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## A Diffusion Approximation in the Ruin Problem for a Controlled Markov Chain

PHAM VAN KIEU

The reward from a controlled Markov chain is approximated by a diffusion process. From a control policy maximizing its expected discounted trajectory under a penalty for reaching zero a control of the original Markov chain is derived.

The ruin problem in controlled Markov process was considered by Z. Koutský in [4]. In the present paper a diffusion approximation is used to calculate controls taking the ruin probability into account. In Part 1 the problem is defined and the proposed solution is explained. In Part 2 a limit theorem is given which confirms the legitimacy of the approximations employed.

### 1. THE STATEMENT OF THE PROBLEM

Let  $\{X_n, n = 0, 1, \dots\}$  denote the trajectory of a controlled Markov chain with transition probabilities

$$(1) \quad p(i, j; z), \quad z \in \mathcal{Z}(i) \quad i, j \in I.$$

Here  $I$  is the finite state space of the chain,  $\mathcal{Z}(i)$  the set of control parameter values in state  $I$ ,  $i \in I$ .  $\mathcal{Z}(i)$ ,  $i \in I$ , are assumed to be closed and bounded in  $R^s$ .  $p(i, j; z)$  is the transition probability from state  $i$  into state  $j$  under control parameter value  $z$ . Further, let  $c(i, j; z)$  denote the reward the controller gets from such transition. The functions

$$c(i, j; z), \quad z \in \mathcal{Z}(i), \quad i, j \in I,$$

as well as the probabilities (1), are assumed to be continuous in  $z$ .

Let  $Z_n$  be the control parameter the controller selects after  $n$  steps.  $\{Z_n, n = 0, 1, \dots\}$  is thus a sequence of random variables depending on the past trajectory. Suppose

that the controller possesses an initial capital  $C_0$ . His capital after  $M$  steps includes the reward from the chain, and equals therefore

$$C_M = C_0 + \sum_{m=0}^{M-1} c(X_m, X_{m+1}; Z_m), \quad M = 1, 2, \dots$$

Introduce  $R = \inf \{M : C_M \leq 0\}$ . If  $R < \infty$ , we say that the controller was ruined after  $R$  steps. To balance the change of being ruined and his aim to maximize the reward when selecting the control policy, the controller employs the criterion

$$(2) \quad E\left\{C_0 + \sum_{m=0}^{R-1} d^{m+1} c(X_m, X_{m+1}; Z_m) - Nd^R\right\},$$

where  $d$  is a discount factor,  $0 \leq d < 1$ , and  $N > 0$  is a penalty for the ruin

From the Markovian property it follows that after  $n$  steps,  $(X_n, C_n)$  contains sufficient information for controlling the chain in an optimal way according to criterion (2). The controller thus looks for a function

$$(3) \quad z(i, C), \quad i \in I, \quad C \in (0, \infty),$$

such that the expectation (2) is maximal for  $Z_n = z(X_n, C_n)$ ,  $n = 0, 1, \dots, R - 1$ .

Let  $\Omega$  be the set of all functions  $\omega \sim z(i)$  mapping  $i \in I$  into  $\mathcal{Z}(i)$ .  $\Omega$  is the set of stationary controls. (3) can be written as

$$(4) \quad \omega(C), \quad C \in (0, \infty).$$

To obtain a diffusion approximation for  $C_n$ ,  $n = 0, 1, \dots$ , introduce the duration  $\tau$  of one step in the chain. Thus, the controller's capital at time  $t$  equals

$$(5) \quad \mathcal{C}_t = C_{[t/\tau]} + \{t/\tau\} (C_{[t/\tau]+1} - C_{[t/\tau]}).$$

In (5),  $[a]$   $\{a\}$  denote the integral part and the fractional part of  $a$ , respectively. Linear interpolation is used to make  $\mathcal{C}_t$  continuous. Assume first that (4) defines a stationary control, i.e.

$$\omega(C) \equiv \omega \sim z(i), \quad C \in (0, \infty).$$

Then  $\{X_n, n = 0, 1, \dots\}$  is a homogeneous Markov chain with transition probabilities

$$(6) \quad \|p(i, j; z(i))\|_{i, j \in I}.$$

Throughout the paper we shall make the following hypothesis.

**Assumption.** For arbitrary  $\omega \in \Omega$  the states which are recurrent with respect to the transition probability matrix (6) form only an irreducible set.

