

Alois Švec

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ON 3-DIMENSIONAL LIE ALGEBRAS OF VECTOR FIELDS

ALOIS ŠVEC, Praha

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In series of papers [1]–[5], I devoted myself to the study of real hypersurfaces of the complex space \mathcal{C}^2 . The local differential geometry of such hypersurfaces consists (at least partly) in the study of 3-dimensional Lie algebras of vector fields on a 3-manifold. Because of this I present a more systematic study of such algebras.

Let G be a 3-dimensional Lie group, g its Lie algebra; let X_1, X_2, X_3 be independent left invariant fields on G . Let $\varphi : G \rightarrow G$ be a (local) diffeomorphism. If $d\varphi(X_i(x)) = X_i(\varphi(x))$ for $i = 1, 2, 3$ and each $x \in \text{Dom } \varphi$, φ is a restriction of a left motion $L_g(x) = gx$ of G ; denote by $\mathcal{M}(G)$ the pseudogroup of such diffeomorphisms. Further, denote by $\mathcal{M}^*(G)$ the pseudogroup of (local) diffeomorphisms $\psi : G \rightarrow G$ such that $d\psi(X_\alpha(x)) \in \{X_\alpha(\psi(x))\}$ for each $x \in \text{Dom } \psi$ and $\alpha = 1, 2$. I am going to show the infinitesimal version of the fact that generally (the exceptions being singled out) $\mathcal{M}(G) = \mathcal{M}^*(G)$.

1. Let L be a 3-dimensional Lie algebra of vector fields on a 3-dimensional differentiable manifold; everything be of class C^∞ . Suppose the existence of two 1-dimensional subspaces t, t' of L such that the plane spanned by them is not a subalgebra of L . A basis (v_1, v_2, v_3) of L is called *canonical* if $v_1 \in t, v_2 \in t'$ (or $v_1 \in t', v_2 \in t$ respectively) and $v_3 = [v_1, v_2]$.

Lemma. *The canonical basis may be chosen in such a way that we have one of the following cases (here, $p \in \mathcal{R}$ and $\varepsilon^2 = \varepsilon_1^2 = \varepsilon_2^2 = 1$):*

- (L_1^p) $[v_1, v_2] = v_3, [v_1, v_3] = [v_2, v_3] = pv_1 - pv_2 + v_3;$
- (L_2^p) $[v_1, v_2] = v_3, [v_1, v_3] = pv_2 + v_3, [v_2, v_3] = 0;$
- (L_3^p) $[v_1, v_2] = v_3, [v_1, v_3] = pv_1 + \varepsilon_1 v_2, [v_2, v_3] = \varepsilon_2 v_1 - pv_2;$
- (L_4) $[v_1, v_2] = v_3, [v_1, v_3] = v_1 + \varepsilon v_2, [v_2, v_3] = -v_2;$
- (L_5) $[v_1, v_2] = v_3, [v_1, v_3] = \varepsilon v_2, [v_2, v_3] = 0;$
- (L_6) $[v_1, v_2] = v_3, [v_1, v_3] = v_1, [v_2, v_3] = -v_2;$
- (L_7) $[v_1, v_2] = v_3, [v_1, v_3] = [v_2, v_3] = 0.$

Proof. Let $(v_1, v_2, v_3), (w_1, w_2, w_3)$ be two canonical bases of L . Then

$$(1) \quad \begin{aligned} [v_1, v_2] &= v_3, \quad [v_1, v_3] = a_1v_1 + a_2v_2 + a_3v_3, \\ [v_2, v_3] &= b_1v_1 + b_2v_2 + b_3v_3; \\ [w_1, w_2] &= w_3, \quad [w_1, w_3] = A_1w_1 + A_2w_2 + A_3w_3, \\ [w_2, w_3] &= B_1w_1 + B_2w_2 + B_3w_3; \end{aligned}$$

$$(2) \quad v_1 = \alpha w_1, \quad v_2 = \beta w_2, \quad v_3 = \alpha\beta w_3; \quad \alpha\beta \neq 0.$$

