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Algorithms. 41. FOURIER. Computation of Fourier-transform integrals

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ALGORITMY

41. FOURIER

COMPUTATION OF FOURIER-TRANSFORM INTEGRALS

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This procedure computes Fourier-transform integrals

$$(1) \quad C(\omega) = \int_0^\infty \cos \omega t f(t) dt$$

and

$$(2) \quad S(\omega) = \int_0^\infty \sin \omega t f(t) dt$$

The integral $C(\omega)$ is written as

$$(3) \quad C(\omega) = \frac{1}{\omega} \int_0^{\pi/2} \cos x f\left(\frac{x}{\omega}\right) dx + \frac{1}{\omega} \sum_{k=1}^{\infty} (-1)^k \int_{-\pi/2}^{\pi/2} \cos x f\left(\frac{x + k\pi}{\omega}\right) dx$$

The first integral on the right side of (3) is evaluated using Romberg integration and a number of the integrals in the summation are computed using Gaussian quadrature formulas with $\cos x$ as weight function. The sum is then estimated by the ϵ -algorithm of Wynn. The modification of this method for the computation of $S(\omega)$ is straightforward. The procedure determines automatically the required number of terms in (3) and the order N of the Gaussian formulas ($N \leq 32$) in order to have a prescribed accuracy. The abscissas and weights of the quadrature formulas are stored in the program.

The user has only to insert

- (a) the value of ω
- (b) a procedure for computing $f(t)$ ($t \geq 0$)
- (c) a tolerance ϵ , indicating the requested absolute accuracy

* Stagiair of the N. F. W. O. (Belgium).