From the central limit theorem for Markov chains follows that  $C_n$  is asymptotically normally distributed  $N(\Theta(\omega)n, \sigma^2(\omega)n)$  as  $n \rightarrow \infty$ . Denote  $1/\sqrt{\tau} = k$ . Let

$$(5') \quad C_0 \approx k, \quad \Theta(\omega) \approx 1/k, \quad \sigma^2(\omega) \approx 1,$$

where  $k$  is fairly large.  $\mathcal{C}_{t+\Delta} - \mathcal{C}_t$  will be approximately normal  $N(\Theta(\omega)k^2\Delta, \sigma^2(\omega)k^2\Delta)$  for  $k^2\Delta$  large. Thus we expect that the evolution of  $\mathcal{C}_t/k$  will be sufficiently closely described by the stochastic differential equation

$$(6') \quad d\gamma_t = \Theta(\omega)k dt + \sigma(\omega) dW_t, \quad t \geq 0,$$

where  $\{W_t, t \geq 0\}$ , is a standardized Wiener process.

In Part 2 of the paper we give a limit theorem establishing the convergence of  $\mathcal{C}_t/k$  to the solution of (6') in the non-stationary case provided that  $\omega(C)$  is continuous.  $\omega$  in (6) then depends on  $k\gamma_t$ . To approximate the criterion, we set  $d = \exp(-\lambda/k^2)$  and consider, instead of (2),

$$(7) \quad E\left(\gamma_0 + \int_0^\zeta e^{-\lambda t} d\gamma_t - v e^{-\lambda\zeta}\right) = E\left(\lambda \int_0^\zeta e^{-\lambda t} (\gamma_t + v) dt\right) - v.$$

where

$$\zeta = \inf\{t : \gamma_t \leq 0\}, \quad v = N/k.$$

The original problem is thus converted into the problem of controlling the diffusion (6') in such way that (7) is maximal. The following recipe can be found in the literature ([5], [7]). Solve

$$\max_{\omega \in \Omega} \left\{ \frac{1}{2} \sigma^2(\omega) \frac{d^2 v}{dy^2} + \Theta(\omega)k \frac{dv}{dy} \right\} - \lambda v + \lambda(\gamma + v) = 0,$$

$$v(0) = 0, \quad v(\gamma) = O(\gamma) \quad \text{as } \gamma \rightarrow \infty.$$

Let a control  $\hat{\omega}(\gamma), \gamma \in [0, \infty)$ , be such that

$$\frac{1}{2} \sigma^2(\hat{\omega}(\gamma)) \frac{d^2 v(\gamma)}{d\gamma^2} + \Theta(\hat{\omega}(\gamma))k \frac{dv(\gamma)}{d\gamma} - \lambda v(\gamma) + \lambda(\gamma + v) = 0.$$

Then  $\hat{\omega}(\gamma)$  is optimal.

If the conditions for the validity of the diffusion approximation (i.e. essentially the order relations (5') and the continuity of  $\hat{\omega}(\gamma)$ ) are fulfilled, then a choice of (4) which is nearly optimal with respect to the criterion (2) is given by

$$\omega(C) = \hat{\omega}(C/k), \quad C \in [0, \infty),$$

or

$$Z_n = \hat{z}(X_n, C_n/k), \quad n = 0, 1 \dots$$

Further, the maximal value of (2) is approximately  $kv(C_0/k) - N$ .

Finally let us mention that to determine  $\Theta(\omega)$ ,  $\sigma^2(\omega)$  for given  $\omega \sim z(i)$  one has to solve

$$(8) \quad \sum_j p(i, j; z(i)) [c(i, j; z(i)) + w_j] - w_i - \Theta = 0, \quad i \in I,$$

and

$$(9) \quad \sum_j p(i, j; z(i)) [(c(i, j; z(i)) - \Theta)^2 + 2(c(i, j; z(i)) - \Theta) w_j + w_j^2] - w_{2i} \sigma^2 - \Theta = 0, \quad i \in I,$$

for the unknowns  $\Theta$ ,  $w_i$ ,  $i \in I$ , and  $\sigma^2$ ,  $w_{2i}$ ,  $i \in I$ , respectively [1], [6].

## 2. THE LIMIT THEOREM

Let the reward functions  $c$  depend on an auxiliary parameter  $k = 1, 2, \dots$ , and denote them by

$$c(i, j; z, k), \quad z \in \mathcal{Z}(i), \quad i, j \in I, \quad k = 1, 2, \dots$$

The functions  $c$  are assumed to be uniformly bounded. To each  $k$  there corresponds a controlled Markov chain with transition probabilities (1), as described in Section 1. To mark the dependence on the parameter, we shall add the index  $k$  to the symbols like  $X_n^k$ ,  $C_n^k$ ,  $Z_n^k$  etc.