From the Jacobi identities,

$$(3) \quad \begin{aligned} a_1 + b_2 &= 0, \quad a_1b_3 - a_3b_1 = 0, \quad a_2b_3 - a_3b_2 = 0; \\ A_1 + B_2 &= 0, \quad A_1B_3 - A_3B_1 = 0, \quad A_2B_3 - A_3B_2 = 0. \end{aligned}$$

Further,

$$(4) \quad \begin{aligned} a_1 &= \alpha\beta A_1, \quad a_2 = \alpha^2 A_2, \quad a_3 = \alpha A_3, \quad b_1 = \beta^2 B_1, \\ b_2 &= \alpha\beta B_2, \quad b_3 = \beta B_3, \end{aligned}$$

and the result follows.

Theorem. Let L be as above. Let $\mathcal{L}(L)$ be the Lie algebra of infinitesimal automorphisms of L , i.e., the Lie algebra of vector fields u on M such that $[v, u] = 0$ for each $v \in L$. Let $\mathcal{L}^*(L)$ be the Lie algebra of vector fields u on M such that $[t, u] \subset t$ and $[t', u] \subset t'$. Then the following conditions are equivalent: (i) $\mathcal{L}(L) \neq \mathcal{L}^*(L)$, (ii) $\dim \mathcal{L}^*(L) = 8$, (iii) L is equal to L_1^0 or L_2^p or L_3^p or L_5 or L_6 or L_7 respectively.

Proof. (1) Consider the algebra L_1^p , and let

$$(5) \quad u = Av_1 + Bv_2 + Cv_3$$

be a vector field. Because of

$$(6) \quad \begin{aligned} [v_1, u] &= (v_1A + pC)v_1 + (v_1B - pC)v_2 + (v_1C + B + C)v_3, \\ [v_2, u] &= (v_2A + pC)v_1 + (v_2B - pC)v_2 + (v_2C - A + C)v_3, \\ [v_3, u] &= (v_3A - pA - pB)v_1 + (v_3B + pA + pB)v_2 + (v_3C - A - B)v_3, \end{aligned}$$

$u \in \mathcal{L}^*(L_1^p)$ if and only if

$$(7) \quad v_2A = -pC; \quad v_1B = pC; \quad v_1C = -B - C, \quad v_2C = A - C.$$

The integrability condition of (7_{3,4}) is $v_3C = v_1A + v_2B + A + B$. Set $D := v_1A$, $E := v_2B$, then

$$(8) \quad v_1A = D; \quad v_2B = E; \quad v_3C = A + B + D + E.$$

The integrability conditions of (7) + (8) are

$$\begin{aligned} v_3A + v_2D &= p(B + C), \quad v_3B - v_1E = p(C - A), \\ v_3B + v_1D + v_1E &= -p(A + B + C) - D, \\ v_3A - v_2D - v_2E &= p(A + B - C) + E. \end{aligned}$$

Set $F := v_3A$, $G := v_3B$, then

$$(9) \quad \begin{aligned} v_3A &= F; \quad v_3B = G; \\ v_1D &= -p(2A + B) - D - 2G, \quad v_2D = p(B + C) - F; \\ v_1E &= p(A - C) + G, \quad v_2E = -p(A + 2B) - E + 2F. \end{aligned}$$

The integrability conditions of (7)–(9) are

$$\begin{aligned} v_1F - v_3D &= p^2C + pD + F, \quad v_2F = p^2C - p(A + B + E) + F, \\ v_1G &= p^2C + p(A + B + D) + G, \quad v_2G - v_3E = p^2C - pE + G, \\ v_3D + v_1F - 2v_2G &= -p^2C + pE - F, \\ v_3E - 2v_1F + v_2G &= -p^2C - pD - G. \end{aligned}$$

