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PERIODIC SOLUTIONS TO CERTAIN EVOLUTION INEQUALITIES

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INTRODUCTION

Let  $X$  be a real reflexive Banach space with norm  $\| \cdot \|$ . We denote by  $X^*$  the dual of  $X$  and by  $(v^*, v)$  the dual pairing between  $v^* \in X^*$  and  $v \in X$ .

Suppose we are given a real Hilbert space  $H$  with norm  $| \cdot |$  such that  $X$  is continuously and densely imbedded into  $H$ . Identifying  $H$  with its dual we get the continuous and dense imbedding  $H \subset X^*$ , and if  $w \in H$  and  $v \in X$ , the dual pairing  $(w, v)$  coincides with the scalar product of  $w$  and  $v$  in  $H$ .

Further, let  $\varphi : X \rightarrow (-\infty, +\infty]$  be a convex, lower semi-continuous functional,  $\varphi \not\equiv +\infty$ . Let  $D(\varphi)$  denote its effective domain, i.e.

$$D(\varphi) = \{v \in X : \varphi(v) < +\infty\}.$$

Let  $A : X \rightarrow X^*$  be a (possibly nonlinear) mapping. We then ask for a function  $u \in L^p(0, T; X)$  ( $0 < T < \infty$ ) such that

$$(1) \quad u' + Au + \partial\varphi(u) \ni f \text{ for a.a. } t \in [0, T], \quad u(0) = u(T)$$

where the derivative  $u' = du/dt$  is to be understood in the sense of vector-valued distributions,  $f$  being a given function. In particular, let  $X$  be a real Hilbert space, and let  $A$  and  $B$  be two linear bounded mappings from  $X$  into  $X^*$ . Under these assumptions we consider the problem of finding a function  $u \in L^2(0, T; X)$  such that

$$(2) \quad u'' + Au' + Bu + \partial\varphi(u') \ni f \text{ for a.a. } t \in [0, T], \\ u(0) = u(T), \quad u'(0) = u'(T).$$

Both in (1) and (2)  $\partial\varphi$  denotes the subdifferential mapping of  $\varphi$  (see e.g. [1], [4]).

The existence of a solution to the problem

$$(1') \quad u' + Mu + \omega u \ni f \text{ for a.a. } t \in [0, T], \quad u(0) = u(T)$$

where  $M$  is an  $m$ -accretive operator in a Banach space with uniformly convex dual, and  $\omega = \text{const} > 0$  has been proved in [1], [3]. The existence of a solution to (1') for  $\omega = 0$  has been established in [3] for  $M$  to be the subdifferential mapping of a convex, lower semi-continuous and coercive functional on a Hilbert space. For general maximal monotone and coercive mappings  $M$  in a Hilbert space the existence of a weak solution to (1') for  $\omega = 0$  has been proved in [4]. In [5], the authors have studied (1') for  $t$ -dependent  $M$ . An existence theorem for weak solutions to the problem (1) for a wide range of nonlinear mappings  $A$  can be found in [3].

Some results on the existence of a solution to special cases of (2) have been presented in [6].

In Section 1 of the present paper we prove the existence of a solution to (1) for  $A$  to be the sum of a monotone gradient operator and a certain "lower order" operator. Our method of proof consists in starting with a weak solution to (1) and proving its regularity then.

The existence of a solution to (2) is proved in Section 2. Following [1], [3] we replace (2) by a first order problem to which the theory of [1]–[4] applies ( $\omega > 0$ ). After establishing a-priori-estimates we are able to carry through the passage to limit  $\omega \rightarrow 0$ .

## SECTION 1

For  $v \in L^p(0, T; X)$  ( $1 < p < \infty$ ) we define

$$\Phi(u) = \begin{cases} \int_0^T \varphi(v(t)) \, dt & \text{if } \varphi(v(\cdot)) \in L^1(0, T), \\ +\infty & \text{otherwise.} \end{cases}$$

$\Phi$  is a convex, lower semi-continuous functional from  $L^p(0, T; X)$  into  $(-\infty, +\infty]$  (see [3], [4]). Let  $D(\Phi)$  denote the effective domain of  $\Phi$ .

