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*Commentationes Mathematicae Universitatis Carolinae*, Vol. 4 (1963), No. 1, 15--28

Persistent URL: <http://dml.cz/dmlcz/104925>

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ON THE LOCAL MAP OF MANIFOLDS

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Let us consider a  $n$ -dimensional differentiable manifold  $M$  of class  $C^\infty$ . Let  $g$  be identical mapping of  $M$ . To every point  $x \in M$  let there correspond just one pair  $(f_x, U_x)$ , where  $f_x$  is a transformation of the class  $C^\infty$  of  $M$  onto itself defined on a neighborhood  $U_x$  of a point  $x \in M$  so, that  $f_x(x) = x$  and that for an arbitrary curve  $c$  going through the point  $x \in M$ , the curves  $f_x(c)$  and  $g(c)$  have an analytic contact of the first order, but no contact of the second order at the point  $x \in M$ .

We can now write briefly

$$f_x \in j_x^1 g \cap (j_x^1(g) - j_x^2(g)) = j_x^1 g$$

when  $j_x^k g$  is an infinitesimal jet of the order  $k$  ( $k$ -jet). We shall speak briefly about a combined manifold  $M_f$ .

It is straightforward that a correspondence between two projective, affine, ... spaces and a tangent homology, affinity, ... of this correspondence is a special case of a notion introduced above. It is possible to show that we can associate so called linearizing tensor (introduced by E. Čech), which plays a fundamental role in the theory of correspondences between two projective, affine, ... spaces, globally with a combined manifold  $M_f$ .

Further a relation among linear connections on  $M$  and the linearizing tensor associated with the combined mani-

-fold  $M_f$  will be shown. It appears that two connections which are in certain correspondence defined by the relation  $M \rightarrow M_f$  have common torsion tensors.

1. Let  $M$  be an  $n$ -dimensional differentiable manifold of the class  $C^\infty$ . Let us denote by  $T_a(M)$  the tangent vector space of  $M$  at a point  $a \in M$  and let  $T(M)$  be the tangent bundle space over  $M$ . Let  $P(M, GL(n, R))$  be a principal fibre bundle over a base manifold  $M$  with Lie structural group  $GL(n, R)$  and with a projection  $\mu$  of  $P$  on  $M$ . We say that the vector  $\tau \in T_a(P)$  is vertical if it is tangent to the fibre going through the point  $b \in P$ . For each  $g \in G = GL(n, R)$  we denote by  $Dg$  the right translation of the manifold  $P$  corresponding to the element  $g$ .

Let  $\mathcal{L}$  be the Lie algebra of the group  $G$ . We denote by  $\sigma$  a differentiable representation of  $G$  on a vector space  $R^n$  and by  $\sigma_0$  its induced representation of the Lie algebra  $\mathcal{L}$  of  $G$  on a vector space  $R^n$ . Let  $\{\mathcal{E}_\rho\}$  be a base of  $\mathcal{L} = R^n \otimes R^{n*}$ . Taking a base  $\{e_i\}$  of  $R^n$  we can express the representation  $\sigma$  of  $G$  on  $R^n$  by a matrix  $(g_{ik})$ :

$$(1) \quad \sigma(g)e_k = g_{ik} e_i, \quad g = (g_{ik}) \in G.$$

Because  $\sigma_0(\mathcal{E}_\rho)$  is an endomorphism of the vector space  $R^n$ , having chosen a base of  $R^n$ , we can write

$$(2) \quad \sigma_0(\mathcal{E}_\rho)e_i = a_{i\rho}^k e_k,$$

where  $(a_{i\rho}^k)$  is a matrix, the elements of which belong to  $R$ , corresponding to  $\mathcal{E}_\rho$ . The adjoint representation of  $G$  on  $\mathcal{L}$  be denoted, as usually,  $adj$ .

