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#### Commentationes Mathematicae Universitatis Carolinae

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### ON WEAK HOMOTOPY

# Jan MENU\* Antwerpen

Abstract: If the definition of homotopy is weakened by using the cross-product instead of the usual cartesian product of spaces, all connected polyhedra become contractible.

Key-words: Cross-product, weak homotopy, polyhedron.

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The cross-product  $X \otimes Y$  (the space obtained from the cartesian product of the underlying sets by the condition that  $f: X \otimes Y \longrightarrow Z$  is continuous iff it is continuous in each variable) is well-known to be a tensor product in the category of topological spaces. Thus, we can

 $f, g: X \longrightarrow Y$  are said to be W-homotopic if there is an  $h: X \otimes I \longrightarrow Y$  such that h(x, 0) = f(x) and h(x, 1) = g(x).

base on it a notion similar to homotopy - we will call it

weak homotopy or W-homotopy - defined as follows:

Thus, W-homotopy is a weaker equivalence than the nor-

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mal one. In this paper we are going to show that it is actually much weaker: e.g. all connected polyhedra are W-ho-motopically trivial.

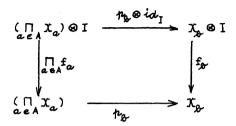
It is evident that every W-homotopically trivial space has to be arcwise connected. The converse is probably not true, but we do not have a counterexample. I am indebted to prof. Pultr, who suggested this problem, and who gave me valuable help.

### 1. Conventions and notations

Throughout this paper the circle is considered as the interval [0,4], with identified endpoints. The closed (open) unit-interval will be denoted by I(J). The closed unit-ball (sphere) in the m-dimensional Euclidean space  $\mathbb{R}^m$  will be denoted by  $\mathbb{B}_m$  ( $\mathbb{S}_m$ ). The polyhedra will always be connected, and they are supposed to be embedded in a suitable Euclidean space. The points of this Euclidean space are sometimes considered as vectors - in order to simplify the notation. For every point  $p \in \mathbb{R}^m$ , we define  $\mathbb{U}(p) = \sqrt[3]{p} = \sqrt[$ 

<u>Proposition 1</u>. The products of W-homotopically trivial spaces are W-homotopically trivial.

<u>Proof.</u> Given a family  $(X_a)_a$  of W-homotopically trivial spaces with homotopy-functions  $f_a$ , consider the following diagram:



where  $\bigcap_{\alpha \in A} f_{\alpha}$  is defined in the following way:  $\bigcap_{\alpha \in A} f_{\alpha}((x_{\alpha})_{\alpha}, t) = (f_{\alpha}(x_{\alpha}, t))_{\alpha}.$  This function is continuous.

<u>Proposition 2</u>. The long line is W-homotopically trivial.

<u>Proof.</u> Let  $L = \{(x,y) | x \in \mathbb{R}, y \in [0,1\mathbb{I}] \}$  be endowed with the lexicographical order, and the associated order-topology. The function  $h: L \otimes \mathbb{I} \to L$ ; h((x,y),t) = (xt,yt), is continuous, and L is W-homotopically trivial.

Proposition 3. The circle is W-homotopically trivial.

<u>Proof.</u> Consider  $h: S \otimes I \longrightarrow S$  defined by:

$$h(\vartheta,t) = \vartheta^{1/t} \quad \text{if } t \neq 0$$
$$= 0 \quad \text{if } t = 0 .$$

Clearly, & is continuous.

Corollary. Every torus is W-homotopically trivial.

3.

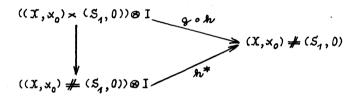
### Suspension

<u>Proposition</u>. The suspension of an arbitrary space is W-homotopically trivial.

<u>Proof.</u> Let  $(X, x_0)$  be an arbitrary pointed space. Define  $h: ((X, x_0) \times (S_1, 0)) \otimes I \longrightarrow (X, x_0) \times (S_1, 0)$  by

$$h(((x, 0), t)) = (x, 0)^{1/t}$$
 if  $t \neq 0$   
 $(x, 0)$  if  $t = 0$ .

Let  $q:(X,x_0)\times(S_1,0)\longrightarrow(x,x_0)\neq(S_1,0)$  be the natural quotient-mapping. At is usually not continuous, but  $q\circ h$  is. The commutativity of the diagram



defines uniquely a continuous mapping  $h^*$  (because  $q \otimes id$  is a quotient mapping).

Corollary. Every sphere is W-homotopically trivial.

#### 4. Polyhedra

<u>Proposition 1.</u> All one-dimensional connected polyhedra are W-homotopically trivial. If  $x_0$  is an arbitrary vertex of the polyhedron P, then the homotopy functions can be chosen in such a way that  $\forall t \in I$ ,  $f(x_0,t)=x_0$ .