Throughout this section we assume that  $2 \leq p < \infty$  and  $\tilde{A}v \in L^p(0, T; X^*)$  ( $1/p + 1/p' = 1$ ) for any  $v \in L^p(0, T; X)$ , where  $(\tilde{A}v)(t) = Av(t)$  for a.a.  $t \in [0, T]$ .<sup>1</sup>

We impose the following additional conditions upon  $A$ :

(1.1)  $A = A_1 + A_2$  where:  $A_1 : X \rightarrow X^*$  is monotone, there exists a functional  $F : X \rightarrow \mathbb{R}^1$  such that  $A_1 = \text{grad } F$ , and  $A_2 : X \rightarrow H$ ;

(1.2)  $\tilde{A}$  is pseudo-monotone<sup>2</sup>) and maps bounded sets into bounded sets;

<sup>1</sup>) Note that this condition can be verified when imposing certain continuity and boundedness conditions upon  $A$ .

<sup>2</sup>) Let  $X$  be a real Banach space with dual  $X^*$ , the dual pairing between  $X^*$  and  $X$  being denoted by  $\langle \cdot, \cdot \rangle$ . A mapping  $S : X \rightarrow X^*$  is called pseudo-monotone if for any sequence  $\{u_j\} \subset X$  such that  $u_j \rightarrow u$  weakly in  $X$  and  $\limsup \langle Su_j, u_j - u \rangle \leq 0$ , it follows that  $\langle Su, u - v \rangle \leq \liminf \langle Su_j, u_j - v \rangle$  for all  $v \in X$ .

(1.3) there exists  $v_0 \in D(\Phi)$  with  $v'_0 \in L^p(0, T; X^*)$  and  $v_0(0) = v_0(T)$  such that

$$\left[ \int_0^T (Av, v - v_0) dt + \Phi(v) \right] \|v\|_{L^p(0, T; X)}^{-1} \rightarrow +\infty \quad \text{as } v \in D(\Phi), \quad \|v\|_{L^p(0, T; X)} \rightarrow \infty.$$

We then have

**Theorem 1.** Let the conditions (1.1)–(1.3) be satisfied. Suppose that  $f = f_1 + f_2$  where

$$f_1 \in L^2(0, T; H), \quad f_2, f'_2 \in L^p(0, T; X^*).$$

Then there exists a solution  $u \in D(\Phi)$  to (1) such that

$$u \in C([0, T]; H), \quad u' \in L^2(0, T; H).$$

*Proof.* Based on the conditions (1.2), (1.3) we obtain from [3] the existence of a function  $u \in D(\Phi) \cap C([0, T]; H)$  such that

$$(1.4) \quad \int_0^T (v' + Au, v - u) dt + \Phi(v) - \Phi(u) \geq \int_0^T (f, v - u) dt$$

$$\forall v \in D(\Phi) \quad \text{with } v' \in L^p(0, T; X^*), \quad v(0) = v(T).$$

Moreover, it holds  $u(0) = u(T)$ .

Let  $\varepsilon > 0$ . We then consider the function

$$u_\varepsilon(t) = e^{-t/\varepsilon} z_\varepsilon + \frac{1}{\varepsilon} \int_0^t e^{(s-t)/\varepsilon} u(s) ds, \quad t \in [0, T]$$

where

$$z_\varepsilon = \frac{1}{\varepsilon(1 - e^{-T/\varepsilon})} \int_0^T e^{(s-T)/\varepsilon} u(s) ds.$$

In other words,  $u_\varepsilon$  solves the problem

$$u_\varepsilon(t) + \varepsilon u'_\varepsilon(t) = u(t) \quad \text{for a.a. } t \in [0, T], \quad u_\varepsilon(0) = u_\varepsilon(T).$$

The following properties of  $u_\varepsilon$  are readily verified (cf. [3]):

$$(1.5) \quad \Phi(u_\varepsilon) \leq \Phi(u) \quad \forall \varepsilon > 0;$$

(1.6) there exists a sequence of reals  $\varepsilon_j$  ( $\varepsilon_j > 0$  for  $j = 1, 2, \dots$ ) such that  $u_{\varepsilon_j} \rightarrow u$  weakly in  $L^p(0, T; X)$  as  $j \rightarrow \infty$ .