Introduce

$$\sum_j p(i, j; z) c(i, j; z, k) = r_1(i, z; k), \quad z \in \mathcal{Z}(i), \quad i \in I, \quad k = 1, \dots,$$

$$\sum_j p(i, j; z) c(i, j; z, k)^2 = r_2(i, z; k), \quad z \in \mathcal{Z}(i), \quad i \in I, \quad k = 1, 2, \dots$$

Assume

$$(10) \quad \left. \begin{aligned} \lim_{k \rightarrow \infty} k r_1(i, z; k) &= \varrho_1(i, z) \\ \lim_{k \rightarrow \infty} k r_2(i, z; k) &= \varrho_2(i, z) \end{aligned} \right\} \text{uniformly in } z \in \mathcal{Z}(i), \quad i \in I.$$

**Theorem.** Let, for  $i \in I$ ,  $z(i, \gamma)$  be a continuous mapping of  $\gamma \in [0, \infty)$  into  $\mathcal{Z}(i)$ . Assume that  $\{X_n^k, n = 0, 1, \dots\}$ ,  $k = 1, 2, \dots$ , is controlled by  $Z_n^k = z(X_n^k, C_n^k/k)$ ,  $n = 0, 1, \dots$ . Let  $T > 0$ . Denote by  $\mathcal{P}_T^k$  the probability distribution of

$$\{\gamma_t^k = k^{-1} [C_{[tk^2]}^k + \{tk^2\} (C_{[tk^2+1]}^k - C_{[tk^2]}^k)], \quad t \in [0, T]\}$$

in the space  $\gamma$  of continuous functions on  $[0, T]$ .

If (10) holds, and  $\lim_{k \rightarrow \infty} C_0^k/k = \bar{\gamma}$ , then  $\mathcal{P}_T^k$  as  $k \rightarrow \infty$  converges weakly to the

probability distribution  $\mathcal{P}_T$  of the Markov process  $\{\gamma_t, t \in [0, T]\}$ , satisfying the stochastic differential equation

$$(11) \quad d\gamma_t = \Theta(\gamma_t) dt + \sigma(\gamma_t) dW_t, \quad t \geq 0; \quad \gamma_0 = \bar{\gamma}.$$

$\{W_t, t \geq 0\}$  is a standardized Wiener process.  $\Theta(\gamma)$  and  $\sigma(\gamma)$  are obtained from the equations

$$\begin{aligned} q_1(i, z(i, \gamma)) + \sum_j p(i, j; z(i, \gamma)) w_j - w_i - \Theta = 0, \quad i \in I, \\ q_2(i, z(i, \gamma)) + \sum_j p(i, j; z(i, \gamma)) w_{2j} - w_{2i} - \sigma^2 = 0, \quad i \in I, \end{aligned}$$

for the unknowns  $\Theta, w_i, i \in I, \sigma^2, w_{2i}, i \in I$ .

The proof of the theorem uses the methods developed in [6], the tightness of probability measures ([2]), and Doob's Theorem 3.3 ([3]). The course of the proof will be outlined in the subsequent four paragraphs.

a) Solve

$$\begin{aligned} r_1(i, z(i, \gamma); k) + \sum_j p(i, j; z(i, \gamma)) w_j^k(\gamma) - w_i^k(\gamma) - \Theta^k(\gamma) = 0, \quad i \in I, \\ \sum_j p(i, j; z(i, \gamma)) [(c(i, j; z(i, \gamma), k) - \Theta^k(\gamma))^2 + 2w_j^k(\gamma)(c(i, j; z(i, \gamma), k) - \Theta^k(\gamma)) + \\ + w_{2j}^k(\gamma)] - w_{2i}^k(\gamma) - \sigma_k^2(\gamma) = 0, \quad i \in I. \end{aligned}$$

Introduce

$$(12) \quad M_n^k = C_n^k - \sum_{m=0}^{n-1} \Theta^k(C_m^k/k) + \sum_{m=0}^{n-1} [w_{X_{m+1}}^k(C_m^k/k) - w_{X_m}^k(C_m^k/k)]$$

or

$$\begin{aligned} M_n^k = C_n^k - \sum_{m=0}^{n-1} \Theta(C_m^k/k) + \sum_{m=1}^{n-1} [w_{X_m}^k(C_{m-1}^k/k) - w_{X_m}^k(C_m^k/k)] + \\ + w_{X_n}^k(C_{n-1}^k/k) - w_{X_0}^k(C_0^k/k), \quad n = 1, 2, \dots \end{aligned}$$

Then  $\{M_n^k, n = 1, 2, \dots\}$  is a martingale with respect to  $\{\mathcal{F}_n^k, n = 1, 2, \dots\}$ , where  $\mathcal{F}_n^k$  denotes the Borel field of random events defined on  $\{X_0^k, X_1^k, \dots, X_n^k\}$ .