<u>Proof.</u> The proposition is trivial for all one-dimensional polyhedra with at most two vertices. Suppose it is proved for all one-dimensional polyhedra with at most m-1 vertices,  $m \geq 3$ . Let P be an arbitrary but fixed poly-

hedron with m vertices, embedded in a suitable  $\mathbb{R}^{4^n}$ , and suppose all segments of P have length 4. Choose an arbitrary vertex  $x_0$  of P, denote the vertices of P by  $(x_i)_{0 \le i \le m-4}$ .

The segments  $[x_i, x_j] \in P$ ,  $x_i$  and  $x_j \neq x_0$ , form at most m-1 maximal connected one-dimensional polyhedra  $P_k^i$ ;  $k \neq i_p \neq m-1$ ;  $P_k^i \cap P_k^i = \emptyset$  if  $k \neq k'$ . Choose  $x_{j_k} \in P_k^i$  such that  $[x_{j_k}, x_0] \in P$ ,  $\forall k \in i_p$ . Consider the polyhedra  $P_k$ , consisting of the vertices of  $P_k^i$  and  $x_0$ , and all the segments in P between these vertices. By induction, the  $P_k^i$  are W-homotopically trivial, and there exist continuous functions  $f_k: P_k^i \otimes I \longrightarrow P_k^i$  such that

$$\begin{split} &f_{R_{R}}(x,1)=x\,,\quad \forall x\in P_{R_{R}}'\\ &f_{R_{R}}(x,0)=x_{j_{R_{R}}}\,,\quad \forall x\in P_{R_{R}}'\\ &f_{R_{R}}(x_{j_{R_{R}}},t)=x_{j_{R_{R}}}\,,\quad \forall t\in I \quad. \end{split}$$

We will define the homotopy functions  $g_{2k}$ , on the polyhedra  $P_{2k}$ . Suppose 2k fixed for the time being.

1) Consider the segment  $[x_0, x_{j_0}]$ .

Define  $q_k(x,t) = t \cdot \overline{x_0 \cdot x}$  if  $x \in [x_0, x_{j_k}]$ .

Define  $d_{g_k}: P'_{g_k} \times P'_{g_k} \longrightarrow R_{\perp}$  by

$$d_{\mathcal{R}}(y, y') = \inf \left\{ \sum_{\alpha=1}^{m-1} \| x_{\alpha} x_{\alpha-1} \| | x_{1} = y, x_{m} = y', x_{m} =$$

A) 
$$t = 1$$

put  $g_{g_k}(x,1) = f_{g_k}(x,1) = x$ 

put  $q_{i_k}(x,t) = 2(\overline{x_{j_k}f_k(x,t)} - (1/4).\overline{x_{j_k}x_{j}})$ , where

b) if  $1/4 \le d_{g_k}(f_{g_k}(x,t), x_{j_k}) \le 1/2$ 

put  $q_{\bullet}(x,t) = f_{\bullet}(x,t)$ 

3) Consider the segments

Define  $\mathcal{H}_{g_{\underline{a}}}: (P_{g_{\underline{a}}} - P'_{g_{\underline{a}}}) \otimes I \longrightarrow R_{+}$  by

if t = 1, put  $q_{q_k}(x, 1) = x$ 

b) if  $1/4 \le \Re_{\mathbf{g}}(x,t) \le 1/2$ 

c) if  $0 \le h_{2e}(x, t) \le 1/4$ ,

a) if  $1/2 \leq k_{\underline{a}}(x,t)$ 

if t + 1

a) if  $d_{\mathbf{g}_{\mathbf{c}}}(\mathbf{f}_{\mathbf{g}_{\mathbf{c}}}(\mathbf{x},\mathbf{t}),\mathbf{x}_{\mathbf{f}_{\mathbf{c}}}) \ge 1/2$ 

B) t + 1

 $f_{\mathcal{R}}(x,t) \in [x_{j_{\mathcal{R}}}, x_{j_{\mathcal{R}}}]$  and  $x_{j_{\mathcal{R}}}$  is uniquely determined

put  $q_{\mathbf{k}}(\mathbf{x},t) = 4 \cdot d_{\mathbf{k}}(\mathbf{f}_{\mathbf{k}}(\mathbf{x},t),\mathbf{x}_{\mathbf{j}_{\mathbf{k}}}) \cdot \mathbf{f}(\mathbf{x}_{\mathbf{j}_{\mathbf{k}}},t) \times \mathbf{j}_{\mathbf{k}}$ 

