

Acta Universitatis Palackianae Olomucensis. Facultas Rerum  
Naturalium. Mathematica

---

Lenka Lakomá  
Projections of tensor spaces

*Acta Universitatis Palackianae Olomucensis. Facultas Rerum Naturalium. Mathematica*, Vol. 38 (1999), No. 1, 87--93

Persistent URL: <http://dml.cz/dmlcz/120389>

**Terms of use:**

© Palacký University Olomouc, Faculty of Science, 1999

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* <http://project.dml.cz>



# Projections of Tensor Spaces <sup>\*</sup>

LENKA LAKOMÁ

*Department of Algebra and Geometry, Faculty of Science,  
 Palacký University, Tomkova 40, 779 00 Olomouc, Czech Republic  
 e-mail: lakoma@matnw.upol.cz*

(Received May 11, 1998)

## Abstract

The problem of projections of tensor spaces is studied in this paper. It is shown that projections of tensor spaces of symmetric tensors are either the identity mapping or its coefficients are equal zero or its coefficients are linear combination of the Kronecker's tensors.

**Key words:** Absolute invariant tensor, equivariant mapping, projection.

**1991 Mathematics Subject Classification:** 15A27, 53A45

## 1 Introduction

Let  $T_k^r \mathbb{R}^n$  be the vector space of tensors of type  $(r, k)$  on  $\mathbb{R}^n$ . This space has a canonical basis. Denote  $\zeta_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r}$  components of any tensor  $\zeta \in T_k^r \mathbb{R}^n$  with respect to this basis.

Let  $L_n^1$  be the first differential group and let  $\nu: L_n^1 \times T_k^r \mathbb{R}^n \rightarrow T_k^r \mathbb{R}^n$  be the action of  $L_n^1$  on  $T_k^r \mathbb{R}^n$ . The mapping  $f: T_k^r \mathbb{R}^n \rightarrow T_k^r \mathbb{R}^n$  is called  $L_n^1$ -equivariant if the next equation is true:

$$f \circ \nu = \nu \circ f.$$

Every equivariant mapping  $\Phi: T_k^r \mathbb{R}^n \rightarrow T_k^r \mathbb{R}^n$  is expressed by the equation

$$\zeta_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r} = \Phi_{q_1 q_2 \dots q_k s_1 s_2 \dots s_r}^{m_1 m_2 \dots m_r p_1 p_2 \dots p_k} \cdot \zeta_{p_1 p_2 \dots p_k}^{s_1 s_2 \dots s_r}$$

where  $\Phi_{q_1 q_2 \dots q_k s_1 s_2 \dots s_r}^{m_1 m_2 \dots m_r p_1 p_2 \dots p_k}$  are components of the absolute invariant tensor.

<sup>\*</sup>Supported by grant No. 201/96/0227 of The Grant Agency of Czech Republic.

The absolute invariant tensor we define by the next way. Let  $GL(\mathbb{R}^n)$  is the general linear group. For any element  $A \in GL(\mathbb{R}^n)$  we define an action  $\mu : GL(\mathbb{R}^n) \times T_k^r \mathbb{R}^n \rightarrow T_k^r \mathbb{R}^n$  of  $GL(\mathbb{R}^n)$  on  $T_k^r \mathbb{R}^n$  by the formula

$$\mu(A, \zeta) = A \cdot \zeta.$$

Tensor  $\zeta \in T_k^r \mathbb{R}^n$  is called an *absolute invariant* if for each element  $A \in GL(\mathbb{R}^n)$ ,  $A \cdot \zeta = \zeta$ . Components of absolute invariant tensor do not depend on the basis. It is easy to check if  $r \neq k$  then the tensor  $\zeta \in T_k^r \mathbb{R}^n$  is the absolute invariant if and only if  $\zeta = 0$  [2].