Set $H := v_1F - \frac{1}{2}pE$, then

$$(10) \quad \begin{aligned} v_3D &= -p^2C - pD + \frac{1}{2}pE - F + H; \\ v_3E &= -p^2C - \frac{1}{2}pD + pE - G + H; \\ v_1F &= \frac{1}{2}pE + H, \quad v_2F = p^2C - p(A + B + E) + F; \\ v_1G &= p^2C + p(A + B + D) + G, \quad v_2G = -\frac{1}{2}pD + H. \end{aligned}$$

The integrability conditions of (9) + (10) are

$$\begin{aligned} v_1H + 2v_3G &= -\frac{9}{2}p^2A - 4p^2B - \frac{3}{2}p^2C - 2pD + \frac{1}{2}pE - pF - \frac{11}{2}pG + H, \\ v_2H + v_3F &= -\frac{1}{2}p^2A - p^2C - pD + pE - pF - pG + H, \\ v_1H - v_3G &= \frac{1}{2}p^2B - p^2C - pD + pE - pF - pG + H, \\ v_2H - 2v_3F &= 4p^2A + \frac{9}{2}p^2B - \frac{3}{2}p^2C - \frac{1}{2}pD + 2pE - \frac{11}{2}pF - pG + H, \end{aligned}$$

and we get

$$\begin{aligned}
 (11) \quad v_3 F &= -\frac{3}{2}p^2 A - \frac{3}{2}p^2 B + \frac{1}{6}p^2 C - \frac{1}{6}pD - \frac{1}{3}pE + \frac{3}{2}pF; \\
 v_3 G &= -\frac{3}{2}p^2 A - \frac{3}{2}p^2 B - \frac{1}{6}p^2 C - \frac{1}{3}pD - \frac{1}{6}pE - \frac{3}{2}pG; \\
 v_1 H &= -\frac{3}{2}p^2 A - p^2 B - \frac{7}{6}p^2 C - \frac{4}{3}pD + \frac{5}{6}pE - pF - \frac{5}{2}pG + H, \\
 v_2 H &= p^2 A + \frac{3}{2}p^2 B - \frac{7}{6}p^2 C - \frac{5}{6}pD + \frac{4}{3}pE - \frac{5}{2}pF - pG + H.
 \end{aligned}$$

The integrability conditions of $(10_3) + (11_1)$ and $(11_3) + (11_4)$ are

$$\begin{aligned}
 (12) \quad v_3 H &= \frac{1}{2}p^2(A + B) + \frac{1}{12}p(4 - 15p)(D + E) - \frac{1}{2}p(F - G), \\
 v_3 H &= \frac{1}{2}p^2(A + B) - \frac{1}{12}p(8 + 3p)(D + E) - \frac{1}{2}p(F - G)
 \end{aligned}$$

respectively. Thus

$$(13) \quad p(1 - p)(D + E) = 0.$$

Suppose $p \neq 0, 1$; then

$$(14) \quad D + E = 0.$$

Applying v_1, v_2, v_3 to (14), we get

$$(15) \quad p(A + B + C) + D + G = 0, \quad p(A + B - C) + E - F = 0$$

$$2H = 2p^2 C + \frac{3}{2}pD - \frac{3}{2}pE + F + G.$$

Thus

$$(16) \quad F - G = 2p(A + B)$$

from (14), $(15_{1,2})$. Applying v_1 , we get

$$(17) \quad D = -pC, \quad E = pC$$

because of (14) and (16). Applying v_2 to (17_1) , we get

$$(18) \quad F = p(A + B), \quad G = -p(A + B)$$

because of (16). Finally,

$$(19) \quad H = -\frac{1}{2}p^2 C$$

from (15₃). Thus

$$(20) \quad \begin{aligned} v_1A &= -pC, & v_2A &= -pC, & v_3A &= p(A+B), \\ v_1B &= pC, & v_2B &= pC, & v_3B &= -p(A+B), \\ v_1C &= -B-C, & v_2C &= A-C, & v_3C &= A+B, \end{aligned}$$

and $u \in \mathcal{L}(L_1^p)$ for $p \neq 0, 1$, i.e., $\mathcal{L}^*(L_1^p) = \mathcal{L}(L_1^p)$ for $p \neq 0, 1$.