We insert  $v = u_\varepsilon$  in (1.4) and obtain

$$(1.7) \quad -\varepsilon \int_0^T |u'_\varepsilon|^2 dt - \varepsilon \int_0^T (Au, u'_\varepsilon) dt + \Phi(u_\varepsilon) - \Phi(u) \geq -\varepsilon \int_0^T (f, u'_\varepsilon) dt \quad \forall \varepsilon > 0.$$

By (1.1),

$$-\int_0^T (Au, u'_\varepsilon) dt \leq \left\{ \int_0^T |A_2 u|^2 dt \right\}^{1/2} \left\{ \int_0^T |u'_\varepsilon|^2 dt \right\}^{1/2}$$

for all  $\varepsilon > 0$ . Observing (1.5) one concludes from (1.7) that

$$\int_0^T |u'_\varepsilon|^2 dt \leq c_1 \left[ 1 + \int_0^T (f, u'_\varepsilon) dt \right] \quad \forall \varepsilon > 0$$

where  $c_1 = \text{const} > 0$ . Taking into account that

$$|u_\varepsilon(t)| \leq \|u\|_{C([0, T]; H)} \quad \forall \varepsilon > 0, \quad \forall t \in [0, T],$$

and that

$$\|u_\varepsilon\|_{L^p(0, T; X)} \leq c_2(1 + \|u\|_{L^p(0, T; X)}) \quad \forall 0 < \varepsilon \leq 1$$

where  $c_2 = \text{const} > 0$ , we find

$$\int_0^T (f_2, u'_\varepsilon) dt \leq \text{const} \quad \forall 0 < \varepsilon \leq 1.$$

Thus

$$\int_0^T |u'_\varepsilon|^2 dt \leq \text{const} \quad \forall 0 < \varepsilon \leq 1.$$

But the latter estimate together with (1.6) implies that  $u'$  exists and belongs to  $L^2(0, T; H)$ .

Let  $\bar{v} \in D(\Phi)$  with  $\bar{v}' \in L^p(0, T; X^*)$ ,  $\bar{v}(0) = \bar{v}(T)$  be given. Let  $0 < \lambda < 1$ . Replacing  $v$  in (1.4) by  $(1 - \lambda)u + \lambda\bar{v}$ , dividing by  $\lambda$  and letting  $\lambda \rightarrow 0$  one obtains

$$(1.8) \quad \int_0^T (u' + Au, \bar{v} - u) dt + \Phi(\bar{v}) - \Phi(u) \geq \int_0^T (f, \bar{v} - u) dt.$$

Let  $v \in D(\Phi)$ . Set, for any  $\varepsilon > 0$ ,

$$v_\varepsilon(t) = e^{-t/\varepsilon} w_\varepsilon + \frac{1}{\varepsilon} \int_0^t e^{(s-t)/\varepsilon} v(s) ds, \quad t \in [0, T]$$

where

$$w_\varepsilon = \frac{1}{\varepsilon(1 - e^{-T/\varepsilon})} \int_0^T e^{(s-T)/\varepsilon} v(s) ds.$$

Let  $\{\varepsilon_j\}$  ( $\varepsilon_j > 0$  for  $j = 1, 2, \dots$ ) be a sequence of reals such that  $v_{\varepsilon_j} \rightarrow v$  weakly in  $L^p(0, T; X)$  as  $j \rightarrow \infty$ . Inserting  $v = v_{\varepsilon_j}$  in (1.8) and using that  $\lim \Phi(v_{\varepsilon_j}) \geq \Phi(v)$  we conclude from (1.8) after passing to limit that

$$\int_0^T (u' + Au, v - u) dt + \Phi(v) - \Phi(u) \geq \int_0^T (f, v - u) dt.$$

Since this inequality is true for any  $v \in D(\Phi)$  we get the first relation in (1).

SECTION 2

Let  $X = V$  be a real Hilbert space.