Furthermore,

$$(13) \quad \begin{aligned} E^k\{(M_{n+l}^k - M_n^k)^2 | \mathcal{F}_n^k\} = E^k\{w_{2X_0}^k(C_n^k/k) - w_{2X_{n+l-1}}^k(C_{n+l-1}^k/k) + \\ + \sum_{m=n+1}^{n+l-1} [w_{2X_m}^k(C_m^k/k) - w_{2X_{m-1}}^k(C_{m-1}^k/k)] + \sum_{m=n}^{n+l-1} \sigma_k^2(C_m^k/k) | \mathcal{F}_n^k\}, \\ n = 0, 1, \dots, \quad l = 1, 2, \dots \end{aligned}$$

b) Set

$$\mu_t^k = k^{-1}[M_{[tk^2]}^k + \{tk^2\}(M_{[tk^2]+1}^k - M_{[tk^2]}^k)], \quad t \in [0, T].$$

130 Denote by  $\mathcal{Q}_T^k$  the probability distribution of  $\{\mu_t^k, t \in [0, T]\}$  on  $\gamma$ . The sequence  $\{\mathcal{Q}_T^k, k = 1, 2, \dots\}$  is tight. In fact, consider, for given  $\varepsilon > 0$ , the following limit

$$\lim_{\delta \rightarrow 0} \lim_{k \rightarrow \infty} P^k \left\{ \sup_{|s-t| < \delta} |\mu_s^k - \mu_t^k| > \varepsilon \right\}.$$

It holds

$$\begin{aligned} P^k \left\{ \sup_{|s-t| < \delta} |\mu_s^k - \mu_t^k| > \varepsilon \right\} &\leq \sum_{l < T/\delta} P^k \left\{ \sup_{l\delta \leq s \leq (l+1)\delta} |\mu_s^k - \mu_{l\delta}^k| > \frac{\varepsilon}{4} \right\}, \\ P^k \left\{ \sup_{l\delta \leq s \leq (l+1)\delta} |\mu_s^k - \mu_{l\delta}^k| > \frac{\varepsilon}{4} \right\} &\leq P^k \left\{ \max_{a_l \leq r \leq a_{l+1}} \left| \sum_{j=a_l+1}^r Y_j^k \right| > \frac{\varepsilon}{4} \right\} \leq \\ &\leq \left( \frac{4}{k\varepsilon} \right)^4 E \left( \max_{a_l \leq r \leq a_{l+1}} \left| \sum_{j=a_l+1}^r Y_j^k \right| \right)^4, \end{aligned}$$

where  $a_l = [l\delta k^2]$ .

To estimate the last term calculate

$$E \left( \sum_{j=a_l+1}^{a_{l+1}} Y_j^k \right)^4 = \sum_{a_l \leq i, j, m, n \leq a_{l+1}} E(Y_i^k Y_j^k Y_m^k Y_n^k).$$

If the largest index is not matched by any other, then, by  $E(Y_n^k \mathcal{F}_{n-1}^k) = 0$ , the term vanishes; hence

$$\begin{aligned} E \left( \sum_{j=a_l+1}^{a_{l+1}} Y_j^k \right)^4 &= \sum_{m=a_l+1}^{a_{l+1}} E(Y_m^k)^4 + 4 \sum_{a_l \leq i < m \leq a_{l+1}} E\{Y_i^k (Y_m^k)^3\} + \\ &+ 6 \sum_{m=2}^{[3k_2]} E \left\{ \left( \sum_{j=a_l+1}^{a_l+m-1} Y_j^k \right)^2 (Y_{a_l+m}^k)^2 \right\} \leq \delta^2 k^4 \text{ const}. \end{aligned}$$

From the martingale inequality (Doob's Theorem 3.4, p. 317),

$$E \left\{ \max_{a_l \leq r \leq a_{l+1}} |M_r^k - M_{a_l}^k|^v \right\} \leq \left( \frac{v}{v-1} \right)^4 E \left\{ |M_{a_{l+1}}^k - M_{a_l}^k|^v \right\},$$

we get

$$E \left\{ \max_{a_l \leq r \leq a_{l+1}} \left( \sum_{j=a_l+1}^r Y_j^k \right)^4 \right\} \leq (4/3)^4 k^4 \delta^2 \cdot \text{const}.$$