(d) a boolean parameter which must be *true* if equation (1) is to be calculated and *false* if equation (2) is to be calculated.

```

real procedure fourierint (f, omega, eps, cosine, ier);
value omega, eps; integer ier; real omega, eps;
real procedure f; boolean cosine;
comment this function returns the value of the integral from zero to infinity of
 $f(x) \times \cos(w \times x)$ . The epsilon algorithm is used to accelerate the con-
vergence.
inputparameters
  f . . . function
  omega . . . pulsation
  eps . . . desired absolute accuracy
  cosine . . . = true if cosine transform is to be computed
            = false if sine transform is to be computed
outputparameters
  ier . . . = k when in k half periods the integral cannot be computed
            with the desired accuracy
            =  $1000 + k$  when in k half periods the integral cannot be comput-
            ed with the desired accuracy and when there was no convergence
            after 25 steps in the epsilon algorithm;
begin real array s[0 : 25, 1 : 3], x2[1 : 83], w2[1 : 83];
real pi, a, z; integer sgn, sgnw, ii, i, im1, im2, j, jl, k;
real procedure oscin1;
begin real s, p, h, a1, a2; array t[0 : 12];
  integer n, j, i, k;
  comment Romberg integration;
  n := 1;
  t[0] := 0.25 × pi × f(0)/z;
  a1 := t[0];
  for k := 1 step 1 until 12 do
    begin n := 2 × n; h := 0.5 × pi/(n × z);
    p := 4; s := 0;
    comment evaluation of trapezoidal rule;
    for i := 1 step 2 until n do
      s := s + f(i × h) × cos(z × i × h);
    t[k] := t[k - 1]/2 + s × h;
    comment Romberg extrapolation;
    for j := k - 1 step -1 until 0 do
      begin t[j] := (p × t[j + 1] - t[j])/(p - 1);
      p := 4 × p
    end j;

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if  $k < 2$  then  $a2 := t[0]$ 
else if  $abs(a1 - a2) < 100 \times eps \wedge abs(a2 - t[0]) < eps$ 
then go to OUT
else begin  $a1 := a2;$ 
 $a2 := t[0]$ 
end;
end k;
ier := 1;
OUT:  $oscin1 := t[0]$ 
end of oscin1;
real procedure oscin2( $j$ );
value  $j$ ; integer  $j$ ;
comment Gaussian quadrature;
begin real  $sum1, sum2$ ; integer  $l, n, i$ ;
 $l := 1; sum1 := 1_{10}50;$ 
for  $n := 1$  step 1 until 10, 12 step 4
until 16 do
begin
 $sum2 := 0;$ 
for  $i := 1$  step 1 until  $n$  do
begin
if cosine then  $sum2 := sum2 + w2[l] \times$ 
 $(f((x2[l] + (j - 1) \times pi)/z) +$ 
 $f((-x2[l] + (j - 1) \times pi)/z))$ 
else  $sum2 := sum2 + w2[l] \times$ 
 $(f((x2[l] + (j - 0.5) \times pi)/z) +$ 
 $f((-x2[l] + (j - 0.5) \times pi)/z));$ 
 $l := l + 1$ 
end i;
comment test on accuracy;
if ( $abs(sum1 - sum2) < eps$ ) then go to FIN
else  $sum1 := sum2$ 
end n;
ier := ier + 1;
FIN:  $oscin2 := sum2/z;$ 
end oscin2;

x2[1] := 1.000000000000000; x2[2] := 0.4392874668600151;
w2[1] := 0.6836673900899030; w2[2] := 0.7759293818723798;
x2[3] := 1.1906765638948560; x2[4] := 0.3238521142128551;
w2[3] := 0.2240706181276202; w2[4] := 0.6058137001229013;

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x2[5] := 0.9197906655171356; x2[6] := 1.3639113020774860;
w2[5] := 0.3247985513772208; w2[6] := 0.0693877484998778;
x2[7] := 0.2564965074162312; x2[8] := 0.7434686478754924;
w2[7] := 0.4919957966032009; w2[8] := 0.3362644778528046;
x2[9] := 1.1537256454567280; x2[10] := 1.4414905401823580;
w2[9] := 0.1442040920302275; w2[10] := 0.0275356335137670;
x2[11] := 0.2123428870690829; x2[12] := 0.6221414570511029;
w2[11] := 0.4127123718856410; w2[12] := 0.3189730757362244;
x2[13] := 0.9878852856245157; x2[14] := 1.2824218392614150;
w2[13] := 0.1840793456376885; w2[14] := 0.0713116318694723;
x2[15] := 1.4825294561888940; x2[16] := 0.1811604682921093;
w2[15] := 0.0129235748709738; w2[16] := 0.3548619551685681;
x2[17] := 0.5341801247535697; x2[18] := 0.8595998627218704;
w2[17] := 0.2945380284952109; w2[18] := 0.1995586475169654;
x2[19] := 1.1400861905028520; x2[20] := 1.3600784903817600;
w2[19] := 0.1054805682651703; w2[20] := 0.0387356701110729;
x2[21] := 1.5067752445913270; x2[22] := 0.1579643816827197;
w2[21] := 0.0068251304430124; w2[22] := 0.3109730008916469;
x2[23] := 0.4676982277627329; x2[24] := 0.7590124026467929;
w2[23] := 0.2700416599568707; w2[24] := 0.2017941600465789;
x2[25] := 1.0201945939238280; x2[26] := 1.2404404819041370;
w2[25] := 0.1268326827931822; w2[26] := 0.0637384718429930;
x2[27] := 1.4103152290051090; x2[28] := 1.5222642294265360;
w2[27] := 0.0226888332160192; w2[28] := 0.0039311912527090;
x2[29] := 0.1400344442469677; x2[30] := 0.4157719767341894;
w2[29] := 0.2766109576482605; w2[30] := 0.2476363209463552;
x2[31] := 0.6786110809756055; x2[32] := 0.9202778620663710;
w2[31] := 0.1974114887025346; w2[32] := 0.1383419552695127;
x2[33] := 1.1330068786005000; x2[34] := 1.3097818904452940;
w2[33] := 0.0830266475732177; w2[34] := 0.0404378939465037;