We will define  $L_n^1$ -equivariant projection of tensor spaces. The mapping  $\pi : T_k^r \mathbb{R}^n \rightarrow T_k^r \mathbb{R}^n$  is said to be an  $L_n^1$ -equivariant projection if it is  $L_n^1$ -equivariant and the equation  $\pi \circ \pi = \pi$  is true.

Now we can describe projections of the tensor space  $\mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$ . Let  $\mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$  denote the subspace of  $T_k^1 \mathbb{R}^n$  of tensors symmetric in subscripts.

For these projections the following theorem holds. This theorem is mentioned in [2].

**Theorem 1** *Each  $L_n^1$ -equivariant projection  $\pi : \mathbb{R}^n \otimes S^k \mathbb{R}^{n*} \rightarrow \mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$  is expressed by the equation*

$$\bar{\zeta}_{q_1 q_2 \dots q_k}^m = t_{q_1 q_2 \dots q_k}^{m p_1 p_2 \dots p_k} \cdot \xi_{p_1 p_2 \dots p_k}^s$$

where

$$\begin{aligned} k! \cdot t_{q_1 q_2 \dots q_k}^{m p_1 p_2 \dots p_k} &= A \sum_{\sigma} \delta_s^m \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} + B \left( \sum_{\sigma} \delta_s^{p_1} \delta_{q_{\sigma(1)}}^m \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} \right. \\ &+ \sum_{\sigma} \delta_s^{p_2} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^m \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots + \sum_{\sigma} \delta_s^{p_k} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^m \left. \right), \end{aligned}$$

$\sigma$  denote permutations of the set  $\{1, 2, \dots, k\}$  and the coefficients  $A, B \in \mathbb{R}$  obey one of the following four possibilities:

- a)  $A = 0, B = 0$ ;
- b)  $A = 0, B = \frac{1}{n+k-1}$ ;
- c)  $A = 1, B = 0$ ;
- d)  $A = 1, B = \frac{-1}{n+k-1}$ .

The next part of this paper deals with the generalization of this theorem.

## 2 Projections of the space $S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$

Let  $\zeta_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_k}$  be a tensor of type  $(r, k)$ . Then we will denote  $\zeta_{\dots j \dots}^{\dots j \dots}$  contraction of this tensor. If we will contract this tensor twice we will this double contraction denote  $\zeta_{\dots j_1 \dots j_2 \dots}^{\dots j_1 \dots j_2 \dots}$ , etc.

Let  $S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$  denote the subspace of  $T_k^r \mathbb{R}^n$  of tensors symmetric in superscripts and subscripts.

The following theorem is the generalization of the theorem 1.

**Theorem 2** Each  $L_n^1$ -equivariant projection  $\pi : S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*} \rightarrow S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$ ,  $r \leq k$ , is expressed by the equation

$$\bar{\xi}_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r} = t_{q_1 q_2 \dots q_k s_1 s_2 \dots s_r}^{m_1 m_2 \dots m_r p_1 p_2 \dots p_k} \cdot \xi_{p_1 p_2 \dots p_k}^{s_1 s_2 \dots s_r} \quad (1)$$