Consequently,

$$P^k \left\{ \sup_{|s-t| \leq \delta} |\mu_s^k - \mu_t^k| > \varepsilon \right\} \leq \left( \frac{4}{k\varepsilon} \right)^4 \left( \frac{4}{3} \right)^4 k^4 \delta^2 \cdot \text{const} \frac{T}{\delta} = \text{const} \cdot \delta.$$

We conclude that

$$\lim_{\delta \rightarrow 0} \lim_{k \rightarrow \infty} P^k \left\{ \sup_{|s-t| \leq \delta} |\mu_s^k - \mu_t^k| > \varepsilon \right\} = 0.$$

Furthermore, from (12), (10) follows

$$(14) \quad \mu_t^k = \gamma_t^k - \int_0^t \Theta^k(\gamma_u^k) du + \eta_t^k, \quad t \geq 0,$$

where

$$(15) \quad \lim_{k \rightarrow \infty} P^k \left\{ \sup_{0 \leq t \leq T} |\eta_t^k| > \varepsilon \right\} = 0 \quad \text{for } \varepsilon > 0.$$

Let  $\bar{\mathcal{P}}_T^k$  be the probability distribution of

$$\mu_s^k - \eta_t^k = \gamma_t^k - \int_0^t \Theta^k(\gamma_u^k) du.$$

We have

$$\begin{aligned} & P^k \left\{ \sup_{|s-t| < \delta} |\gamma_s^k - \gamma_t^k - \int_t^s \Theta^k(\gamma_u^k) du| < \varepsilon \right\} \leq \\ & \leq P^k \left\{ \sup_{|s-t| < \delta} |\mu_s^k - \mu_t^k| > \frac{\varepsilon}{2} \right\} + P^k \left\{ \sup_{|s-t| < \delta} |\eta_s^k - \eta_t^k| > \frac{\varepsilon}{2} \right\}. \end{aligned}$$

By the above result and by (15) the right hand side converges to zero as  $k \rightarrow \infty$ ,  $\delta \rightarrow 0$ . Thus,  $\{\bar{\mathcal{P}}_T^k, k = 1, 2, \dots\}$  is tight. Similarly, from  $P^k \left\{ \sup_{|s-t| \leq \delta} \left| \int_t^s \Theta(\gamma_u^k) du \right| > \varepsilon/2 \right\} \rightarrow 0$  as  $\delta \rightarrow 0$ , it follows that  $\{\mathcal{P}_T^k, k = 1, 2, \dots\}$  is tight.  <sup>$|s-t| \leq \delta$</sup>

c) From this we imply that there exist a subsequence  $\{\mathcal{P}_T^{k_j}, j = 1, 2, \dots\}$  of  $\{\mathcal{P}_T^k, k = 1, 2, \dots\}$ ,  $\lim_{j \rightarrow \infty} k_j = \infty$ , possessing the weak limit  $\mathcal{P}_T$ . Define

$$\mu_t = \gamma_t - \int_0^t \Theta(\gamma_u) du, \quad t \in [0, T].$$

Then  $\{\mu_t, t \in [0, T]\}$  is a martingale on  $(\gamma, \mathcal{P}_T)$  with respect to  $\{\Phi_t, t \in [0, T]\}$ , where  $\Phi_t$  denotes the Borel field of random events defined on  $\{\gamma_s, s \in [0, t]\}$ . From (13) through a passage to the limit follows

$$(17) \quad \mathcal{E}_T \{ (\mu_{t+h} - \mu_t)^2 | \Phi_t \} = \mathcal{E}_T \left\{ \int_t^{t+h} \sigma^2(\gamma_s) ds | \Phi_t \right\}, \quad 0 \leq t < t+h \leq T.$$

d) Using (17) and

$$\mathcal{E}_T \{ (\gamma_{t+h} - \gamma_t) | \Phi_t \} = \mathcal{E}_T \left\{ \int_t^{t+h} \Theta(\gamma_s) ds | \Phi_t \right\}, \quad 0 \leq t < t+h \leq T,$$

the assumptions of Doob's Theorem 3.3 ([3] p. 287) are verified for  $\{\gamma_t, t \in [0, T]\}$  on  $(\gamma, \mathcal{P}_T)$ . This shows that  $\mathcal{P}_T$  is the probability distribution of a Markov process, satisfying (11). Such probability distribution is unique. Consequently,  $\{\mathcal{P}_T^k, k = 1, 2, \dots\}$  has only one accumulation point. This together with its tightness implies the assertion of the theorem.



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