Let  $A$  and  $B$  be linear bounded mappings from  $V$  into  $V^*$  which satisfy the following conditions:

$$(2.1) \quad (Av, v) \geq \alpha_0 \|v\|^2 \quad \forall v \in V, \quad \alpha_0 = \text{const} > 0;$$

$$(2.2) \quad (Bv, v) \geq \beta_0 \|v\|^2 \quad \forall v \in V, \quad \beta_0 = \text{const} > 0,$$

$$(Bu, v) = (Bv, u) \quad \forall u, v \in V.$$

We further assume that

$$(2.3) \quad \partial\Phi \text{ maps bounded sets into bounded sets.}$$

The aim of this section is to prove

**Theorem 2.** *Let  $f \in L^2(0, T; H)$  with  $f' \in L^2(0, T; H)$  and  $f(0) = f(T)$  be given. Then there exists a function  $u \in C([0, T]; V)$  such that*

$$(2.4) \quad u' \in D(\Phi), \quad u'' \in L^2(0, T; V^*),$$

$$(2.5) \quad \int_0^T (u'' + Au' + Bu, v - u') dt + \Phi(v) - \Phi(u') \geq \\ \geq \int_0^T (f, v - u') dt \quad \forall v \in D(\Phi),$$

$$(2.6) \quad u(0) = u(T), \quad u'(0) = u'(T).$$

**Proof.** 1° Approximate solutions. Set  $\mathbf{X} = V \times H$ .  $\mathbf{X}$  is a Hilbert space with respect to the scalar product  $\langle \mathbf{U}_1, \mathbf{U}_2 \rangle = (Bu_1, u_2) + (v_1, v_2)$  where  $\mathbf{U}_i = \{u_i, v_i\}$ ,  $u_i \in V$ ,  $v_i \in H$  ( $i = 1, 2$ ).

We define

$$D(\mathbf{M}) = \{\{u, v\} \in V \times H : v \in D(\varphi), (Bu + Av + \partial\varphi(v)) \cap H \neq \emptyset\},$$

and

$$\mathbf{M}(\mathbf{U}) = \{-v, (Bu + Av + \partial\varphi(v)) \cap H\}$$

for any  $\mathbf{U} \in D(\mathbf{M})$  ( $\mathbf{U} = \{u, v\}$ ).

It is readily seen that  $\mathbf{M}$  is monotone in  $\mathbf{X}$ . Moreover,  $\mathbf{M}$  is maximal monotone in  $\mathbf{X}$  (i.e., equivalently,  $R(I + \mathbf{M}) = \mathbf{X}$ ). Indeed, let  $\{g, h\} \in \mathbf{X}$  be given. Note first of all that the mapping  $I + A + B$  is monotone, hemi-continuous, bounded and

coercive from  $V$  into  $V^*$ . Since  $\partial\varphi$  is maximal monotone from  $V$  into  $2^{V^*}$  we get  $R(I + A + B + \partial\varphi) = V^*$  (cf. e.g. [1]). Hence there exists an element  $v \in D(\partial\varphi)$  such that

$$v + Av + Bv + \partial\varphi(v) \ni h - Bg.$$

Setting  $v + g = u$  it follows

$$u - v = g,$$

$$v + Bu + Av + \partial\varphi(v) \ni h.$$

Taking into account that  $h - v \in H$  we reach the desired assertion.

Thus, setting  $F = \{0, f\}$  for a.a.  $t \in [0, T]$ , we obtain from [1]–[4] for any  $\omega > 0$  the existence and uniqueness of a function  $\mathbf{U} \in C([0, T]; \mathbf{X})^3$  which satisfies

$$(2.7) \quad \mathbf{U}(t) \in D(\mathbf{M}) \quad \forall t \in [0, T], \quad \mathbf{U}' \in L^\infty(0, T; \mathbf{X}),$$

$$(2.8) \quad \mathbf{U}' + \mathbf{M}(\mathbf{U}) + \omega\mathbf{U} \ni F \quad \text{for a.a. } t \in [0, T],$$

$$(2.9) \quad \mathbf{U}(0) = \mathbf{U}(T).$$

Equivalently, when writing  $\mathbf{U} = \{u, v\}$  we have  $u \in C([0, T]; V)$ ,  $v \in C([0, T]; H)$  and