Suppose $p = 1$. Then

$$(21) \quad \begin{aligned} v_1A &= D, & v_2A &= -C, & v_3A &= F; \\ v_1B &= C, & v_2B &= E, & v_3B &= G; \\ v_1C &= -B-C, & v_2C &= A-C, & v_3C &= A+B+D+E; \\ v_1D &= -2A-B-D-2G, & v_2D &= B+C-F, \\ v_3D &= -C-D+\frac{1}{2}E-F+H; \\ v_1E &= A-C+G, & v_2E &= A-2B-E+2F, \\ v_3E &= -C-\frac{1}{2}D+E-G+H; \\ v_1F &= \frac{1}{2}E+H, & v_2F &= -A-B+C-E+F, \\ v_3F &= -\frac{3}{2}A-\frac{3}{2}B+\frac{1}{6}C-\frac{1}{6}D-\frac{1}{3}E+\frac{3}{2}F; \\ v_1G &= A+B+C+D+G, & v_2G &= -\frac{1}{2}D+H, \\ v_3G &= -\frac{3}{2}A-\frac{3}{2}B-\frac{1}{6}C-\frac{1}{3}D-\frac{1}{6}E-\frac{3}{2}G; \\ v_1H &= -\frac{3}{2}A-B-\frac{7}{6}C-\frac{4}{3}D+\frac{5}{6}E-F-\frac{5}{2}G+H, \\ v_2H &= A+\frac{3}{2}B-\frac{7}{6}C-\frac{5}{6}D+\frac{4}{3}E-\frac{5}{2}F-G+H. \end{aligned}$$

The integrability conditions of (21₁₇) + (21₁₈) and (21₁₉) + (21₂₁) are $2C = D + 3E$ and $2C = -3D - E$ respectively, i.e.,

$$(22) \quad D = -C, \quad E = C.$$

Applying v_1, v_2, v_3 to $C + D = 0$, we get

$$(23) \quad G = -A - B, \quad F = A + B, \quad H = -\frac{1}{2}E,$$

i.e., $\mathcal{L}^*(L_1^1) = \mathcal{L}(L_1^1)$.

Let $p = 0$. Then

$$\begin{aligned}
 (24) \quad & v_1 A = D, \quad v_2 A = 0, \quad v_3 A = F; \\
 & v_1 B = 0, \quad v_2 B = E, \quad v_3 B = G; \\
 & v_1 C = -B - C, \quad v_2 C = A - C, \quad v_3 C = A + B + D + E; \\
 & v_1 D = -D - 2G, \quad v_2 D = -F, \quad v_3 D = -F + H; \\
 & v_1 E = G, \quad v_2 E = -E + 2F, \quad v_3 E = -G + H; \\
 & v_1 F = H, \quad v_2 F = F, \quad v_3 F = 0; \\
 & v_1 G = G, \quad v_2 G = H, \quad v_3 G = 0; \\
 & v_1 H = H, \quad v_2 H = H.
 \end{aligned}$$

The integrability conditions of this system reduce to

$$(25) \quad v_3 H = 0.$$

The system (24) + (25) being completely integrable, we have $\dim \mathcal{L}^*(L_1^0) = 8$.