where

$$\begin{aligned} & r!k! \cdot t_{q_1 q_2 \dots q_k s_1 s_2 \dots s_r}^{m_1 m_2 \dots m_r p_1 p_2 \dots p_k} = \\ & = A_0 \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} \\ & + A_1 \left( \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} \right. \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_2} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{m_1} \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_k} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^{m_1} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{p_1} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_2} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{p_2} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{m_2} \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{p_k} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^{m_2} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r-1)}}^{m_{r-1}} \delta_{s_{\rho(r)}}^{p_1} \delta_{q_{\sigma(1)}}^{m_r} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k)}}^{p_k} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r-1)}}^{m_{r-1}} \delta_{s_{\rho(r)}}^{p_2} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{m_r} \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \delta_{s_{\rho(2)}}^{m_2} \dots \delta_{s_{\rho(r-1)}}^{m_{r-1}} \delta_{s_{\rho(r)}}^{p_k} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^{m_r} \left. \right) \\ & + A_2 \left( \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \delta_{s_{\rho(2)}}^{p_2} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_1} \delta_{q_{\sigma(2)}}^{m_2} \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} \right. \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \delta_{s_{\rho(2)}}^{p_3} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_1} \delta_{q_{\sigma(2)}}^{p_2} \delta_{q_{\sigma(3)}}^{m_2} \delta_{q_{\sigma(4)}}^{p_4} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \delta_{s_{\rho(2)}}^{p_k} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^{m_2} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_{k-1}} \delta_{s_{\rho(2)}}^{p_k} \delta_{s_{\rho(3)}}^{m_3} \dots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \dots \delta_{q_{\sigma(k-2)}}^{p_{k-2}} \delta_{q_{\sigma(k-1)}}^{m_1} \delta_{q_{\sigma(k)}}^{m_2} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \dots \delta_{s_{\rho(r-2)}}^{m_{r-2}} \delta_{s_{\rho(r-1)}}^{p_1} \delta_{s_{\rho(r)}}^{p_2} \delta_{q_{\sigma(1)}}^{m_{r-1}} \delta_{q_{\sigma(2)}}^{m_r} \delta_{q_{\sigma(3)}}^{p_3} \dots \delta_{q_{\sigma(k)}}^{p_k} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \dots \delta_{s_{\rho(r-2)}}^{m_{r-2}} \delta_{s_{\rho(r-1)}}^{p_1} \delta_{s_{\rho(r)}}^{p_3} \delta_{q_{\sigma(1)}}^{m_{r-1}} \delta_{q_{\sigma(2)}}^{p_2} \delta_{q_{\sigma(3)}}^{m_r} \delta_{q_{\sigma(4)}}^{p_4} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \dots \delta_{s_{\rho(r-2)}}^{m_{r-2}} \delta_{s_{\rho(r-1)}}^{p_1} \delta_{s_{\rho(r)}}^{p_k} \delta_{q_{\sigma(1)}}^{m_{r-1}} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-1)}}^{p_{k-1}} \delta_{q_{\sigma(k)}}^{m_r} \\ & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \dots \delta_{s_{\rho(r-2)}}^{m_{r-2}} \delta_{s_{\rho(r-1)}}^{p_{k-1}} \dots \delta_{s_{\rho(r)}}^{p_k} \delta_{q_{\sigma(1)}}^{p_1} \dots \delta_{q_{\sigma(k-2)}}^{p_{k-2}} \delta_{q_{\sigma(k-1)}}^{m_{r-1}} \delta_{q_{\sigma(k)}}^{m_r} \left. \right) + \dots \\ & + A_r \left( \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \delta_{s_{\rho(2)}}^{p_2} \dots \delta_{s_{\rho(r)}}^{p_r} \delta_{q_{\sigma(1)}}^{m_1} \delta_{q_{\sigma(2)}}^{m_2} \dots \delta_{q_{\sigma(r)}}^{m_r} \delta_{q_{\sigma(r+1)}}^{p_{r+1}} \dots \delta_{q_{\sigma(k)}}^{p_k} + \dots \right. \\ & \left. + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_{k-r+1}} \delta_{s_{\rho(2)}}^{p_{k-r+2}} \dots \delta_{s_{\rho(r)}}^{p_k} \delta_{q_{\sigma(1)}}^{p_1} \delta_{q_{\sigma(2)}}^{p_2} \dots \delta_{q_{\sigma(k-r)}}^{p_{k-r}} \delta_{q_{\sigma(k-r+1)}}^{m_1} \dots \delta_{q_{\sigma(k)}}^{m_r} \right), \end{aligned}$$

$\sigma$  and  $\rho$  are permutation of the sets  $\{1, 2, \dots, k\}$  and  $\{1, 2, \dots, r\}$  respectively.