We have on  $G$  the left invariant vector fields

$$(3) \quad \mathcal{E}_{ij}(g) = g_{ri} \left( \frac{\partial}{\partial x_j} \right) g, \quad g \in G.$$

$$1) \quad i, j, k = 1, 2, \dots, n \quad \quad \quad -16- \quad \rho, \sigma, \dots = 1, 2, \dots, s$$

It is easy to show that

$$(4) \quad [\varepsilon_{ij}, \varepsilon_{ks}] = \delta_{ki} \varepsilon_{sj} - \delta_{kj} \varepsilon_{is}.$$

The representation  $\sigma_0$  of  $\mathcal{L}$  on  $R^n$  can be expressed in the following way:

$$(5) \quad \sigma_0(\varepsilon_{ij})e_k = \delta_{ki} \sigma_{jn} e_n.$$

If we have an  $R^n$ -valued  $q$ -form

$$(6) \quad \varphi = \varphi^i \otimes e_i$$

on  $M$  and an  $\mathcal{L}$ -valued  $q'$ -form

$$(7) \quad \phi = \phi^p \otimes \varepsilon_p$$

on  $M$ , then we can define the  $R^n$ -valued  $(q+q')$ -form

$\phi \cdot \varphi$  as follows:

$$(8) \quad \phi \cdot \varphi = (\phi^p \otimes \varepsilon_p) \cdot (\varphi^i \otimes e_i) = \sigma_0(\varepsilon_p) \cdot e_i \otimes \phi^p \wedge \varphi^i.$$

Now let us have two vector spaces  $A = R^n \otimes \hat{\Lambda} R^{n*}, B = \mathcal{L} \otimes R^{n*}$

( $R^{n*}$  being the dual vector space of  $R^n$ ). If we denote

by  $\sigma^*$  the dual representation of  $\sigma$ , we obtain

the representations  $\mathcal{R} = \sigma \otimes \hat{\Lambda} \sigma^*$  and  $\mathcal{L}' = \text{adj} \otimes \sigma^*$

of the group  $G$  on the vector spaces  $A$  and  $B$  respectively.

Let  $\{e^i\}$  be the dual base of the base  $\{e_i\}$

of  $R^n$ . We define the linear map  $\mathcal{A} : B \rightarrow A$  as

follows:

$$(9) \quad \mathcal{A} \left( \sum_{p,k} \xi_k^p e^k \otimes \varepsilon_p \right) = \sum_{p,i,j,k} (a_{pj}^i \xi_k^p - a_{pk}^i \xi_j^p) e_i \otimes e^j \wedge e^k.$$

Since we have  $\mathcal{L} = R^n \otimes R^{n*}$ , the vector  $\varepsilon_p$  of

the base  $\{\varepsilon_p\}$  can be written in the form  $\sum_{i,j} \sigma_0(\varepsilon_p) e_i \otimes e^j$

-in the base  $\{e_i \otimes e^j\}$  of  $R^n \otimes R^{n*}$ .

Now we can write  $\varepsilon_p = a_{ip}^k e_k \otimes e^i$ . The mapping  $\mathcal{A}$  is then, in fact, a mapping of  $B = R^n \otimes R^{n*} \otimes R^{n*}$

into  $A = R^n \otimes \hat{\wedge} R^{n*}$  ; which, having chosen a base of  $R^n$  , assigns to every element  $\sum_{i,j} \delta_{ij}^k e_k \otimes e^i \otimes e^j$  an element  $(\delta_{ij}^k - \delta_{ji}^k) e_k \otimes e^i \wedge e^k$  .

It is straightforward to verify that we have

$$(10) \quad A \mathcal{L}(g) = \mathcal{R}(g) A, \quad g \in G.$$

If considering  $x \in P$  as an isomorphism of  $R^n$  on  $T_x(M)$ , ( $\pi x = a$ ) we can define a fundamental 1-form as follows:

Definition: The fundamental 1-form on  $P$  is an  $R^n$ -valued 1-form  $\theta$  on  $P$  , which assigns to a vector  $\tau_x \in T_x(P)$  a vector

$$(11) \quad \theta(\tau_x) = x^{-1} \cdot \pi^{-1} \tau_x .$$

It is easy to verify that a fundamental 1-form satisfies the following conditions:

- a)  $D_g^* \theta = g^{-1} \cdot \theta, \quad g \in G,$
- b)  $\theta(\tau) = 0 \iff \pi \tau = 0.$