x2[35] := 1.4446014873666510; x2[36] := 1.5327507132362300;
w2[35] := 0.0141152681568540; w2[36] := 0.0024194677567616;

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x2[37] := 0.1257600093435378; x2[38] := 0.3741337804491100;
w2[37] := 0.2490124783166383; w2[38] := 0.2277838163923600;
x2[39] := 0.6131272013222985; x2[40] := 0.8366838494891686;
w2[39] := 0.1899572674803385; w2[40] := 0.1432902231210859;
x2[41] := 1.0390514169347030; x2[42] := 1.2149186859960250;
w2[41] := 0.0963162571178597; w2[42] := 0.0560897522251605;
x2[43] := 1.3595638434785010; x2[44] := 1.4690102441122380;
w2[43] := 0.0267613742135268; w2[44] := 0.0092199875076379;
x2[45] := 1.5401756452752600; x2[46] := 0.1141265351397092;
w2[45] := 0.0015688436253925; w2[46] := 0.2263773256347921;
x2[47] := 0.3400227092105425; x2[48] := 0.5588854287853609;
w2[47] := 0.2103759285736437; w2[48] := 0.1812793354304047;
x2[49] := 0.7661509164888158; x2[50] := 0.9574468180865112;
w2[49] := 0.1441093214522280; w2[50] := 0.1047137538563544;
x2[51] := 1.1286754879087500; x2[52] := 1.2761025302615130;
w2[51] := 0.0684209743603314; w2[52] := 0.0390333646242024;
x2[53] := 1.3964496146801940; x2[54] := 1.4869880241013160;
w2[53] := 0.0183607593751510; w2[54] := 0.0062681947298298;
x2[55] := 1.5456233315613980; x2[56] := 0.0963084478801410;
w2[55] := 0.0010610419630624; w2[56] := 0.1914882094764121;
x2[57] := 0.2875039148019434; x2[58] := 0.4744518972742523;
w2[57] := 0.1817599290152465; w2[58] := 0.1635809306224327;
x2[59] := 0.6543769826862947; x2[60] := 0.8245889260330872;
w2[59] := 0.1392528630385753; w2[60] := 0.1116634500044801;
x2[61] := 0.9825182190263299; x2[62] := 1.1257529026114140;
w2[61] := 0.0837771210970006; w2[62] := 0.0581732191016194;
x2[63] := 1.2520765599390550; x2[64] := 1.3595070401753290;
w2[63] := 0.0367203461329272; w2[64] := 0.0204245886202449;
x2[65] := 1.4463349271495560; x2[66] := 1.5111599536054150;
w2[65] := 0.0094386847436585; w2[66] := 0.0031851139632458;
x2[67] := 1.5529206113728880; x2[68] := 0.0733917083744216;
w2[67] := 0.0005355441841570; w2[68] := 0.1462831701019649;

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x2[69] := 0.2195432169219730; x2[70] := 0.3638036135469709;
w2[69] := 0.1419245828750883; w2[70] := 0.1335454455634596;
x2[71] := 0.5049275494140530; x2[72] := 0.6416928214471680;
w2[71] := 0.1217818246542211; w2[72] := 0.1074943692922972;
x2[73] := 0.7729097379327027; x2[74] := 0.8974305746698114;
w2[73] := 0.0916731299075996; w2[74] := 0.0753350045262599;
x2[75] := 1.0141591218860860; x2[76] := 1.1220603001321730;
w2[75] := 0.0594279652953817; w2[76] := 0.0447534582942820;
x2[77] := 1.2201697939902740; x2[78] := 1.3076036151419680;
w2[77] := 0.0319139368609826; w2[78] := 0.0212875259455956;
x2[79] := 1.3835674612763600; x2[80] := 1.4473656842873490;
w2[79] := 0.0130274103587377; w2[80] := 0.0070804715378565;
x2[81] := 1.4984096108013310; x2[82] := 1.5362247792530200;
w2[81] := 0.0032183097393748; w2[82] := 0.0010740035337058;
x2[83] := 1.5604552434125810; w2[83] := 0.0001793915131927;

sgn := -1; ii := 1; ier := 0;
a := 0; sgnw := 1; z := omega;
s[0, 1] := 11050; pi = 3.141592653589793;
comment test for the sign of the pulsation;
if z < 0 then begin z := -z; sgnw := -1
    end;
comment test to see if the cosine transform or the sine transform is desired;
if cosine then begin a := oscin1;
    sgnw := 1; ii := ii + 1;
    s[1, 2] := -oscin2(ii);
    sgn := -sgn; ii := ii + 1
    end
    else begin s[1, 2] := oscin2(ii);
        ii := ii + 1
    end;
s[1, 3] := s[1, 2] + oscin2(ii) × sgn;
comment epsilon algorithm;
for i := 2 step 1 until 25 do
    begin for k := 2 step 1 until 3 do
        begin s[1, 1] := s[1, 2]; s[1, 2] := s[1, 3];
            ii := ii + 1; sgn := -sgn;
            s[1, 3] := [1, 3] + oscin2(ii) × sgn;
    
```

```

for  $j := 1$  step 1 until  $i = 2$  do
  begin  $j1 := j + 1$ ;  $s[j1, 1] := s[j1, 2]$ ;
     $s[j1, 2] := s[j1, 3]$ ;
     $s[j1, 3] := \text{if } abs(s[j, 2] - s[j, 1]) < 1_{10} - 30$ 
       $\vee abs(s[j, 2] - s[j, 3]) < 1_{10} - 30$ 
       $\vee abs(s[j, 2] - s[j - 1, 1]) < 1_{10} - 30$ 
    then  $s[j, 2]$ 
      else  $s[j, 2] = 1/(1/(s[j, 2] - s[j, 1])$ 
         $+ 1/(s[j, 2] - s[j, 3]) - 1/(s[j, 2] - s[j - 1, 1]))$ 
    end;
   $j1 := i - 1$ ;
   $s[i, k] := \text{if } abs(s[j1, 2] - s[j1, 1]) < 1_{10} - 30$ 
     $\vee abs(s[j1, 2] - s[j1, 3]) < 1_{10} - 30$ 
     $\vee abs(s[j1, 2] - s[j1 - 1, 1]) < 1_{10} - 30$ 
  then  $s[j1, 2]$ 
    else  $s[j1, 2] = 1/(1/(s[j1, 2] - s[j1, 1])$ 
       $+ 1/(s[j1, 2] - s[j1, 3]) - 1/(s[j1, 2] - s[j1 - 1, 1]))$ 
  end;
  if  $abs(s[i, 2] - s[i, 3]) < eps \wedge abs(s[i - 1, 2] -$ 
     $s[i - 1, 3]) < eps$  then go to OUT
  end;
   $ier := ier + 1000$ ;
OUT: fourierint := ( $s[i, 2] + a$ )  $\times sgnw$ 
end of fourierint