 $h_{\underline{t}_{0}}(x,t) = \|\overline{x_{j}} \hat{x}\|^{1/t}$  if  $t \neq 0$ , and  $x \in [x_{o}, x_{j}]$ 

c) if  $0 \le d_{\mathbb{R}}(f_{\mathbb{R}}(x,t), x_{f_{\mathbb{R}}}) \le 1/4$ 

 $[x_0, x_{\frac{1}{2}}], x_{\frac{1}{2}} \in P_{k}; [x_0, x_{\frac{1}{2}}] \in P, j \neq j_{k}$ 

put  $g_{\mathbf{k}}(x,t) = h_{\mathbf{k}}(x,t) \cdot \overrightarrow{x_{i} x}$ ;  $x \in [x_{0}, x_{i}]$ 

put  $q_{i_0}(x,t) = 2(h_{i_0}(x,t) - 1/2) \cdot \overrightarrow{x_i} x$ ,

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$$i)$$
  $t=0$ 

put 
$$q_{\mathbf{x}}(\mathbf{x},0) = \mathbf{x}_0$$

ii)  $t \neq 0$ 

put  $Q_{3,k}: J \longrightarrow R_+$  by

$$Q_{j,k}(t) = max \left\{ \sum_{i=1}^{m-1} \| g_{k}(x_{j}, t_{i}) g_{k}(x_{j}, t_{i+1}) \| | m \in \mathbb{N}, (t_{i})_{i} \right\}$$

partitions of [t, 1[, [ $g_{\mathbf{k}}(x_i, t_i)$ ,  $g_{\mathbf{k}}(x_i, t_{i+1})$ ] c P } .

Define 
$$\kappa_{j,k}$$
:  $Im(q_{j,k}) \longrightarrow P_{k}$  by 
$$\kappa_{j,k}(q_{j,k}(t)) = q_{k}(x_{j},t) ,$$

define  $s_{j,k,t}:[x_j,x_{t,j}] \longrightarrow [0,q_j,k]$  by

 $k_{j,k,t}(x) = 2_{j,k}(t).(1-4k_{k}(x,t))$  if  $x \in [x_{j}, x_{o}]$  and where  $x_{t,j}$  is that point on  $[x_{j}, x_{o}]$  such that  $k_{k}(x_{t,j},t) = 1/4$ . Define  $g_{k}(x,t) = k_{j,k} \circ k_{j,k,t}(x)$  if  $x \in [x_{j}, x_{o}]$ .

4) The polyhedron P. Define  $g(x,t) = g_{\mathcal{R}}(x,t)$  if  $x \in P_{\mathcal{R}}$ . It is clear from the construction that  $g: P \otimes I \longrightarrow P$  is a continuous function such that  $g(-,1) = id_{P}$ ,  $g(-,0) = x_{0}$ .

<u>Proposition 2</u>. All connected polyhedra are W-homotopi-cally trivial.

<u>Proof.</u> The theorem is proved for all one-dimensional polyhedra, suppose it is proved for all d-dimensional ones, with  $d \leq m-1$ ,  $m \geq 2$ . Let P be an arbitrary fixed m-dimensional polyhedron embedded in a suitable  $\mathbb{R}^n$ . P' is the (m-1)-dimensional skeleton of P, with a homotopy function g'.

A) Define 
$$g(x,t) = g'(x,t)$$
 for  $x \in P'$ .

B) 1) There exist 
$$f_k: B_n \longrightarrow R^n$$
,  $1 \le k \le m$ , such that 
$$f_k(B_m) \subset P, \ \forall k \le m$$

$$f_{\mathcal{R}} \mid B_{m}$$
 is a homeomorphism onto the image

$$f_{k} \mid S_{n} \subset P'$$

$$f_{k} \mid S_{n} \subset P'$$

$$f_{k} \mid S_{n} \setminus C \mid S_{n} \mid C \mid P'; \quad k \neq k'$$

$$\bigcup_{k=1}^{m} f_{k}(B_m) \cup P' = P .$$

- 2) If  $B_m$  is the unit-ball, define  $k': B_m X I \longrightarrow B_m$  as follows:
- a) h'((0,0,...,0),t)=(1-t,0,...,0)

b) 
$$y \neq (0, 0, ..., 0): h'(y, t) \in [(1-t, 0, ..., 0), U(y)]$$
  
and

$$\|\vec{y}\| = \frac{\|\hat{\mathcal{X}}(y,t) - (1-t,0,...,0)\|}{\|(1-t,0,...,0)\|}$$

take an  $h: B_m \otimes J \longrightarrow B_m$  such that

$$h((0,0,...,0),t) = h'((0,0,...,0),t)$$

$$h(y,t) \in [(1-t,0,...,0), U(y)], y + (0,0,...,0)$$

and

$$\frac{\|\mathbf{h}(\mathbf{y},t) - \mathbf{U}(\mathbf{y})\|}{\|(\mathbf{1}-t,0,...,0) - \mathbf{U}(\mathbf{y})\|} = \left(\frac{\|\mathbf{h}(\mathbf{y},t) - \mathbf{U}(\mathbf{y})\|}{\|(\mathbf{1}-t,0,...,0) - \mathbf{U}(\mathbf{y})\|}\right)^{1/t}$$