Let a frame  $\{\vartheta_\alpha^1, \dots, \vartheta_\alpha^n\}$  be given on a neighborhood  $U_\alpha$  on  $M$  . The form  $\vartheta_\alpha = \vartheta_\alpha^i \otimes e_i$  is an  $R^n$ -valued 1-form on  $U_\alpha$  . If we consider two neighborhoods  $U_\alpha, U_\beta$  ;  $U_\alpha \cap U_\beta \neq \emptyset$  and if  $g_{\alpha\beta}$  denotes the coordinate transformations of  $P$  , then  $\vartheta_\alpha = g_{\alpha\beta}(a) \vartheta_\beta$ ,  $a \in U_\alpha \cap U_\beta$  . Denoting by  $\pi_\alpha$  the cross-projection of  $P$  , it holds according to the definition of a principal fibre bundle that

$$\pi_\beta(x) = g_{\beta\alpha}(\pi(x)) \pi_\alpha(x), \quad x \in \pi^{-1}(U_\alpha \cap U_\beta) .$$

Now we can define the  $R^n$ -valued fundamental 1-form  $\theta_\alpha$  on  $P$  by  $\theta_\alpha = \pi_\alpha^{-1}(x) \cdot \pi^* \vartheta_\alpha$  . Namely,  $\theta_\alpha = \theta_\beta$  holds.

A connexion  $\Gamma$  on  $P$  be given by a system of horizontal spaces. To every point  $x \in P$  there is assigned a so-called horizontal space  $H_x$  and a so-called vertical space  $V_x$  so, that their union is  $T_x(P)$ . For arbitrary  $g \in G$  and  $x \in P$ ,  $H_{xg} = D'g H_x$  and  $H_x$  depend differentiably on a point  $x \in P$ . A connexion  $\Gamma$  on  $P$  can also be given by an  $\mathcal{L}$ -valued differential 1-form  $\omega$  on  $P$ . The  $R^n$ -valued 2-form on  $P$

$$(12) \quad \Sigma_\omega = d\theta + \omega\theta,$$

where  $\theta$  is a fundamental 1-form on  $P$ , is called the torsion form  $\Sigma_\omega$  of a connexion  $\Gamma$ .

The tensor  $t\Sigma_\omega$  assigned to the torsion form  $\Sigma_\omega$  is called the torsion tensor.  $t\Sigma_\omega$  is the mapping of  $P$  into  $A$  of the type  $\mathcal{R}$ .

2. In this part it will be shown that a differentiable transformation of certain type of  $P$  onto itself assigns to a connexion on  $P$  against a connexion on  $P$  and that there exists a tensor on  $P$  which depends only on a respective mapping of  $P$  onto itself.

Let  $h$  be a differentiable map of  $P$  onto itself, such that the following conditions are satisfied:

$$1) \quad h \circ Dg = Dg \circ h$$

2)  $h' \tau_x = \tau_{hx}$ , for an arbitrary vertical vector  $\tau_x$ .

3) If  $\Gamma$  is a connexion on  $P$  and  $\tau_x$  a horizontal vector, then there exists a vertical vector  $\nu_x$  so,

that  $h' \tau_x = \tau_{hx} + v_{hx}$ .

A map  $h' H_x$  of a vector space  $H_x$  is again a horizontal vector space at a point  $hx$ . Then let us denote  $H'_{hx}$ . It is easy to verify that a system of spaces  $H'_x$  which are assigned to the points of  $P$ , define a connexion  $\Gamma'$  on  $P$ . We have clearly

Proposition: Let  $\omega$  and  $\omega'$  denote the connexion forms of the connexions  $\Gamma$  and  $\Gamma'$  respectively.  $\Gamma'$  is the map of  $\Gamma$  as described above. Then the tensor  $tu$ , where  $u = \omega' - \omega$ , is independent on the choice of a connexion  $\Gamma$  on  $P$ .