(2) Let $L = L_2^0$. Then

$$\begin{aligned}
 (26) \quad & [v_1, u] = v_1 A \cdot v_1 + (v_1 B + pC) v_2 + (v_1 C + B + C) v_3, \\
 & [v_2, u] = v_2 A \cdot v_1 + v_2 B \cdot v_2 + (v_2 C - A) v_3,
 \end{aligned}$$

i.e., $v_1 C = -B - C$, $v_2 C = A$ for $u \in \mathcal{L}^*(L_2^0)$. The integrability condition being $v_3 C = v_1 A + v_2 B + A$, our starting point are the equations

$$\begin{aligned}
 (27) \quad & v_1 A = D, \quad v_2 A = 0; \quad v_1 B = -pC, \quad v_2 B = E; \\
 & v_1 C = -B - C, \quad v_2 C = A, \quad v_3 C = A + D + E.
 \end{aligned}$$

The integrability conditions are

$$\begin{aligned}
 & v_3 A + v_2 D = 0, \quad v_3 B - v_1 E = pA, \quad v_3 A - v_2 D - v_2 E = 0, \\
 & v_3 B + v_1 D + v_1 E = pA - D.
 \end{aligned}$$

For $F := v_3 A$, $G := v_3 B$, we get

$$\begin{aligned}
 (28) \quad & v_3 A = F; \quad v_3 B = G; \\
 & v_1 D = 2pA - D - 2G, \quad v_2 D = -F; \\
 & v_1 E = -pA + G, \quad v_2 E = 2F.
 \end{aligned}$$

The integrability conditions of (27) + (28) are

$$\begin{aligned} v_3D - v_1F = -F, \quad v_2F = 0, \quad v_1G = -p(A + D) + G, \quad v_3E - v_2G = 0, \\ v_3D + v_1F - 2v_2G = -F, \quad v_3E - 2v_1F + v_2G = 0, \end{aligned}$$

Set $H := v_3D$, then

$$(29) \quad \begin{aligned} v_3D = H; \quad v_3E = F + H; \quad v_1F = F + H, \quad v_2F = 0; \\ v_1G = -p(A + D) + G, \quad v_2G = F + H. \end{aligned}$$

The integrability conditions of (28) + (29) imply

$$(30) \quad v_3F = 0; \quad v_3G = 0; \quad v_1H = pF, \quad v_2H = 0;$$

the integrability of conditions (29), (30) reduce to

$$(31) \quad v_3H = 0.$$

The system (27)–(31) being completely integrable, we have $\dim \mathcal{L}^*(L_2^p) = 8$.

(3) Let $L = L_3^p$. Then

$$(32) \quad \begin{aligned} [v_1, u] &= (v_1A + pC)v_1 + (v_1B + \varepsilon_1C)v_2 + (v_1C + B)v_3, \\ [v_2, u] &= (v_2A + \varepsilon_2C)v_1 + (v_2B - pC)v_2 + (v_2C - A)v_3, \\ [v_3, u] &= (v_3A - pA - \varepsilon_2B)v_1 + (v_3B - \varepsilon_1A + pB)v_2 + v_3C.v_3. \end{aligned}$$

Let $u \in \mathcal{L}^*(L_3^p)$, then

$$v_1B + \varepsilon_1C = 0, \quad v_2A + \varepsilon_2C = 0, \quad v_1C + B = 0, \quad v_2C - A = 0.$$

From the last two equations, $v_3C = v_1A + v_2B$, and our starting points is the system

$$(33) \quad \begin{aligned} v_1A = D, \quad v_2A = -\varepsilon_2C; \quad v_1B = -\varepsilon_1C, \quad v_2B = E; \\ v_1C = -B, \quad v_2C = A, \quad v_3C = D + E. \end{aligned}$$

Its integrability conditions are

$$\begin{aligned} v_3A + v_2D = \varepsilon_2B, \quad v_3B - v_1E = \varepsilon_1A, \\ v_3B + v_1D + v_1E = \varepsilon_1A - pB, \quad v_3A - v_2D - v_2E = pA + \varepsilon_2B. \end{aligned}$$