The coefficients  $A_0, A_h$ ; ( $h = 1, 2, \dots, r$ ) are obey one of the following possibilities:

$$\begin{aligned} 1) & A_0 = A_1 = \dots = A_r = 0; \\ 2) & A_0 = A_1 = \dots = A_{i-1} = 0, \quad (i = 1, 2, \dots, r), \\ & A_h = \frac{(-1)^{h-i} i(i+1)(i+2) \dots (h-1) \cdot h!}{(h-i)!(x-i-1)(x-i-2) \dots (x-i-h)}, \quad (h = i, i+1, \dots, r); \end{aligned}$$

or

$$\begin{aligned} 3) & A_0 = 1, \quad A_1 = \dots = A_r = 0; \\ 4) & A_0 = 1, \quad A_1 = \dots = A_{i-1} = 0; \quad (i = 2, 3, \dots, r), \\ & A_h = \frac{(-1)^{h-i+1} i(i+1)(i+2) \dots (h-1) \cdot h!}{(h-i)!(x-i-1)(x-i-2) \dots (x-i-h)}, \quad (h = i, i+1, \dots, r), \end{aligned}$$

where  $x = n + k + r$ .

**Proof** Let  $\pi : S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*} \rightarrow S^r \mathbb{R}^n \otimes S^k \mathbb{R}^{n*}$  be an  $L_n^1$ -equivariant projection expressed by the equation (1). Tensor  $t$  has expression (2). From the equality  $\pi \circ \pi = \pi$  we obtain following equation

$$t_{q_1 q_2 \dots q_k s_1 s_2 \dots s_r}^{m_1 m_2 \dots m_r p_1 p_2 \dots p_k} \cdot t_{p_1 p_2 \dots p_k j_1 j_2 \dots j_r}^{s_1 s_2 \dots s_r i_1 i_2 \dots i_k} = t_{q_1 q_2 \dots q_k j_1 j_2 \dots j_r}^{m_1 m_2 \dots m_r i_1 i_2 \dots i_k} \quad (3)$$

Now we substitute  $t$  in (3) from (2) and we obtain difficulty equation. After some computation and when we compare left-hand side and right-hand side we get following system of equations. For  $h$  even we have

$$A_0^2 = A_0; \quad (4)$$

$$\begin{aligned} & 2A_0 A_h + \frac{1}{h!} (x-h-1)(x-h-2) \dots (x-2h) A_h^2 \\ & + \sum_{i=[\frac{h}{2}]+1}^{h-1} \frac{h^2 (h-1)^2 \dots (i+1)^2}{(2i-h)! [(h-i)!]^2} (x-h-1)(x-h-2) \dots (x-2i) A_i^2 \\ & + 2 \sum_{i=1}^{h-1} \frac{h(h-1) \dots (h-i+1)}{(i!)^2} (x-h-1)(x-h-2) \dots (x-h-i) A_i A_h \\ & + 2 \sum_{i=1}^{h-1} \frac{h^2 (h-1)^2 \dots (j+1)^2 j(j-1) \dots (h-i+1)}{i! (h-j)! (i+j-h)!} (x-h-1)(x-h-2) \dots (x-i-j) A_i A_j \\ & + \frac{h^2 (h-1)^2 \dots (\frac{h}{2}+1)^2}{(\frac{h}{2}!)^2} A_{\frac{h}{2}}^2 + 2 \sum_{i=[\frac{h}{2}]+1}^{h-1} \frac{h^2 (h-1)^2 \dots (i+1)^2}{[(h-i)!]^2} A_{h-i} A_i = A_h \end{aligned}$$

$$* = \begin{cases} j = 2, \dots, h-1 \\ i = 1, \dots, h-2, \quad i < j, \quad i+j > h, \end{cases} \quad x = n + k + r, \quad h = 1, 2, \dots, r.$$