Proof: Let  $\{h_1, \dots, h_m\}$  be a base of  $H_x$  and  $\{v_1, \dots, v_n\}$  be a base of  $V_x$ . Let  $\tilde{h}_i$  be a map of a vector  $h_i$ , where the mapping  $h$  is chosen.  $\{\tilde{h}_1, \dots, \tilde{h}_m\}$  is obviously a base of  $H'_x$

(the horizontal space at the point  $x \in P$  of the connexion  $\Gamma'$ ). Hence we have

$$(13) \quad h_i = \tilde{h}_i + v_i^\alpha v_\alpha,$$

where  $v_i^\alpha$  is a function of a point  $x \in P$ . A base  $\{v_\alpha\}$  of  $V_x$  be chosen so, that the equation

$$(14) \quad \omega(v_\alpha) = \varepsilon_\alpha$$

holds.

The tangent vector  $\tau \in T_x(P)$  be given by

$$(15) \quad \tau = a^i h_i + b^\alpha v_\alpha.$$

Now we have

$$(16) \quad \omega(\tau) = b^\alpha \varepsilon_\alpha, \quad \omega'(\tau) = (b^\alpha + a^i v_i^\alpha) \varepsilon_\alpha,$$

where  $\omega'$  is the 1-form of the connexion  $\Gamma'$  on  $P$ .

By making use of (16), we have

$$(17) \quad u(\tau) = a^i v_i^\alpha \varepsilon_\alpha.$$

If  $\{h_1, \dots, h_n\}$  is the dual base of  $\{\theta^1, \dots, \theta^n\}$  ( $\theta^i$  are fundamental forms on  $M$ ) we can write

$$(18) \quad u = v_i^\alpha \theta^i \otimes \varepsilon_\alpha.$$

If  $\{e^i \otimes e^j \otimes e_k\}$  is a base of  $B$ , then

$$(19) \quad a_{pj}^k v_i^p$$

are components of the tensor  $t u$ .

Let  $\pi$  be a connexion form of a new connexion  $\Omega$  on

$P$ . The horizontal spaces  $K$  be formed by vectors

$$(20) \quad k_i = \lambda_i^j h_j + \varphi_i^\alpha v_\alpha; \quad \lambda_i^j, \varphi_i^\alpha \text{ are functions of a point } x \in P.$$

Assume that  $\text{Det} |\lambda_i^j| \neq 0$

on  $P$ . If  $a = (a_i^j)$ , we shall denote by  $(\tilde{a}_i^j) = a^{-1}$  the inverse of  $a$ . We can write now

$$(21) \quad h_i = \tilde{\lambda}_i^j k_j + \phi_i^\alpha v_\alpha.$$

From the equations (19) and (20) we have

$$(22) \quad \phi_i^\alpha + \tilde{\lambda}_i^j \varphi_j^\alpha = 0.$$

When  $K'$  is a  $h$ -map of the horizontal space  $K$ , we have the horizontal space  $K'$  spanned by vectors

$$(23) \quad \tilde{h}_i = \lambda_i^j \tilde{h}_j + \varphi_i^\alpha v_\alpha.$$

We can write then

$$(24) \quad k_i = \tilde{k}_i + \lambda_i^k v_k^\alpha v_\alpha.$$

The vector  $\tau$  can be written as follows:

$$(25) \quad \begin{aligned} \tau &= a^i \tilde{\lambda}_i^j k_j + (a^i \phi_i^\alpha + b^\alpha) v_\alpha, \\ \tau &= a^i \tilde{\lambda}_i^j \tilde{k}_j + (a^i \phi_i^\alpha + b^\alpha + a^k v_k^\alpha) v_\alpha \end{aligned}$$

If we denote by  $\pi'$  the connexion form of the connexion

$\Omega'$  ( $\Omega'$  is the map of the connexion  $\Omega$ ) we have



$$(26) \quad u' = \pi' - \pi = v_i^{\alpha} \theta^i \otimes \varepsilon_{\alpha} .$$

From (18) and (26) we see that  $u$  is independent of the choice of the initial connexion. It is clear that the choice of a base of  $H$  does not play any essential role through the proof.

