The following conditions are equivalent:

- (A) \mathcal{V} has transitive principal tolerances.
- (E) For every natural number n , every $(n + 2)$ -ary \mathcal{V} -polynomials f_1, g, f_2 and every n -ary \mathcal{V} -polynomials s, t, u, v such that (*) holds in \mathcal{V} there exist $(n + 2)$ -ary \mathcal{V} -polynomials g_1, f, g_2 such that (**) holds in \mathcal{V} .
- (F) For every natural number n , every $(n + 2)$ -ary \mathcal{V} -polynomials f_1, f_2 and every n -ary \mathcal{V} -polynomials s, t there exist $(n + 2)$ -ary \mathcal{V} -polynomials g_1, f, g_2

such that **(**)** holds in \mathcal{V} , where

$$(***) \begin{cases} u(x_1, \dots, x_n) \equiv f_1(s(x_1, \dots, x_n), t(x_1, \dots, x_n), x_1, \dots, x_n) \\ v(x_1, \dots, x_n) \equiv f_2(t(x_1, \dots, x_n), s(x_1, \dots, x_n), x_1, \dots, x_n). \end{cases}$$

Proof. For **(A)** \Leftrightarrow **(E)** see [1].

Troughout the proof, \mathbf{x} is a concise form for x_1, \dots, x_n .

(E) \Rightarrow **(F)**: Let **(E)** be true in \mathcal{V} . Let n be a natural number and f_1, f_2 arbitrary $(n+2)$ -ary \mathcal{V} -polynomials, s, t arbitrary n -ary \mathcal{V} -polynomials. Take $g(y, z, \mathbf{x}) \equiv y$ and u, v as in **(***)**. Since **(*)** is satisfied in \mathcal{V} , there exist $(n+2)$ -ary \mathcal{V} -polynomials g_1, f, g_2 such that **(**)** holds in \mathcal{V} . This proves statement **(F)**.

(F) \Rightarrow **(E)**: Let **(F)** be true in \mathcal{V} . Let $n, f'_1, g', f'_2, s', t', u', v'$ satisfy the assumptions of statement **(E)**. Inasmuch as $n, f_1 \equiv f'_1, f_2 \equiv f'_2, s \equiv s', t \equiv t'$ also satisfy the assumptions of statement **(F)**, there exist $(n+2)$ -ary \mathcal{V} -polynomials g_1, f, g_2 such that **(**)** holds in \mathcal{V} for u, v defined by **(***)**. Put

$g'_1(y, z, \mathbf{x}) \equiv g_1(g'(y, z, \mathbf{x}), g'(z, y, \mathbf{x}), \mathbf{x}), \quad g'_2(y, z, \mathbf{x}) \equiv g_2(g'(y, z, \mathbf{x}), g'(z, y, \mathbf{x}), \mathbf{x})$
and $f' \equiv f$. Since

$$u(\mathbf{x}) = g'(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \quad v(\mathbf{x}) = g'(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x})$$

are \mathcal{V} -identities, we obtain \mathcal{V} -identities

$$\begin{aligned} f'_1(t'(\mathbf{x}), s'(\mathbf{x}), \mathbf{x}) &= g_1(u(\mathbf{x}), v(\mathbf{x}), \mathbf{x}) = g_1(g'(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \\ &g'(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \mathbf{x}) \equiv g'_1(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \\ f'(s'(\mathbf{x}), t'(\mathbf{x}), \mathbf{x}) &= g_1(v(\mathbf{x}), u(\mathbf{x}), \mathbf{x}) = g_1(g'(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \\ &g'(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \mathbf{x}) \equiv g'_1(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \\ f'_2(t'(\mathbf{x}), s'(\mathbf{x}), \mathbf{x}) &= g_2(u(\mathbf{x}), v(\mathbf{x}), \mathbf{x}) = g_2(g'(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \\ &g'(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \mathbf{x}) \equiv g'_2(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \\ f'_2(s'(\mathbf{x}), t'(\mathbf{x}), \mathbf{x}) &= g_2(v(\mathbf{x}), u(\mathbf{x}), \mathbf{x}) = g_2(g'(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \\ &g'(u'(\mathbf{x}), v'(\mathbf{x}), \mathbf{x}), \mathbf{x}) \equiv g'_2(v'(\mathbf{x}), u'(\mathbf{x}), \mathbf{x}), \end{aligned}$$

proving **(E)**. Q.E.D.

In the case **(F)**, **(**)** with **(***)** should be read

$$\begin{aligned} f_1(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}) &= g_1(f_1(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}), f_2(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}), \mathbf{x}), \\ f(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}) &= g_1(f_2(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}), f_1(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}), \mathbf{x}), \\ f(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}) &= g_2(f_1(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}), f_2(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}), \mathbf{x}), \\ f_2(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}) &= g_2(f_2(t(\mathbf{x}), s(\mathbf{x}), \mathbf{x}), f_1(s(\mathbf{x}), t(\mathbf{x}), \mathbf{x}), \mathbf{x}). \end{aligned}$$

Reference

- [1] Niederle, J.: Conditions for trivial principal tolerances. Arch. Math. (Brno) 19 (1983), 145–152.

Author's address: Viniční 60, 615 00 Brno 15, Czechoslovakia.