3) If  $\alpha \in P - P'$ , then  $\exists ! k \leq m$  such that  $\alpha \in f_{k}(B_{m})$ . Define the functions  $h_{k}: f_{k}(B_{m}) \otimes J \longrightarrow f_{k}(B_{m})$  by

$$h_{k}(z,t) = f_{k} \circ h((f_{k}^{-1}(z),t))$$
.

4) x e P' .

Define  $q_x: I \longrightarrow R$  by

$$Q_{x}(t) = \sup \left\{ \sum_{i=1}^{\mu-1} \| \overline{g'(x,t_{i}) g'(x,t_{i+1})} \| \right\}$$

where  $(t_i)_i$  are partitions of [t, 11].

Define  $\kappa_x : Im(q_x) \longrightarrow Im(q'(x,-)) \subset P'$  by  $\kappa_x(q_x(t)) = q'(x,t).$ 

- 5)  $\alpha \in f_{\Phi_n}(B_m) P'$ ; & fixed.
- a) Put  $g_{4c}(x,1)=x$  and  $g_{4c}(x,0)=x_0$  , where  $x_0=g^3(-,0)$ 
  - b) t e J .

Notation:

$$v(y,t) = \|(1-t,0,...,0) - \overline{u(y)}\|, y \in B_m, y \neq (0,0,...,0)$$

$$u_k(z,t) = d(k(f_k^{-1}(z),t), u(f_k^{-1}(z))).$$

Let  $A_{x,t,k}$  and  $B_{x,t,k}$  be the points on the segment  $\Gamma(1-t,0,...,0)$ ,  $U(f_a^{-1}(x))$ ] such that

$$\|\overline{A_{\alpha,t,\infty}} - (\overline{1-t,0,...,0})\| = v(f_{\infty}^{-1}(\alpha),t)/2$$

$$\|\overline{B}_{x,t,t_0} - \overline{(1-\theta,0,...,0)}\| = 3\nu (f_{y_0}^{-1}(x),t)/4$$
1) If  $\nu(f_{x_0}^{-1}(x),t)/2 \le \mu_{x_0}(x,t)$  put

$$q_{a}(x,t) = h_{a}(x,t) .$$

2) If  $v(f_{\frac{1}{2}}^{-1}(z),t)/4 \le \mu_{\frac{1}{2}}(z,t) \le v(f_{\frac{1}{2}}^{-1}(z),t)/2$  define the linear functions

$$v_{\alpha,t,\mathfrak{R}}: \lceil A_{\alpha,t,\mathfrak{R}}, B_{\alpha,t,\mathfrak{R}} \rceil \longrightarrow \lceil A_{\alpha,t,\mathfrak{R}}, U(f_{\mathfrak{R}}^{-}(\alpha)) \rceil$$

such that

$$w_{\alpha,t,k}(A_{\alpha,t,k}) = A_{\alpha,t,k}$$

$$w_{\alpha,t,k}(B_{\alpha,t,k}) = \mathcal{U}(f_{\alpha}^{-1}(\alpha))$$

define  $q_{\mathbf{k}}(x,t) = \mathbf{f}_{\mathbf{k}} \circ v_{2,t,\mathbf{k}} \circ h\left((\mathbf{f}_{\mathbf{k}}^{-1}(x),t)\right)$ .

3) If 
$$0 \le \mu_{\mathbf{g}}(x,t) \le \nu(f_{\mathbf{g}}^{-1}(x),t)/4$$

define  $\mathcal{A}_{q,t,k}:[\mathcal{U}(q),\mathcal{B}_{z,t,k}] \to [0,q_x(t)]$ , where  $z = f_k(q)$  and  $x = f_k(\mathcal{U}(q))$ , to be the linear functions such that

$$S_{y,t,\mathcal{R}}(B_{x,t,\mathcal{R}}) = 0$$

$$S_{y,t,\mathcal{R}}(U(y)) = Q_{x}(t),$$

define  $q_{g_k}(x,t) = x_x \circ s_{y,t,g_k}(x)$ , where  $x = f_{g_k}(y)$ ,  $x = f_{g_k}(U(y))$ .

put  $q(x,t) = q_k(x,t)$  if  $x \in f_k(B_n)$ .

The function  $q: P \otimes I \longrightarrow P$  is continuous.

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