3. Throughout this chapter let us consider how to define the functions  $v_i^{\alpha}(x)$  mentioned above. It is possible to show that having  $M_f$  associated to  $M$ , we can construct the functions  $v_i^{\alpha}(x)$ . In the neighborhood  $U_{x_0}$  of a point  $x_0$  on  $M$  let us have a coordinate system  $(x^1, \dots, x^n)$ ,  $x_0 = (x_0^1, \dots, x_0^n)$ . The mapping

$f_{x_0}$  can be written as follows:

$$(27) \quad x^i = f_{x_0}^i(x^1, \dots, x^n), \quad x_0^i = x_0^i = f_{x_0}^i(x_0^1, \dots, x_0^n); \quad (i=1, 2, \dots, n).$$

If we put

$$(28) \quad A_k^i(x_0, x) = \frac{\partial f_{x_0}^i}{\partial x^k}$$

We have

$$(29) \quad A_k^i(x_0, x_0) = \delta_k^i$$

because  $f_{x_0} \in \mathcal{J}_{x_0} g$ .

The function  $A_k^i(x, y)$ ;  $x, y \in M$  can be considered as a function on  $M \times M$ , which is defined in some neighborhood  $V$  of the point  $(x_0, x_0) \in M \times M$ .

Let us have two neighborhoods  $V_{\alpha}, V_{\beta}$ ;  $V_{\alpha} \cap V_{\beta} \neq \emptyset$  on  $M \times M$  and let  $(x^1, \dots, x^{2n}), (y^1, \dots, y^{2n})$  be coordinates of points  $u \in V_{\alpha}, v \in V_{\beta}$  respectively, so that  $(x^1, \dots, x^n), (x^{n+1}, \dots, x^{2n})$  are coordinates in some neighborhoods  $U_1, U_2$  on  $M$  and analogously  $(y^1, \dots, y^n), (y^{n+1}, \dots, y^{2n})$  are coordinates in some

neighborhoods  $U_3, U_4$  on  $M$ . For points of the intersection  $V_\alpha \cap V_\beta$  let us have the same transformation of coordinates as it is for points of  $U_2 \cap U_4$  on  $M$ . Namely, if we have a neighborhood  $U_1$  on  $M$ , we can associate to every point  $x \in U_1$  the neighborhood  $U_x$  on  $M$ . If we have  $U_2 = \bigcup_{x \in U_1} U_x$  and analogously for  $U_3$  and  $U_4$ , then we have  $U_1 \subset U_2, U_3 \subset U_4$  and in that case it is sufficient to consider the transformations of coordinates in the intersection  $U_2 \cap U_4$  only. In this interpretation  $(x^1, \dots, x^n), (x^{n+1}, \dots, x^{2n})$  are coordinates of two points of  $U_2$ .

We shall denote

$$(30) \quad A_{k,j}^i(u) = \frac{\partial A_k^i(x^1, \dots, x^n, x^{n+1}, \dots, x^{2n})}{\partial x^{j+n}}, \quad (i, j, k=1, 2, \dots, n).$$

The functions are defined on  $V_\alpha$ . Let  $B_{k,j}^i(v)$  be analogously defined functions on  $V_\beta$ . We obtain easily the relations

$$(31) \quad B_{k,j}^i(v) = h_{k,j}^i(v) A_{k,j}^i(u) k_{k,j}^i(v); \quad h_{k,j}^i(v), k_{k,j}^i(v) \in G,$$

where  $u = v$ . It is straightforward to verify that

$$(32) \quad B_{j,k}^i(v) = h_{k,j}^i(v) A_{k,j}^i(u) k_{k,j}^i(v) k_{k,j}^i(v) + (\dots).$$

The expressions  $(\dots)$  are equal to zero on the diagonal  $\tilde{M}$  of the product  $M \times M$ . We shall not request those expressions in detail. On  $\tilde{M}$  there holds also:

$$(33) \quad k_{i,i}^j(v) = \tilde{h}_{i,i}^j(v).$$

( $\tilde{h}_{i,i}^j$  be the coefficient of the inverse matrix to the matrix  $(h_{i,i}^j)$ ).