$$v(t) \in D(\varphi) \quad \forall t \in [0, T],$$

$$[Bu(t) + Av(t) + \partial\varphi(v(t))] \cap H \neq \emptyset \quad \forall t \in [0, T],$$

$$(2.7') \quad u' \in L^\infty(0, T; V), \quad v' \in L^\infty(0, T; H),$$

$$(2.8') \quad u' - v + \omega u = 0 \quad \text{for a.a. } t \in [0, T],$$

$$(2.8'') \quad v' + Av + Bu + \partial\varphi(v) + \omega v \ni f \quad \text{for a.a. } t \in [0, T],$$

$$(2.9') \quad u(0) = u(T), \quad v(0) = v(T).$$

By (2.7') and (2.8'),  $v \in L^\infty(0, T; V)$ . Setting  $w = f - v' - Av - Bu - \omega v$  for a.a.  $t \in [0, T]$ , we have  $w \in \partial\varphi(v)$  for a.a.  $t \in [0, T]$  and  $w \in L^2(0, T; V^*)$ . Further, observing that  $v$  is weakly continuous from  $[0, T]$  into  $V^4$  one easily verifies that the function  $t \mapsto \varphi(v(t))$  is integrable on  $[0, T]$ , i.e.  $v \in D(\Phi)$ . We now infer from (2.8'') that  $w \in \partial\Phi(v)$ .

<sup>2</sup> A-priori-estimates. From (2.8') it follows

$$(2.10) \quad Bu' = Bv - \omega Bu \quad \text{for a.a. } t \in [0, T].$$

<sup>3</sup> More precisely,  $U_\omega$  should be written to indicate the dependence of the solution on  $\omega$ . However, for notational convenience, we drop the suffix  $\omega$ .

<sup>4</sup> Cf. Lions, J.-L. et Magenes, E.: Problèmes aux limites non homogènes et applications, vol. I (chap. 3, 8.4). Dunod, Paris 1968.

Since  $u(0) = u(T)$  we find

$$(2.11) \quad \int_0^T (Bv, u) dt \geq 0 \quad \forall \omega > 0.$$

Recall that

$$(2.12) \quad v' + Av + Bu + w + \omega v = f \quad \text{for a.a. } t \in [0, T]$$

where  $w \in \partial\varphi(v)$  for a.a.  $t \in [0, T]$  (cf. (2.8')). Observing (2.11) we conclude from the latter equality after multiplying by  $v$  that

$$(2.13) \quad \|v\|_{L^2(0, T; V)} \leq \text{const} \quad \forall \omega > 0.$$

Since  $w \in \partial\Phi(v)$  the hypothesis (2.3) implies

$$(2.14) \quad \|w\|_{L^2(0, T; V^*)} \leq \text{const} \quad \forall \omega > 0.$$

Next, by the aid of (2.13) one easily derives from (2.10) the estimate

$$(2.15) \quad \|u'\|_{L^2(0, T; V)} \leq \text{const} \quad \forall \omega > 0.$$

Let  $\omega_0 = \text{const} > 0$  be arbitrary, but fixed. We multiply (2.12) by  $u$ . Using that

$$\int_0^T (v', u) dt = - \int_0^T (v, u') dt,$$

one obtains, for any  $0 < \omega \leq \omega_0$ ,

$$\begin{aligned} \int_0^T (Bu, u) dt &\leq \|v\|_{L^2(0, T; H)} \|u'\|_{L^2(0, T; H)} + \\ &+ c(\|f\|_{L^2(0, T; H)} + \|v\|_{L^2(0, T; V)} + \|w\|_{L^2(0, T; V^*)}) \|u\|_{L^2(0, T; V)} \end{aligned}$$

where  $c = \text{const} > 0$ . By (2.13)–(2.15),

$$(2.16) \quad \|u\|_{L^2(0, T; V)} \leq \text{const} \quad \forall 0 < \omega \leq \omega_0.$$

Finally, we infer from (2.12) by virtue of (2.13)–(2.16) that

$$(2.17) \quad \|v'\|_{L^2(0, T; V^*)} \leq \text{const} \quad \forall 0 < \omega \leq \omega_0.$$

3° Passage to limit. Let  $\{\omega_n\}$  be a sequence of reals such that  $0 < \omega_n \leq \omega_0$  ( $n = 1, 2, \dots$ ) and  $\omega_n \rightarrow 0$  as  $n \rightarrow \infty$ .