```

Examples. We tested this procedure for a large number of functions $f(t)$ and various values of ω and ε . For 97% of the testcases reliable results were obtained.

Table 1

$$\int_0^\infty \frac{1}{x^2 + a^2} \cos \omega x dx$$

a	ω	$\varepsilon = 10^{-5}$		$\varepsilon = 10^{-10}$	
		ε_{act}	N	ε_{act}	N
0.125	0.5	0.27×10^{-6}	608	0.11×10^{-10}	4302
	8.0	0.15×10^{-6}	160	0.41×10^{-11}	520
	256.0	0.13×10^{-6}	128	0.41×10^{-11}	224
2.0	0.5	0.68×10^{-6}	112	0.87×10^{-11}	322
	8.0	0.40×10^{-8}	128	0.65×10^{-11}	200
	256.0	0.82×10^{-8}	76	0.16×10^{-14}	112

Moreover, the algorithm is found to be very efficient. The results of two test functions are listed in table 1 and 2, where we have used the notation N to denote the number of function evaluations, ε the requested absolute accuracy and ε_{act} the actual absolute error.

Table 2

$$\int_0^\infty \frac{x}{x^2 + a^2} \sin \omega x dx$$

a	ω	$\varepsilon = 10^{-5}$		$\varepsilon = 10^{-10}$	
		ε_{act}	N	ε_{act}	N
0.125	0.5	0.21×10^{-6}	274	0.45×10^{-6} (ier = 1)	362
	8.0	0.20×10^{-6}	138	0.35×10^{-11}	304
	256.0	0.91×10^{-7}	96	0.54×10^{-10}	168
2.0	0.5	0.20×10^{-6}	138	0.22×10^{-11}	268
	8.0	0.58×10^{-6}	96	0.16×10^{-11}	168
	256.0	0.27×10^{-12}	72	0.56×10^{-14}	96

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