For  $h$  odd we have

$$A_0^2 = A_0; \quad (5)$$

$$\begin{aligned}
 & 2A_0A_h + \frac{1}{h!}(x-h-1)(x-h-2)\cdots(x-2h)A_h^2 \\
 & + \sum_{i=[\frac{h}{2}]+1}^{h-1} \frac{h^2(h-1)^2\cdots(i+1)^2}{(2i-h)![(h-i)!]^2}(x-h-1)(x-h-2)\cdots(x-2i)A_i^2 \\
 & + 2\sum_{i=1}^{h-1} \frac{h(h-1)\cdots(h-i+1)}{(i!)^2}(x-h-1)(x-h-2)\cdots(x-h-i)A_iA_h \\
 & + 2\sum_{i=1}^{h-1} \frac{h^2(h-1)^2\cdots(j+1)^2j(j-1)\cdots(h-i+1)}{i!(h-j)!(i+j-h)!}(x-h-1)(x-h-2)\cdots(x-i-j)A_iA_j \\
 & + 2\sum_{i=[\frac{h}{2}]+1}^{h-1} \frac{h^2(h-1)^2\cdots(i+1)^2}{[(h-i)!]^2}A_{h-i}A_i = A_h \\
 & * = \begin{cases} j = 2, \dots, h-1 \\ i = 1, \dots, h-2, & i < j, i+j > h, \end{cases} \quad x = n+k+r, h = 1, 2, \dots, r.
 \end{aligned}$$

And to prove the converse we must check that each of the mappings expressed by the equation (2) where coefficients  $A_0, A_1, \dots, A_r$  are defined by (4) or (5), is an  $L_n^1$ -equivariant projection.

Equations (4) and (5) have a trivial solution and coefficients of the identity mapping are also the solution of these equations. These two solutions give mappings which are obviously  $L_n^1$ -equivariant projections. Now from the first equation we get  $A_0$  is 0 or 1. For these two coefficients we get mappings which sums will be the identity mapping. Therefore we now compute only mapping for which  $A_0 = 0$ .