Set $F := v_3A$, $G := v_3B$, then the prolongation of (33) is

$$(34) \quad \begin{aligned} v_3A &= F; \quad v_3B = G; \\ v_1D &= 2\varepsilon_1A - pB - 2G, \quad v_2D = \varepsilon_2B - F; \\ v_1E &= -\varepsilon_1A + G, \quad v_2E = -pA - 2\varepsilon_2B + 2F. \end{aligned}$$

Set $H := v_1F - \frac{1}{2}pD$; the integrability conditions of (33) + (34) imply

$$(35) \quad \begin{aligned} v_3D &= \varepsilon_1\varepsilon_2C - \frac{1}{2}pD + H; \quad v_3E = \varepsilon_1\varepsilon_2C + \frac{1}{2}pE + H; \\ v_1F &= \frac{1}{2}pD + H, \quad v_2F = \varepsilon_2pC - \varepsilon_2E; \\ v_1G &= -\varepsilon_1pC - \varepsilon_1D, \quad v_2G = -\frac{1}{2}pE + H. \end{aligned}$$

The integrability conditions of (34) + (35) are

$$(36) \quad \begin{aligned} v_3F &= (\varepsilon_1\varepsilon_2 - \frac{1}{2}p^2)A - \frac{3}{2}\varepsilon_2pB + \frac{3}{2}pF; \\ v_3G &= \frac{3}{2}\varepsilon_1pA + (\varepsilon_1\varepsilon_2 - \frac{1}{2}p^2)B - \frac{3}{2}pG; \\ v_1H &= -\frac{1}{2}p^2B + \varepsilon_1F - pG, \quad v_2H = \frac{1}{2}p^2A - pF - \varepsilon_2G. \end{aligned}$$

The integrability condition of (36₃) + (36₄) is

$$(37) \quad v_3H = \varepsilon_1\varepsilon_2(D + E);$$

the integrability condition of (36₃) + (37) reduces to

$$(38) \quad p(pA + \varepsilon_2B - F) = 0.$$

Let $p \neq 0$; then

$$(39) \quad F = pA + \varepsilon_2B.$$

Applying v_1 and v_2 to this equation, we get

$$(40) \quad H = -\varepsilon_1\varepsilon_2C + \frac{1}{2}pD, \quad E = pC$$

respectively. Applying v_1 and v_3 to (40₂), we get

$$(41) \quad G = \varepsilon_1A - pB, \quad D = -pC$$

respectively. Thus $u \in \mathcal{L}^*(L_3^p)$, $p \neq 0$, implies $u \in \mathcal{L}(L_3^p)$.

In the case $p = 0$, it is easy to see that the system (33)–(37) is completely integrable. Thus $\dim \mathcal{L}^*(L_3^0) = 8$.

(4) Let $L = L_4$. Then

$$(42) \quad \begin{aligned} [v_1, u] &= (v_1A + C)v_1 + (v_1B + \varepsilon C)v_2 + (v_1C + B)v_3, \\ [v_2, u] &= v_2A \cdot v_1 + (v_2B - C)v_2 + (v_2C - A)v_3, \\ [v_3, u] &= (v_3A - A)v_1 + (v_3B - \varepsilon A + B)v_2 + v_3C \cdot v_3. \end{aligned}$$

From $v_1C = -B$, $v_2C = A$, we get $v_3C = v_1A + v_2B$, and we may write

$$(43) \quad \begin{aligned} v_1A = D, \quad v_2A = 0; \quad v_1B = -\varepsilon C, \quad v_2B = E; \\ v_1C = -B, \quad v_2C = A, \quad v_3C = D + E \end{aligned}$$

for $u \in \mathcal{L}^*(L_4)$. The integrability conditions of (43) allow us to write

$$(44) \quad \begin{aligned} v_3A = F; \quad v_3B = G; \\ v_1D = 2\varepsilon A - B - 2G, \quad v_2D = -F; \\ v_1E = -\varepsilon A + G, \quad v_2E = -A + 2F, \end{aligned}$$

and a further differentiation yields

$$(45) \quad \begin{aligned} v_3D = H - \frac{1}{2}D; \quad v_3E = H + \frac{1}{2}E; \\ v_1F = H + \frac{1}{2}D, \quad v_2F = 0; \quad v_1G = -\varepsilon(C + D), \quad v_2G = H - \frac{1}{2}E. \end{aligned}$$