Let us identify the points  $(v, w_\alpha) \in V_\alpha \times G$

$$(34) \quad (v, w_\beta) \in V_\beta \times G, \quad v \in V_\alpha \cap V_\beta \quad \text{if the equation} \\ w_\alpha = h_{\alpha\beta}(v) w_\beta, \quad h_{\alpha\beta}(v) = (h_{\alpha\beta}^j(v))$$

is satisfied.

If we denote  $R$  the union of the sets  $\{V_\alpha \times G\}$  under the above described identification, we have a principal fibre bundle  $R$ . We can consider  $R$  as a principal fibre bundle over  $M \times M$ , (if we shall make any

extension of the covering and of the functions  $h_{\alpha\beta}$ )

with the structural group  $G$  and natural projection

$$q: R \rightarrow M \times M.$$

Let us define on  $q^{-1}(V_\alpha)$  the functions

$$(35) \quad v_{(\alpha)\beta}^{ij}(w_\alpha) = A_{\alpha\beta}^e(u) w_{\alpha\beta}^{(a)} w_{\alpha\beta}^{(a)} \tilde{w}_{\alpha\beta}^{(a)} \tilde{w}_{\alpha\beta}^{(a)}, \quad u = q(w_\alpha).$$

If  $u = v \in V_\alpha \cap V_\beta$ , then we have

$$(36) \quad v_{(\beta)\alpha}^{ij}(w_\beta) = B_{\alpha\beta}^e(v) w_{\beta\alpha}^{(b)} w_{\beta\alpha}^{(b)} \tilde{w}_{\beta\alpha}^{(b)} \tilde{w}_{\beta\alpha}^{(b)}.$$

Now, it follows from (31), (32), (33) that on  $\tilde{M}$  the relation

$$(37) \quad v_{(\alpha)\beta}^{ij}(w_\alpha) = v_{(\beta)\alpha}^{ij}(w_\beta)$$

is satisfied. From (36) it follows that the functions (34) are globally defined on a principal fibre bundle  $S(\tilde{M}, G)$  which is a submanifold of  $R$ . We can identify in a natural way  $\tilde{M}$  and  $M$ . In that what follows we shall

speak about the principal fibre bundle  $P(M, G)$  instead of  $S(\tilde{M}, G)$ . Let us now define the map of

$P$  into  $B = R^n \otimes R^{n*} \otimes R^{n*}$  as follows:

Let us associate an element

$$(38) \quad v_j^{ik}(x) e_k \otimes e^i \otimes e^j$$

for the point  $x \in P$ . We can make now the identification

$$(39) \quad v_j^{ik}(x) = a_{pj}^k v_i^p(x),$$

where  $a_{pj}^k v_i^p(x)$  are the components of the tensor  $tu$  (19). From (5) we see that  $a_{(ij)k}^b = \tilde{d}_{ia}^b \tilde{d}_{jk}^a$  and that (38) can be written in the form

$$(40) \quad v_j^{ik}(x) = a_{(un)j}^k v_i^{(un)}(x) = \tilde{d}_{ik}^a \tilde{d}_{ja}^b v_i^{(un)}(x) = v_i^{(kj)}(x).$$

The equation (13) goes under (39) into the equations

$$(41) \quad h_i = \tilde{h}_i + v_i^{(kj)} v_{kj} = \tilde{h}_i + v_j^{ik}(x) v_{kj}, \quad (i, j, k = 1, 2, \dots, n)$$

If we have associated a combined manifold  $M_f$  to a manifold, then the differentiable mapping of connexions on  $P$  into itself is given.  $v_j^{ik}$  are the components of the tensor  $tu$ .

Definition: Let  $u$  be a  $\mathcal{L}$ -valued 1-form on  $P$  given in the chosen base by the equation (18). The functions  $v_i^\alpha(x)$  be given by (38), (39). Then we say that the tensor  $tu$  is a linearisating tensor.

From (34) we get

$$(42) \quad v_k^{ij} = v_j^{ki}.$$

According to the above considerations we have the following

Lemma : It is possible to associate a linearisating tensor  $tu$  on the pair  $P(M, G)$  as a mapping of  $P$  into  $B$  to the combined manifold  $M_f$ .  $tu$  is the tensor corresponding to the 1-form on  $P$  defined by (18).