We take the mapping which is given by the equation

$$\begin{aligned}
 & r!k! \cdot \bar{\xi}_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r} = \sum_h \left[ A_h \cdot \xi_{p_1 \dots p_k}^{s_1 \dots s_r} \right. \\
 & \cdot \left( \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_1} \cdots \delta_{s_{\rho(h)}}^{p_h} \delta_{s_{\rho(h+1)}}^{m_{h+1}} \cdots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{m_1} \cdots \delta_{q_{\sigma(h)}}^{m_h} \delta_{q_{\sigma(h+1)}}^{p_{h+1}} \cdots \delta_{q_{\sigma(k)}}^{p_k} + \cdots \right. \\
 & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \cdots \delta_{s_{\rho(h)}}^{m_{r-h}} \delta_{s_{\rho(h+1)}}^{p_1} \cdots \delta_{s_{\rho(r)}}^{p_h} \delta_{q_{\sigma(1)}}^{m_{r-h+1}} \cdots \delta_{q_{\sigma(h)}}^{m_r} \delta_{q_{\sigma(h+1)}}^{p_{h+1}} \cdots \delta_{q_{\sigma(k)}}^{p_k} + \cdots \\
 & + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{p_{k-h+1}} \cdots \delta_{s_{\rho(h)}}^{p_k} \delta_{s_{\rho(h+1)}}^{m_{h+1}} \cdots \delta_{s_{\rho(r)}}^{m_r} \delta_{q_{\sigma(1)}}^{p_1} \cdots \delta_{q_{\sigma(h)}}^{p_{k-h}} \delta_{q_{\sigma(h+1)}}^{m_1} \cdots \delta_{q_{\sigma(k)}}^{m_h} + \cdots \\
 & \left. + \sum_{\rho} \sum_{\sigma} \delta_{s_{\rho(1)}}^{m_1} \cdots \delta_{s_{\rho(h)}}^{m_{r-h}} \delta_{s_{\rho(h+1)}}^{p_{k-h+1}} \cdots \delta_{s_{\rho(r)}}^{p_k} \delta_{q_{\sigma(1)}}^{p_1} \cdots \delta_{q_{\sigma(h)}}^{p_{k-h}} \delta_{q_{\sigma(h+1)}}^{m_{r-h+1}} \cdots \delta_{q_{\sigma(k)}}^{m_r} \right) \\
 & = \sum_h A_h \left( \sum_{\rho} \sum_{\sigma} \delta_{q_{\sigma(1)}}^{m_1} \cdots \delta_{q_{\sigma(r)}}^{m_h} \cdot \xi_{q_{\sigma_1} \dots q_{\sigma_k}}^{m_1 \dots j_1 \dots j_h \dots m_r} + \cdots \right. \\
 & + \sum_{\rho} \sum_{\sigma} \delta_{q_{\sigma(k-r+1)}}^{m_1} \cdots \delta_{q_{\sigma(k)}}^{m_h} \cdot \xi_{q_{\sigma_1} \dots j_1 \dots j_h \dots q_{\sigma_k}}^{m_1 \dots j_1 \dots j_h \dots m_r} + \cdots \\
 & + \sum_{\rho} \sum_{\sigma} \delta_{q_{\sigma(1)}}^{m_{r-h+1}} \cdots \delta_{q_{\sigma(r)}}^{m_r} \cdot \xi_{q_{\sigma_1} \dots j_1 \dots j_h \dots q_{\sigma_k}}^{m_1 \dots j_1 \dots j_h \dots m_r} + \cdots \\
 & \left. + \sum_{\rho} \sum_{\sigma} \delta_{q_{\sigma(k-r+1)}}^{m_{r-h+1}} \cdots \delta_{q_{\sigma(k)}}^{m_r} \cdot \xi_{q_{\sigma_1} \dots j_1 \dots j_h \dots q_{\sigma_k}}^{m_1 \dots j_1 \dots j_h \dots m_r} \right)
 \end{aligned}$$

where  $h = i, i+1, \dots, r; i = 1, \dots, h$ . To prove that this mapping is a projection we must check if

$$\bar{\xi}_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r} = \bar{\xi}_{q_1 q_2 \dots q_k}^{m_1 m_2 \dots m_r}.$$