From the preceding two sections we obtain for each  $n$  the existence of functions  $u_n \in C([0, T]; V)$ ,  $v_n \in C([0, T]; H)$  and  $w_n \in L^2(0, T; V^*)$  with  $u'_n \in L^\infty(0, T; V)$ ,  $v'_n \in L^\infty(0, T; H)$  and  $w_n \in \partial\varphi(v_n)$  for a.a.  $t \in [0, T]$  such that

$$(2.18) \quad u'_n - v_n + \omega_n u_n = 0 \quad \text{for a.a. } t \in [0, T],$$

$$(2.19) \quad v'_n + Av_n + Bu_n + w_n + \omega_n v_n = f \quad \text{for a.a. } t \in [0, T],$$

$$(2.20) \quad u_n(0) = u_n(T), \quad v_n(0) = v_n(T)$$



(cf. (2.7')–(2.9')) and, without any loss of generality,

$$(2.21) \quad u_n \rightarrow u \quad \text{weakly in } L^2(0, T; V),$$

$$u'_n \rightarrow u' \quad \text{weakly in } L^2(0, T; V),$$

$$(2.22) \quad v_n \rightarrow v \quad \text{weakly in } L^2(0, T; V),$$

$$v'_n \rightarrow v' \quad \text{weakly in } L^2(0, T; V^*),$$

$$(2.23) \quad w_n \rightarrow w \quad \text{weakly in } L^2(0, T; V^*)$$

as  $n \rightarrow \infty$  (cf. (2.13)–(2.17)).

The passage to limit in (2.18) yields  $u' = v$  for a.a.  $t \in [0, T]$ . Using this we conclude from (2.19) after passing to limit that

$$(2.24) \quad u'' + Au' + Bu + w = f \quad \text{for a.a. } t \in [0, T].$$

Further, by (2.21) and (2.22), the conditions (2.20) are preserved when letting  $n \rightarrow \infty$ . Thus

$$u(0) = u(T), \quad u'(0) = u'(T).$$

It remains to show that  $w \in \partial\Phi(v)$ . To this end, we note that, for each  $n$ ,

$$B(u'_n - u') = B(v_n - v) - \omega_n Bu_n,$$

which implies

$$(2.25) \quad \int_0^T (Bu_n, v_n - v) dt = \int_0^T (B(v_n - v), u) dt + \omega_n \int_0^T (Bu_n, u_n - u) dt.$$

On the other hand, we obtain from (2.19)

$$\begin{aligned} \int_0^T (w_n, v_n - v) dt &= \int_0^T (f, v_n - v) dt + \int_0^T (v'_n, v) dt - \int_0^T (Av_n, v_n - v) dt - \\ &\quad - \int_0^T (Bu_n, v_n - v) dt - \omega_n \int_0^T (v_n, v_n - v) dt. \end{aligned}$$

Observing (2.25) one finds

$$\limsup \int_0^T (w_n, v_n - v) dt \leq \int_0^T (v', v) dt = 0.$$

Since  $\partial\Phi$  is maximal monotone the first convergence property in (2.22), (2.23) and the latter inequality imply  $w \in \partial\Phi(v)$ .

Thus, the function  $u$  obtained in (2.21) satisfies (2.4)–(2.6).

Let us finally mention a unilateral boundary value problem in linear viscoelasticity to which Theorem 2 applies.