It is also possible to show that the following lemma is satisfied.

Lemma : Let  $\omega$  be a  $\Gamma$ -connexion 1-form on  $P$  and  $\omega'$  a  $\Gamma'$ -connexion 1-form on  $P$ ,

where  $\Gamma'$  is the map of  $\Gamma$ , when  $h$  is the mapping of  $P$  onto itself 2. Let  $\Sigma_\omega, \Sigma_{\omega'}$  be the torsion forms of these connexions respectively. Then the relation

$$(43) \quad t\Sigma_{\omega'} = t\Sigma_\omega,$$

satisfies their torsion tensors.

Proof. According to the definition (12) of the torsion form we can write

$$(44) \quad \begin{aligned} \Sigma_{\omega'} - \Sigma_\omega &= u \cdot \theta = \\ &= (v_i^\alpha \theta^i \otimes \varepsilon_\alpha) \cdot (\theta^k \otimes e_k) = \\ &= v_i^\alpha \sigma_\alpha(\varepsilon_\alpha) e_k \otimes \theta^i \wedge \theta^k = \\ &= a_{\alpha k}^j v_i^\alpha e_j \otimes \theta^i \wedge \theta^k = \\ &= \frac{1}{2} (a_{\alpha k}^j v_i^\alpha - a_{\alpha i}^j v_k^\alpha) e_j \otimes \theta^i \wedge \theta^k \end{aligned}$$

But from (41) we have

$$(45) \quad a_{\alpha k}^j v_i^\alpha = a_{\alpha i}^j v_k^\alpha$$

and then we have

$$(46) \quad t\Sigma_{\omega'} - t\Sigma_\omega = A \cdot tu = 0.$$

4. If we compare the notion of linearisating tensor introduced above with that one defined by E. Čech [3], then we have

Proposition: Let  $M \equiv A_n$  be an  $n$ -dimensional affine space and  $f_x$  be the tangent mapping of the identity mapping of  $A_n$  onto itself at a point  $x \in A_n$ .

Then the linearisating tensor associated to  $(A_n)_f$  is the Čech's linearisating tensor [3].

Proof: Let  $\{A, J_1, \dots, J_n\}$  be a moving frame of  $A_n$ . We have the well known fundamental equations

$$(47) \quad dA = \omega^i J_i, \quad dJ_i = \omega_i^k J_k, \quad (i, k = 1, 2, \dots, n).$$

Let  $\mathbb{A}$  be an affine mapping of  $A_n$  onto itself. Let  $\{A', J'_1, \dots, J'_n\}$  be a  $\mathbb{A}$ -map of  $\{A, J_1, \dots, J_n\}$ .

$$(48) \quad \mathbb{A}A = A', \quad \mathbb{A}J_i = J'_i \quad (i = 1, 2, \dots, n).$$

According to (46) we have

$$(49) \quad dA' = \pi^i J'_i, \quad dJ'_i = \pi_i^k J'_k.$$

We say that the mapping  $\mathbb{A}$  is a tangent affine mapping if the following conditions are satisfied:

$$(50) \quad \mathbb{A}A = A', \quad \mathbb{A}dA = dA', \quad A = A'.$$

The necessary and sufficient conditions for  $\mathbb{A}$  to be a tangent affine mapping are:

$$(51) \quad \omega^i = \pi^i \quad (i = 1, 2, \dots, n).$$

We have then

$$(52) \quad [\omega^k \omega_k^i - \pi_k^i] = 0 \quad (i, k = 1, 2, \dots, n).$$

According to (51) we have

$$(53) \quad \omega_k^i - \pi_k^i = c_{kj}^i \omega^j \quad (i, j, k = 1, 2, \dots, n),$$

where  $c_{kj}^i = c_{jk}^i$ .  $c_{jk}^i$  is a tensor defined on the neighborhood of a point  $A$ . It is so called Čech's linearisating tensor which plays a fundamental role in the theory of correspondences between two affine (projective, ...) spaces. That this tensor is a linearisating tensor mentioned above it is straightforward to see from [2].

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