Contracting equation (6) we obtain

$$\begin{aligned}
\bar{\xi}_{q_1 q_2 \dots q_{k-i} j_1 j_2 \dots j_i}^{m_1 m_2 \dots m_{r-i} j_1 j_2 \dots j_i} &= \xi_{q_1 q_2 \dots q_{k-i} j_1 j_2 \dots j_i}^{m_1 m_2 \dots m_{r-i} j_1 j_2 \dots j_i} \\
&+ \left( A_i \frac{(x-i-2)(x-i-3) \dots (x-2i)}{(i-1)!} + A_{i+1} \frac{(x-i-2)(x-i-3) \dots (x-2i-1)}{(i+1)!} \right) \xi_{q_1 \dots q_{k-i-1} j_1 \dots j_{i+1}}^{m_1 \dots m_{r-i-1} j_1 \dots j_{i+1}} \\
&+ \left( A_i \frac{i(i-1)(x-i-3)(x-i-4) \dots (x-2i)}{2!j_i!} + A_{i+1} \frac{i(x-i-3)(x-i-4) \dots (x-2i-1)}{(i+1)!} \right) \\
&+ A_{i+2} \frac{(x-i-3)(x-i-4) \dots (x-2i-2)}{(i+2)!} \cdot \xi_{q_1 \dots q_{k-i-1} j_1 \dots j_{i+2}}^{m_1 \dots m_{r-i-1} j_1 \dots j_{i+2}} + \dots \\
&+ \left( A_i \frac{1}{i!} + A_{i+1} \frac{i(x-2i-1)}{(i+1)!} + A_{i+2} \frac{i(i-1)(x-2i-1)(x-2i-2)}{2!(i+2)!} + \dots \right) \\
&+ A_{2i-2} \frac{i(i-1)(x-2i-1)(x-2i-2) \dots (x-3i-2)}{2!(2i-2)!} + A_{2i-1} \frac{i(x-2i-1)(x-2i-2) \dots (x-3i+1)}{(2i-1)!} \\
&+ A_{2i} \frac{(x-2i-1)(x-2i-2) \dots (x-3i)}{(2i)!} \cdot \xi_{q_1 \dots q_{k-i-1} j_1 \dots j_{2i}}^{m_1 \dots m_{r-i-1} j_1 \dots j_{2i}} \\
&+ \left( A_{i+1} \frac{1}{(i+1)!} + A_{i+2} \frac{(i+1)(x-2i-2)}{(i+2)!} + A_{i+3} \frac{(i+1)i(x-2i-2)(x-2i-3)}{2!(i+3)!} + \dots \right) \\
&+ A_{2i-1} \frac{(i+1)i(x-2i-2)(x-2i-3) \dots (x-3i-1)}{2!(2i-1)!} + A_{2i} \frac{(i+1)(x-2i-2)(x-2i-3) \dots (x-3i)}{(2i)!} \\
&+ A_{2i+1} \frac{(x-2i-2)(x-2i-3) \dots (x-3i-1)}{(2i+1)!} \cdot \xi_{q_1 \dots q_{k-i-1} j_1 \dots j_{2i+1}}^{m_1 \dots m_{r-i-1} j_1 \dots j_{2i+1}} + \dots \\
&+ \left( A_{h-i} \frac{1}{(h-i)!} + A_{h-i+1} \frac{(h-i)(x-h-1)}{(h-i+1)!} \right) \\
&+ A_{h-i+2} \frac{(h-i)(h-i-1)(x-h-1)(x-h-2)}{2!(h-i+2)!} + \dots \\
&+ A_{h-2} \frac{(h-i)(h-i-1)(x-h-1)(x-h-2) \dots (x-h-i+2)}{2!(h-2)!} \\
&+ A_{h-1} \frac{(h-i)(x-h-1)(x-h-2) \dots (x-h-i+1)}{(h-1)!} \\
&+ A_h \frac{(x-h-1)(x-h-2) \dots (x-h-i)}{h!} \cdot \xi_{q_1 \dots q_{k-i-1} j_1 \dots j_h}^{m_1 \dots m_{r-i-1} j_1 \dots j_h}
\end{aligned}$$

where  $i = 1, \dots, h$ .

If  $\pi$  is the projection then  $\pi \circ \pi = \pi$ , i.e.

$$\bar{\xi}_{q_1 q_2 \dots q_{k-i} j_1 j_2 \dots j_i}^{m_1 m_2 \dots m_{r-i} j_1 j_2 \dots j_i} = \xi_{q_1 q_2 \dots q_{k-i} j_1 j_2 \dots j_i}^{m_1 m_2 \dots m_{r-i} j_1 j_2 \dots j_i} \quad (7)$$

We can see that the equation (7) is true if next equations hold.