Finally,

$$(46) \quad \begin{aligned} v_3F = -\frac{1}{2}A + \frac{3}{2}F; \quad v_3G = \frac{3}{2}\varepsilon A - \frac{1}{2}B - \frac{3}{2}G; \\ v_1H = -\frac{1}{2}B + \varepsilon F - G, \quad v_2H = \frac{1}{2}A - F. \end{aligned}$$

The integrability conditions are

$$v_3H = 0, \quad v_3H = -\frac{1}{2}(C - E), \quad 3D = -2C - E.$$

Thus

$$(47) \quad D = -C, \quad E = C.$$

Applying v_1, v_2, v_3 to (47₂), we get

$$(48) \quad G = \varepsilon A - B, \quad F = A, \quad H = -\frac{1}{2}C$$

respectively. Thus $\mathcal{L}^*(L_4) = \mathcal{L}(L_4)$.

(5) Let $L = L_5$. We have

$$(49) \quad \begin{aligned} [v_1, u] &= v_1A \cdot v_1 + (v_1B + \varepsilon C) v_2 + (v_1C + B) v_3, \\ [v_2, u] &= v_2A \cdot v_1 + v_2B \cdot v_2 + (v_2C - A) v_3. \end{aligned}$$

By the same procedure, we get successively

$$(50) \quad \begin{aligned} v_1A = D, \quad v_2A = 0; \quad v_1B = -\varepsilon C, \quad v_2B = E; \\ v_1C = -B, \quad v_2C = A, \quad v_3C = D + E; \end{aligned}$$

$$(51) \quad v_3A = F; \quad v_3B = G;$$

$$v_1D = 2\varepsilon A - 2G, \quad v_2D = -F; \quad v_1E = G - \varepsilon A, \quad v_2E = 2F;$$

$$(52) \quad v_3D = H; \quad v_3E = H; \quad v_1F = H, \quad v_2F = 0; \quad v_1G = -\varepsilon D, \quad v_2G = H;$$

$$(53) \quad v_3F = 0; \quad v_3G = 0; \quad v_1H = \varepsilon F, \quad v_2H = 0,$$

$$(54) \quad v_3H = 0$$

for $u \in \mathcal{L}^*(L_5)$. The system (50)–(54) being completely integrable, $\dim \mathcal{L}^*(L_5) = 8$.

(6) Let $L = L_6$. Then

$$(55) \quad \begin{aligned} [v_1, u] &= (v_1A + C) v_1 + v_1B \cdot v_2 + (v_1C + B) v_3, \\ [v_2, u] &= v_2A \cdot v_1 + (v_2B - C) v_2 + (v_2C - A) v_3, \end{aligned}$$

and we get the completely integrable system

$$(56) \quad \begin{aligned} v_1A = D, \quad v_2A = 0; \quad v_1B = 0, \quad v_2B = E; \\ v_1C = -B, \quad v_2C = A, \quad v_3C = D + E; \end{aligned}$$

$$(57) \quad v_3A = F; \quad v_3B = G;$$

$$v_1D = -B - 2G, \quad v_2D = -F; \quad v_1E = G, \quad v_2E = -A + 2F;$$

$$(58) \quad v_3D = H - \frac{1}{2}D; \quad v_3E = H + \frac{1}{2}E;$$

$$v_1F = H + \frac{1}{2}D, \quad v_2F = 0; \quad v_1G = 0, \quad v_2G = H - \frac{1}{2}E;$$

$$(59) \quad v_3F = -\frac{1}{2}A + \frac{3}{2}F; \quad v_3G = -\frac{1}{2}B - \frac{3}{2}G;$$

$$v_1H = -\frac{1}{2}B - G, \quad v_2H = \frac{1}{2}A - F,$$

$$(60) \quad v_3H = 0$$

for $u \in \mathcal{L}^*(L_6)$. Thus $\dim \mathcal{L}^*(L_6) = 8$.