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^3$  with sufficiently smooth boundary  $\Gamma$ . Denoting by  $u = \{u_1, u_2, u_3\}$  the displacement vector in  $\Omega$ , the vibrations of a viscoelastic body with short memory which occupies the region  $\Omega$  are governed by the system of equations

$$(*) \quad \frac{\partial^2 u_i}{\partial t^2} - \frac{\partial}{\partial x_j} \sigma_{ij} = f_i \quad \text{in } \Omega \times [0, T], \quad i = 1, 2, 3$$

where

$$\sigma_{ij} = a_{ijkl}^{(0)} \varepsilon_{kl} + a_{ijkl}^{(1)} \frac{\partial}{\partial t} \varepsilon_{kl},$$

$$\varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right),$$

and the coefficients  $a_{ijkl}^{(s)}$  ( $s = 0, 1$ ) are assumed to satisfy the following conditions:

$a_{ijkl}^{(s)}$  is measurable and bounded in  $\Omega$ ,

$$a_{ijkl}^{(s)} = a_{jikl}^{(s)} = a_{klij}^{(s)},$$

$$a_{ijkl}^{(s)} \varepsilon_{ij} \varepsilon_{kl} \geq \mu_0 \varepsilon_{ij}^2 \quad \text{for all symmetric tensors } \{\varepsilon_{ij}\}.$$

The vector  $f = \{f_1, f_2, f_3\}$  represents the given body force.

In order to formulate boundary conditions for  $u$ , let  $n = \{n_1, n_2, n_3\}$  denote the unit outer normal with respect to  $\Omega$  and let

$$\sigma_N = \sigma_{ij} n_i n_j,$$

$$\sigma_T = \{\sigma_{T1}, \sigma_{T2}, \sigma_{T3}\} \quad \text{where } \sigma_{Ti} = \sigma_{ij} n_j - \sigma_N n_i,$$

and

$$v_N = v_i n_i, \quad v_T = v - v_N n.$$

Let  $g \in L^2(\Gamma)$ ,  $g > 0$  a.e. on  $\Gamma$ . We then consider the following boundary conditions:

$$(**) \quad u_N = 0 \quad \text{on } \Gamma \times [0, T],$$

$$\left. \begin{array}{l} |\sigma_T| < g \Rightarrow \frac{\partial u_T}{\partial t} = 0, \\ |\sigma_T| = g \Rightarrow \exists \lambda \geq 0 : \frac{\partial u_T}{\partial t} = -\lambda \sigma_T \end{array} \right\} \quad \text{on } \Gamma \times [0, T].$$

<sup>5)</sup> We use the convention that a repeated suffix means summation over 1, 2, 3.

For introducing the weak formulation of boundary value problem (\*), (\*\*), let  $W_2^1(\Omega)$  denote the usual Sobolev space<sup>6</sup>) and let

$$V = \{v \in [W_2^1(\Omega)]^3 : v_N = 0 \text{ a.e. on } \Gamma\}.$$

We define, for any  $u, v \in V$ ,

$$a^{(s)}(u, v) = \int_{\Omega} a_{ijkl}^{(s)} \varepsilon_{kl}(u) \varepsilon_{ij}(v) dx \quad (s = 0, 1),$$

$$\varphi(v) = \int_{\Gamma} g |v_T| d\Gamma.$$

Applying Theorem 2 we get: Let  $f_i \in L^2(0, T; L^2(\Omega))$ ,  $f'_i \in L^2(0, T; L^2(\Omega))$  and  $f_i(0) = f_i(T)$  ( $i = 1, 2, 3$ ). Then there exists a function  $u \in C([0, T]; V)$  with  $u' \in L^2(0, T; V)$  and  $u'' \in L^2(0, T; V^*)$  such that

$$\int_0^T (u'', v - u') dt + \int_0^T a^{(0)}(u, v - u') dt + \int_0^T a^{(1)}(u', v - u') dt +$$

$$+ \int_0^T \varphi(v) dt - \int_0^T \varphi(u') dt \geq \int_0^T (f, v - u') dt$$

for all  $v \in L^2(0, T; V)$ , and  $u(0) = u(T)$ ,  $u'(0) = u'(T)$ .

We dispense with further details and refer to the book: *Duvaut, G. et Lions, J.-L.: Les inéquations en mécanique et en physique (chap. 3). Dunod, Paris 1972.*

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<sup>6</sup>) See e.g. *Nečas, J.:* Les méthodes directes en théorie des équations elliptiques. *Academia*, Prague 1967.