$$\begin{aligned}
A_i \frac{(x-i-2)(x-i-3) \dots (x-2i)}{(i-1)!} + A_{i+1} \frac{(x-i-2)(x-i-3) \dots (x-2i-1)}{(i+1)!} &= 0, \\
A_i \frac{i(i-1)(x-i-3)(x-i-4) \dots (x-2i)}{2!j_i!} + A_{i+1} \frac{i(x-i-3)(x-i-4) \dots (x-2i-1)}{(i+1)!} \\
+ A_{i+2} \frac{(x-i-3)(x-i-4) \dots (x-2i-2)}{(i+2)!} &= 0, \\
\dots\dots\dots \\
A_i \frac{1}{i!} + A_{i+1} \frac{i(x-2i-1)}{(i+1)!} + A_{i+2} \frac{i(i-1)(x-2i-1)(x-2i-2)}{2!(i+2)!} + \dots \\
+ A_{2i-2} \frac{i(i-1)(x-2i-1)(x-2i-2) \dots (x-3i-2)}{2!(2i-2)!} \\
+ A_{2i-1} \frac{i(x-2i-1)(x-2i-2) \dots (x-3i+1)}{(2i-1)!} \\
+ A_{2i} \frac{(x-2i-1)(x-2i-2) \dots (x-3i)}{(2i)!} &= 0,
\end{aligned}$$

$$\begin{aligned}
 & A_{i+1} \frac{1}{(i+1)!} + A_{i+2} \frac{(i+1)(x-2i-2)}{(i+2)!} + A_{i+3} \frac{(i+1)i(x-2i-2)(x-2i-3)}{2!(i+3)!} + \dots \\
 & + A_{2i-1} \frac{(i+1)i(x-2i-2)(x-2i-3)\dots(x-3i-1)}{2!(2i-1)!} + A_{2i} \frac{(i+1)(x-2i-2)(x-2i-3)\dots(x-3i)}{(2i)!} \\
 & + A_{2i+1} \frac{(x-2i-2)(x-2i-3)\dots(x-3i-1)}{(2i+1)!} = 0, \\
 & \dots\dots\dots \\
 & A_{h-i} \frac{1}{(h-i)!} + A_{h-i+1} \frac{(h-i)(x-h-1)}{(h-i+1)!} + A_{h-i+2} \frac{(h-i)(h-i-1)(x-h-1)(x-h-2)}{2!(h-i+2)!} + \dots \\
 & + A_{h-2} \frac{(h-i)(h-i-1)(x-h-1)(x-h-2)\dots(x-h-i+2)}{2!(h-2)!} \\
 & + A_{h-1} \frac{(h-i)(x-h-1)(x-h-2)\dots(x-h-i+1)}{(h-1)!} \\
 & + A_h \frac{(x-h-1)(x-h-2)\dots(x-h-i)}{h!} = 0.
 \end{aligned}$$

For  $A_0 = A_1 = \dots = A_{i-1} = 0$  we can compute  $A_i$ . From equations (4) we get one nonzero solution

$$A_i = \frac{i!}{(x-i-1)(x-i-2)\dots(x-2i)}. \tag{8}$$

When we know  $A_i$  we compute  $A_h$  for  $h = i + 1, i + 2, \dots, r$ :

$$A_h = \frac{(-1)^{h-i} i(i+1)(i+2)\dots(h-1) \cdot h!}{(h-i)!(x-i-1)(x-i-2)\dots(x-i-h)}. \tag{9}$$

Solutions (8) and (9) we can write in the next form

$$A_h = \frac{(-1)^{h-i} i(i+1)(i+2)\dots(h-1) \cdot h!}{(h-i)!(x-i-1)(x-i-2)\dots(x-i-h)}, \quad (h = i, i + 1, \dots, r).$$

We obtain solutions which are also solutions of the system of equations (4) and the proof is complete.

## References

- [1] Conlon, L.: *Differentiable manifolds: a first course*. Boston, Basel, Berlin, Birkhäuser, 1993.
- [2] Krupka, D., Janyška, J.: *Lectures on differential invariants*. Brno, Univ. J. E. Purkyně, 1990, 193 p.
- [3] Krupka, D.: *The trace decomposition problem*. Beiträge zur Algebra und Geometrie **36**, 2 (1995), 303–315.
- [4] Mikeš, J.: *On general trace decomposition problem*. Proc. Conf., Aug. 28 – Sept. 1, 1995, Brno, Czech Republic.
- [5] Weyl, H.: *Classical groups*. Princetown, New Jersey, 1946.