(7) Let $L = L_7$. Then

$$(61) \quad \begin{aligned} [v_1, u] &= v_1 A \cdot v_1 + v_1 B \cdot v_2 + (v_1 C + B) v_3, \\ [v_2, u] &= v_2 A \cdot v_1 + v_2 B \cdot v_2 + (v_2 C - A) v_3. \end{aligned}$$

The result follows from the complete integrability of the system

$$(62) \quad v_1 A = D, \quad v_2 A = 0; \quad v_1 B = 0, \quad v_2 B = E;$$

$$v_1 C = -B, \quad v_2 C = A, \quad v_3 C = D + E;$$

$$(63) \quad v_3 A = F; \quad v_3 B = G;$$

$$v_1 D = -2G, \quad v_2 D = -F; \quad v_1 E = G, \quad v_2 E = 2F;$$

$$(64) \quad v_3 D = H, \quad v_3 E = H; \quad v_1 F = H, \quad v_2 F = 0; \quad v_1 G = 0, \quad v_2 G = H;$$

$$(65) \quad v_3 F = 0; \quad v_3 G = 0; \quad v_1 H = 0, \quad v_2 H = 0,$$

$$(66) \quad v_3 H = 0$$

for $u \in \mathcal{L}^*(L_7)$; namely, $\dim \mathcal{L}^*(L_7) = 8$.

2. Let us add two remarks.

(1) Let G be the group of matrices of the form

$$(67) \quad \begin{pmatrix} \alpha & 0 & 0 \\ 0 & \beta & 0 \\ \gamma & \delta & \varphi \end{pmatrix}, \quad \alpha\beta\varphi \neq 0,$$

and let L be one of the algebras of the type L_1^p, \dots, L_7 . Denote by $B_G(L)$ the G -structure on M^3 generated by the section (v_1, v_2, v_3) . Then it is possible to prove the following theorem:

The conditions (i)–(iii) of our Theorem are equivalent to the following one:
(iv) the G -structure $B_G(L)$ contains a section (w_1, w_2, w_3) satisfying $[w_1, w_2] = w_3$, $[w_1, w_3] = [w_2, w_3] = 0$.

(2) Let $M^{2n-1} \subset \mathcal{C}^n$ be a real hypersurface of the complex space, and let $\Gamma(M^{2n-1})$ be the pseudogroup of (local) biholomorphic mappings of \mathcal{C}^n preserving M^{2n-1} . One of the problems is to determine hypersurfaces which are transitive with respect to $\Gamma(M^{2n-1})$. It turns out that the problem to determine all possible numbers $\dim \Gamma(M^{2n-1})$ is equivalent to the following one:

Let M^{2n-1} be a differentiable manifold, and let L be a Lie algebra of vector fields on M^{2n-1} . Suppose that $\dim L = 2n - 1$ and that there are two subalgebras $K_1, K_2 \subset L$ such that $\dim K_1 = \dim K_2 = n - 1$, $K_1 \cap K_2 = \{0\}$, $[K_1, K_2] = L$. Denote by $\mathcal{L}^*(L; K_1, K_2)$ the Lie algebra of vector fields u on M^{2n-1} satisfying $[K_1, u] \subset K_1$, $[K_2, u] \subset K_2$. We have to determine all possible values of $\dim \mathcal{L}^*(L; K_1, K_2)$.

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Author's address: 118 00 Praha 1, Malostranské nám. 25, ČSSR (Matematicko-fyzikální fakulta UK).